

THE VARIANT OF THE GOURSAT PROBLEM FOR THE SIXTH ORDER EQUATION

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Abstract. Our study is considered as a continuation of results in [1-8]. More precisely we investigate the Goursat problem in class $C^{2+2+2}(D)$ for the equation (1) below by Riemann method variant from the works [8] and [9].

1. Introduction

In the domain $D = \{(x, y, z); x_0 < x < x_1, y_0 < y < y_1, z_0 < z < z_1\}$ we consider the equation with variable coefficients:

$$L(u) = \sum_{\alpha, \beta, \gamma=0}^2 a_{\alpha\beta\gamma}(x, y, z) \frac{\partial^{\alpha+\beta+\gamma} u}{\partial x^\alpha \partial y^\beta \partial z^\gamma} = F(x, y, z). \quad (1)$$

It may be considered as a special generalization of the investigation in [1-8]. Many authors studied this problem in the different directions (e.g., [1-8]). The most general results were obtained in [7]. On the other hand, our aim in this paper is to consider the equation (1) which is a complication to the works [8-11] with higher derivative u_{xyz} . This equation plays an important role in approximation and transformation theory and during the description of vibration processes (see, [12]). The problem of integral transformation representation of type of ordinary linear differential operator into others is reduced to the similar equation in [13].

2. Main Results

Let X, Y, Z be bounds D for $x = x_0, y = y_0, z = z_0$, respectively. We consider that $a_{222} \equiv 1$, and the smoothness of other coefficients (1) is defined by the inclusions:

$$a_{\alpha\beta\gamma} \in C^{\alpha+\beta+\gamma}(\overline{D}), \quad F \in C^{2+2+2}(\overline{D}). \quad (2)$$

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Here, $C^{\alpha+\beta+\gamma}$ describes the class of continuous in \bar{D} together with derivatives $\partial^{r+s+t}/\partial x^r \partial y^s \partial z^t$ ($r = 0, \dots, \alpha$; $s = 0, \dots, \beta$; $t = 0, \dots, \gamma$).

Problem (Goursat). To find, in class $C^{2+2+2}(\bar{D})$, the solution of equation (1) satisfying the following boundary conditions:

$$\begin{aligned} u|_X &= \varphi(y, z), & u|_Y &= \psi(x, z), & u|_Z &= \theta(x, y); \\ u_x|_X &= \varphi_1(y, z), & u_y|_Y &= \psi_1(x, z), & u_z|_Z &= \theta_1(x, y). \end{aligned} \quad (3)$$

where

$$\varphi, \varphi_1 \in C^{2+2}(\bar{X}) \quad \psi, \psi_1 \in C^{2+2}(\bar{Y}) \quad \theta, \theta_1 \in C^{2+2}(\bar{Z}).$$

We suppose the satisfaction of the condition in ribs D

$$\varphi(y_0, z) = \psi(x_0, z), \quad \varphi(y, z_0) = \theta(x_0, y), \quad \psi(x, z_0) = \theta(x, y_0). \quad (4)$$

Here the agreed values are continuously differentiated. We solve this problem by means of the development of (using) the Riemann method variant from the works [8] and [9].

Riemann function $R(x, y, z, \zeta, \eta, \varsigma)$ is called the solution of following integral equation:

$$\begin{aligned} V(x, y, z) &- \int_{\varsigma}^z [a_{221}(x, y, \gamma)V(x, y, \gamma) - (z - \gamma)a_{220}(x, y, \gamma)V(x, y, \gamma)]d\gamma \\ &- \int_{\eta}^y [a_{212}(x, \beta, z)V(x, \beta, z) - (y - \beta)a_{202}(x, \beta, z)V(x, \beta, z)]d\beta \\ &- \int_{\zeta}^x [a_{122}(\alpha, y, z)V(\alpha, y, z) - (x - \alpha)a_{022}(\alpha, y, z)V(\alpha, y, z)]d\alpha \\ &+ \int_{\zeta}^x \int_{\eta}^y [a_{112}(\alpha, \beta, z)V(\alpha, \beta, z) - (y - \beta)a_{102}(\alpha, \beta, z)V(\alpha, \beta, z) \\ &\quad - (x - \alpha)a_{012}(\alpha, \beta, z)V(\alpha, \beta, z) + (x - \alpha)(y - \beta)a_{002}(\alpha, \beta, z)V(\alpha, \beta, z)]d\beta d\alpha \\ &+ \int_{\zeta}^x \int_{\varsigma}^z [a_{121}(\alpha, y, \gamma)V(\alpha, y, \gamma) - (z - \gamma)a_{120}(\alpha, y, \gamma)V(\alpha, y, \gamma) \\ &\quad - (x - \alpha)a_{021}(\alpha, y, \gamma)V(\alpha, y, \gamma) + (x - \alpha)(z - \gamma)a_{020}(\alpha, y, \gamma)V(\alpha, y, \gamma)]d\gamma d\alpha \\ &+ \int_{\eta}^y \int_{\varsigma}^z [a_{211}(x, \beta, \gamma)V(x, \beta, \gamma) - (y - \beta)a_{201}(x, \beta, \gamma)V(x, \beta, \gamma) \\ &\quad - (z - \gamma)a_{210}(x, \beta, \gamma)V(x, \beta, \gamma) + (y - \beta)(z - \gamma)a_{200}(x, \beta, \gamma)V(x, \beta, \gamma)]d\gamma d\beta \\ &- \int_{\zeta}^x \int_{\eta}^y \int_{\varsigma}^z [a_{111}(\alpha, \beta, \gamma)V(\alpha, \beta, \gamma) - (y - \beta)a_{101}(\alpha, \beta, \gamma)V(\alpha, \beta, \gamma) \\ &\quad - (x - \alpha)a_{011}(\alpha, \beta, \gamma)V(\alpha, \beta, \gamma) - (z - \gamma)a_{110}(\alpha, \beta, \gamma)V(\alpha, \beta, \gamma) \\ &\quad + (y - \beta)(z - \gamma)a_{100}(\alpha, \beta, \gamma)V(\alpha, \beta, \gamma) + (x - \alpha)(z - \gamma)a_{010}(\alpha, \beta, \gamma)V(\alpha, \beta, \gamma) \\ &\quad + (x - \alpha)(y - \beta)a_{001}(\alpha, \beta, \gamma)V(\alpha, \beta, \gamma) \\ &\quad - (x - \alpha)(y - \beta)(z - \gamma)a_{000}(\alpha, \beta, \gamma)V(\alpha, \beta, \gamma)]d\alpha d\beta d\gamma = 1. \end{aligned} \quad (5)$$

which exists and unique (see [14], pp.180). We may verify that the realization of the identity for any function u from the class $C^{2+2+2}(\overline{D})$ directly by the inspection:

$$\begin{aligned}
(uR)_{xxxyyzz} = & RL(u) + (uA_1)_{xxyyz} + (uA_2)_{xxyzz} + (uA_3)_{xyyzz} - (uB_1)_{xyzz} \\
& - (uB_2)_{xxyz} - (uB_3)_{xyyz} - (uB_4)_{xxyy} - (uB_5)_{xxzz} - (uB_6)_{yyzz} + (uC_1)_{xyz} \\
& + (uC_2)_{xzz} + (uC_3)_{xyy} + (uC_4)_{xxy} + (uC_5)_{xxz} + (uC_6)_{yyz} + (uC_7)_{yzz} \\
& - (uD_1)_{xy} - (uD_2)_{xz} - (uD_3)_{yz} - (uD_4)_{zz} - (uD_5)_{yy} - (uD_6)_{xx} + (uE_1)_x \\
& + (uE_2)_y + (uE_3)_z + \{u(a_{002}R)_z + u_x(a_{102}R)_z + u_y(a_{012}R)_z + u_{xy}(a_{112}R)_z \\
& + u_{xx}(a_{202}R)_z + u_{yy}(a_{022}R)_z + u_{xxy}(a_{212}R)_z + u_{xyy}(a_{122}R)_z + u_{xxy}R_z\}_z \\
& + \{u(a_{202}R)_{xz} + u_y(a_{212}R)_{xz} + u_{yy}R_{xz}\}_{xz} + \{u(a_{022}R)_{yz} + u_x(a_{122}R)_{yz} \\
& + u_{xx}R_{yz}\}_{yz} + \{uR_{xyz}\}_{xyz} + \{u(a_{200}R)_x + u_y(a_{210}R)_x + u_{yy}(a_{220}R)_x \\
& + u_z(a_{201}R)_x + u_{zz}(a_{202}R)_x + u_{yz}(a_{211}R)_x + u_{yyz}(a_{221}R)_x + u_{yzz}(a_{212}R)_x \\
& + u_{yyzz}R_x\}_x + \{u(a_{020}R)_y + u_x(a_{120}R)_y + u_z(a_{021}R)_y + u_{xz}(a_{121}R)_y \\
& + u_{xx}(a_{220}R)_y + u_{zz}(a_{022}R)_y + u_{xzz}(a_{122}R)_y + u_{xxz}(a_{221}R)_y \\
& + u_{xxzz}R_y\}_y + \{u(a_{220}R)_{xy} + u_z(a_{221}R)_{xy} + u_{zz}R_{xy}\}_{xy}, \tag{6}
\end{aligned}$$

where the notation

$$A_1 = R_z - a_{221}R, \quad A_2 = R_y - a_{212}R, \quad A_3 = R_x - a_{122}R,$$

$$B_1 = R_{xy} - (a_{212}R)_x - (a_{122}R)_y + a_{112}R, \quad B_2 = R_{yz} - (a_{221}R)_y - (a_{212}R)_z + a_{211}R,$$

$$B_3 = R_{xz} - (a_{221}R)_x - (a_{122}R)_z + a_{121}R, \quad B_4 = R_{zz} - (a_{221}R)_z + a_{220}R,$$

$$B_5 = R_{yy} - (a_{212}R)_y + a_{202}R, \quad B_6 = R_{xx} - (a_{122}R)_x + a_{022}R,$$

$$\begin{aligned}
C_1 = & R_{xyz} - (a_{221}R)_{xy} - (a_{212}R)_{xz} - (a_{122}R)_{yz} + (a_{112}R)_z \\
& + (a_{211}R)_x + (a_{121}R)_y - a_{111}R,
\end{aligned}$$

$$C_2 = R_{xyy} - (a_{212}R)_{xy} - (a_{122}R)_{yy} - (a_{112}R)_y + (a_{202}R)_x - a_{102}R,$$

$$C_3 = R_{xzz} - (a_{221}R)_{xz} - (a_{122}R)_{zz} - (a_{121}R)_z + (a_{220}R)_x - a_{120}R,$$

$$C_4 = R_{yzz} - (a_{221}R)_{yz} - (a_{212}R)_{zz} + (a_{211}R)_z + (a_{220}R)_y - a_{210}R,$$

$$C_5 = R_{yyz} - (a_{221}R)_{yy} - (a_{212}R)_{yz} + (a_{211}R)_y + (a_{202}R)_z - a_{201}R,$$

$$C_6 = R_{xxz} - (a_{221}R)_{xx} - (a_{122}R)_{xz} + (a_{121}R)_x + (a_{022}R)_y - a_{021}R,$$

$$C_7 = R_{xxy} - (a_{212}R)_{xx} - (a_{122}R)_{xy} + (a_{112}R)_x + (a_{022}R)_y - a_{012}R,$$

$$\begin{aligned}
D_1 = & R_{xyzz} - (a_{221}R)_{xyz} - (a_{212}R)_{xzz} - (a_{122}R)_{yzz} + (a_{112}R)_{zz} + (a_{211}R)_{xz} \\
& + (a_{121}R)_{yz} + (a_{220}R)_{xy} - (a_{111}R)_z - (a_{120}R)_y - (a_{210}R)_x + a_{110}R,
\end{aligned}$$

$$\begin{aligned}
D_2 = & R_{xyyz} - (a_{221}R)_{xyy} - (a_{212}R)_{xyz} - (a_{122}R)_{yyz} + (a_{112}R)_{yz} + (a_{211}R)_{xy} \\
& + (a_{121}R)_{yy} + (a_{202}R)_{xz} - (a_{111}R)_y - (a_{102}R)_z - (a_{201}R)_x + a_{101}R,
\end{aligned}$$

$$\begin{aligned}
D_3 &= R_{xxyz} - (a_{221}R)_{xxy} - (a_{212}R)_{xxz} - (a_{122}R)_{xyz} + (a_{112}R)_{xz} + (a_{211}R)_{xx} \\
&\quad + (a_{121}R)_{xy} + (a_{022}R)_{yz} - (a_{111}R)_x - (a_{021}R)_y - (a_{012}R)_z + a_{011}R, \\
D_4 &= R_{xxyy} - (a_{212}R)_{xxy} - (a_{122}R)_{xyy} + (a_{112}R)_{xy} + (a_{202}R)_{xx} \\
&\quad + (a_{022}R)_{yy} - (a_{102}R)_x - (a_{012}R)_y + a_{002}R, \\
D_5 &= R_{xxzz} - (a_{221}R)_{xxz} - (a_{122}R)_{xzz} + (a_{121}R)_{xz} + (a_{220}R)_{xx} \\
&\quad + (a_{022}R)_{zz} - (a_{120}R)_x - (a_{012}R)_z + a_{020}R, \\
D_6 &= R_{yyzz} - (a_{221}R)_{yyz} - (a_{212}R)_{yzz} + (a_{211}R)_{yz} + (a_{220}R)_{yy} \\
&\quad + (a_{202}R)_{zz} - (a_{210}R)_y - (a_{201}R)_z + a_{200}R, \\
E_1 &= R_{xyyzz} - (a_{221}R)_{xyyz} - (a_{212}R)_{xyzz} - (a_{122}R)_{yyzz} + (a_{112}R)_{yzz} + (a_{211}R)_{xyz} \\
&\quad + (a_{121}R)_{yyz} + (a_{220}R)_{xyy} + (a_{202}R)_{xzz} - (a_{111}R)_{yz} - (a_{102}R)_{zz} - (a_{120}R)_{yy} \\
&\quad - (a_{210}R)_{xy} - (a_{201}R)_{xz} + (a_{110}R)_y + (a_{101}R)_z + (a_{200}R)_x - a_{100}R, \\
E_2 &= R_{xxyzz} - (a_{221}R)_{xxyz} - (a_{212}R)_{xxzz} - (a_{122}R)_{xyzz} + (a_{112}R)_{xzz} + (a_{211}R)_{xxz} \\
&\quad + (a_{121}R)_{xyz} + (a_{220}R)_{xxy} + (a_{022}R)_{yzz} - (a_{111}R)_{xz} - (a_{120}R)_{xy} - (a_{210}R)_{xx} \\
&\quad - (a_{021}R)_{yz} - (a_{012}R)_{zz} + (a_{110}R)_x + (a_{011}R)_z + (a_{020}R)_y - a_{010}R, \\
E_3 &= R_{xxyyz} - (a_{221}R)_{xxyy} - (a_{212}R)_{xxyy} - (a_{122}R)_{xyyz} + (a_{112}R)_{xyz} + (a_{211}R)_{xxy} \\
&\quad + (a_{121}R)_{xyy} + (a_{202}R)_{xxz} + (a_{022}R)_{yyz} - (a_{111}R)_{xy} - (a_{102}R)_{xz} - (a_{201}R)_{xx} \\
&\quad - (a_{021}R)_{yy} - (a_{012}R)_{yz} + (a_{101}R)_x + (a_{011}R)_y + (a_{002}R)_z - a_{001}R. \quad (7)
\end{aligned}$$

Here $a_{\alpha\beta\gamma}$ depend on (x, y, z) , while R and its derivatives depend on $(x, y, z, \zeta, \eta, \varsigma)$. The derivation (6) is a heuristics problem. The easiest way to check the identity itself is the direct calculation. Here we consider that R with its first three arguments satisfies the adjoint equation (1)

$$\begin{aligned}
L^*(V) &\equiv V_{xxyyzz} - (a_{221}V)_{xxyyz} - (a_{211}V)_{xxyzz} - (a_{121}V)_{xyyzz} + (a_{112}V)_{xyz} \\
&\quad + (a_{211}V)_{xxyz} + (a_{121}V)_{xyyz} + (a_{220}V)_{xxyy} + (a_{202}V)_{xxzz} + (a_{022}V)_{yyzz} \\
&\quad - (a_{110}V)_{xyz} - (a_{102}V)_{xzz} - (a_{120}V)_{xyy} - (a_{210}V)_{xxy} - (a_{201}V)_{xxz} \\
&\quad - (a_{021}V)_{yyz} + (a_{012}V)_{yzz} + (a_{110}V)_{xy} + (a_{101}V)_{xz} + (a_{011}V)_{yz} + (a_{002}V)_{zz} \\
&\quad + (a_{020}V)_{yy} + (a_{200}V)_{xx} - (a_{100}V)_x - (a_{010}V)_y - (a_{001}V)_z - a_{000}V = 0. \quad (8)
\end{aligned}$$

It directly follows from (5) that

$$\begin{aligned}
&A_1(x, y, z, x, y, z) \equiv A_2(x, y, z, x, y, z) \equiv A_3(x, y, z, x, y, z) \\
&\equiv B_1(x, y, z, x, y, z) \equiv B_2(x, y, z, x, y, z) \equiv B_3(x, y, z, x, y, z) \\
&\equiv B_4(x, y, z, x, y, z) \equiv B_5(x, y, z, x, y, z) \equiv C_1(x, y, z, x, y, z) \\
&\equiv C_2(x, y, z, x, y, z) \equiv C_3(x, y, z, x, y, z) \equiv C_4(x, y, z, x, y, z) \\
&\equiv C_5(x, y, z, x, y, z) \equiv C_6(x, y, z, x, y, z) \equiv C_7(x, y, z, x, y, z) \\
&\equiv D_1(x, y, z, x, y, z) \equiv D_2(x, y, z, x, y, z) \equiv D_3(x, y, z, x, y, z) \\
&\equiv D_4(x, y, z, x, y, z) \equiv D_5(x, y, z, x, y, z) \equiv D_6(x, y, z, x, y, z) \\
&\equiv E_1(x, y, z, x, y, z) \equiv E_2(x, y, z, x, y, z) \equiv E_3(x, y, z, x, y, z) \equiv 0. \quad (9)
\end{aligned}$$

Now, we put for (6) $x = \alpha$, $y = \beta$, $z = \gamma$, $\zeta = x$, $\eta = y$. and $\varsigma = z$, and calculate the triple integral in the bounds $x_0 < \alpha < x$, $y_0 < \beta < y$, $z_0 < \gamma < z$ from the right and left parts. Here, taking into account the identity (9), boundary conditions (3) and the fact that $u(x, y, z)$ is the solution of the equation (1) we obtain the formula:

$$\begin{aligned}
u_{xyz} = & \int_{x_0}^x \int_{y_0}^y \int_{z_0}^z R(\alpha, \beta, \gamma, x, y, z) d\gamma d\beta d\alpha + \varphi_{1yz}(y, z)R(x_0, y, z, x, y, z) \\
& + \psi_{1xz}(x, z)R(x, y_0, z, x, y, z) - \varphi_{1yz}(y_0, z)R(x_0, y_0, z, x, y, z) \\
& + \theta_{1xy}(x, y)R(x, y, z_0, x, y, z) - \varphi_{1yz}(y, z_0)R(x_0, y, z_0, x, y, z) \\
& - \psi_{1xz}(x, z_0)R(x, y_0, z_0, x, y, z) + \varphi_{1yz}(y_0, z_0)R(x_0, y_0, z_0, x, y, z) \\
& - A_1(x_0, y, z)\varphi_{1y}(y, z) - A_1(x, y_0, z)\psi_{1y}(x, z) + A_1(x_0, y_0, z)\varphi_{1y}(y_0, z) \\
& - A_1(x, y, z_0)\theta_{xy}(x, y) + A_1(x_0, y, z_0)\varphi_{1y}(y, z_0) + A_1(x, y_0, z_0)\psi_{1x}(x, z_0) \\
& - A_1(x_0, y_0, z_0)\varphi_{1y}(y_0, z_0) - A_2(x_0, y, z)\varphi_{1z}(y, z) - A_2(x, y_0, z)\psi_{xy}(x, z) \\
& + A_2(x_0, y_0, z)\varphi_{1z}(y_0, z) - A_2(x, y, z_0)\theta_{1x}(x, y) + A_2(x_0, y, z_0)\varphi_{1y}(y, z_0) \\
& + A_2(x, y_0, z_0)\theta_{1x}(x, y_0) - A_2(x_0, y_0, z_0)\varphi_{1z}(y_0, z_0) - A_3(x_0, y, z)\varphi_{yz}(y, z) \\
& - A_3(x, y_0, z)\psi_{1z}(x, z) + A_3(x_0, y_0, z)\psi_{1z}(x_0, z) - A_3(x, y, z_0)\theta_{1y}(x, y) \\
& + A_3(x_0, y, z_0)\theta_{1y}(x_0, y) + A_3(x, y_0, z_0)\psi_{1z}(x, z_0) - A_3(x_0, y_0, z_0)\psi_{1z}(x_0, z_0) \\
& + B_1(x_0, y, z)\varphi_z(y, z) + B_1(x, y_0, z)\psi_z(x, z) - B_1(x_0, y_0, z)\varphi_z(y_0, z) \\
& + B_1(x, y, z_0)\theta_1(x, y) - B_1(x_0, y, z_0)\theta_1(x_0, y) - B_1(x, y_0, z_0)\theta_1(x, y_0) \\
& + B_1(x_0, y_0, z_0)\theta_1(x_0, y_0) + B_2(x_0, y, z)\varphi_1(y, z) + B_2(x, y_0, z)\psi_{1x}(x, z) \\
& - B_2(x_0, y_0, z)\varphi_1(y_0, z) + B_2(x, y, z_0)\theta(x, y) - B_2(x_0, y, z_0)\varphi_1(y, z_0) \\
& - B_2(x, y_0, z_0)\theta_x(x, y_0) + B_2(x_0, y_0, z_0)\varphi_1(y_0, z_0) + B_3(x_0, y, z)\varphi_y(y, z) \\
& + B_3(x, y_0, z)\psi_1(x, z) - B_3(x_0, y_0, z)\psi_1(x_0, z) + B_3(x, y, z_0)\theta_y(x, y) \\
& - B_3(x_0, y, z_0)\varphi_y(y, z_0) - B_3(x, y_0, z_0)\psi_1(x, z_0) + B_3(x_0, y_0, z_0)\psi_1(x_0, z_0) \\
& - C_1(x_0, y, z)\varphi(y, z) - C_1(x, y_0, z)\psi(x, z) + C_1(x_0, y_0, z)\varphi(y_0, z) \\
& - C_1(x, y, z_0)\theta(x, y) + C_1(x_0, y, z_0)\varphi(y, z_0) + C_1(x, y_0, z_0)\psi(x, z_0) \\
& - C_1(x_0, y_0, z_0)\varphi(y_0, z_0) \\
& + \int_{x_0}^x \{ B_6(\alpha, y_0, z)\psi_{1z}(\alpha, z) + B_6(\alpha, y, z_0)\theta_{1y}(\alpha, y) + B_6(\alpha, y_0, z_0)\psi_{1z}(\alpha, z_0) \\
& - C_6(\alpha, y_0, z)\psi_1(\alpha, z) - C_6(\alpha, y, z_0)\theta_y(\alpha, y) + C_6(\alpha, y_0, z_0)\psi_1(\alpha, z_0) \\
& - C_7(\alpha, y_0, z)\psi_z(\alpha, z) - C_7(\alpha, y, z_0)\theta_1(\alpha, y) + C_7(\alpha, y_0, z_0)\theta_1(\alpha, y_0) \\
& + D_3(\alpha, y_0, z)\psi(\alpha, z) + D_3(\alpha, y, z_0)\theta(\alpha, y) - D_3(\alpha, y_0, z_0)\psi(\alpha, z_0) \} d\alpha
\end{aligned}$$

$$\begin{aligned}
& + \int_{y_0}^y \{B_5(x, \beta, z_0)\theta_{1x}(x, \beta) + B_5(x_0, \beta, z)\varphi_{1z}(\beta, z) - B_5(x_0, \beta, z_0)\varphi_{1z}(\beta, z_0) \\
& \quad - C_2(x_0, \beta, z)\varphi_z(\beta, z) - C_2(x, \beta, z_0)\theta_1(x, \beta) + C_2(x_0, \beta, z_0)\theta_1(x_0, \beta) \\
& \quad - C_5(x_0, \beta, z)\varphi_1(\beta, z) - C_5(x, \beta, z_0)\theta_x(x, \beta) + C_5(x_0, \beta, z_0)\varphi_1(\beta, z_0) \\
& \quad + D_2(x_0, \beta, z)\varphi(\beta, z) + D_2(x, \beta, z_0)\theta(x, \beta) - D_2(x_0, \beta, z_0)\varphi(\beta, z_0)\}d\beta \\
& + \int_{z_0}^z \{B_4(x_0, y, \gamma)\varphi_{1y}(y, \gamma) + B_4(x, y_0, \gamma)\psi_{1x}(x, \gamma) - B_4(x_0, y_0, \gamma)\varphi_{1y}(y_0, \gamma) \\
& \quad - C_3(x_0, y, \gamma)\varphi_y(y, \gamma) - C_3(x, y_0, \gamma)\psi_1(x, \gamma) + C_3(x_0, y_0, \gamma)\psi_1(x_0, \gamma) \\
& \quad - C_4(x_0, y, \gamma)\varphi_1(y, \gamma) - C_4(x, y_0, \gamma)\psi_x(x, \gamma) + C_4(x_0, y_0, \gamma)\varphi_1(y_0, \gamma) \\
& \quad + D_1(x_0, y, \gamma)\varphi(y, \gamma) + D_1(x, y_0, \gamma)\psi(x, \gamma) - D_1(x_0, y_0, \gamma)\varphi(y_0, \gamma)\}d\gamma \\
& + \int_{x_0}^x \int_{y_0}^y \{D_4(\alpha, \beta, z_0)\theta_1(\alpha, \beta) - E_1(\alpha, \beta, z_0)\theta(\alpha, \beta)\}d\beta d\alpha \\
& + \int_{x_0}^x \int_{z_0}^z \{D_5(\alpha, y_0, \gamma)\psi_1(\alpha, \gamma) - E_2(\alpha, y_0, \gamma)\psi(\alpha, \gamma)\}d\gamma d\alpha \\
& + \int_{y_0}^y \int_{z_0}^z \{D_6(x_0, \beta, \gamma)\varphi_1(\beta, \gamma) - E_1(x_0, \beta, \gamma)\varphi(\beta, \gamma)\}d\gamma d\beta. \tag{10}
\end{aligned}$$

Hence, marking the right part (10) without the first addend as $H(x, y, z, x, y, z)$, we come to the solution of the problem under our consideration (1) and (3):

$$\begin{aligned}
u(x, y, z) & = \varphi(y, z) + \psi(x, z) + \theta(x, y) - \varphi(y_0, z) - \psi(x, z_0) - \theta(x_0, y) + \varphi(y_0, z_0) \\
& \quad + \int_{x_0}^x \int_{y_0}^y \int_{z_0}^z H(\alpha, \beta, \gamma, \alpha, \beta, \gamma) d\gamma d\beta d\alpha \\
& \quad + \int_{x_0}^x \int_{x_0}^\alpha \int_{y_0}^y \int_{y_0}^\beta \int_{z_0}^z \int_{z_0}^\gamma R(t_1, t_2, t_3, \alpha, \beta, \gamma) F(t_1, t_2, t_3) dt_3 d\gamma dt_2 d\beta dt_1 d\alpha. \tag{11}
\end{aligned}$$

Smoothness (differentiable) conditions (2) for coefficients of the equation (1) provide belonging to the solution class $C^{2+2+2}(D)$. If we consider the functions $\varphi, \varphi_1, \psi, \psi_1, \theta, \theta_1$ as derivatives we may consider (10) and (11) as a general representation of the solution for the equation (1), in the similar way as it is done in [15] for the equation with the higher derivative u_{xy} . Therefore, our results may be formulated as follows:

Theorem. *The Goursat problem for the equation (1) with the boundary conditions (3) and conditions (4) has the solution which is written by means of the formula (11).*

Special cases

Formulas (10) and (11) provide for the solution of the problem (1) under the conditions (3) in quadratures if the explicit form R is known. We shall mention some of these cases that were obtained by means of direct solution (5).

Let us consider seven coefficients of the equation (1) $a_{221}, a_{212}, a_{122}, a_{112}, a_{211}, a_{121}, a_{111}$ as different from zero while all the others are identically equal to zero. Here (5) has

the same form as the equation (4) from the paper [11]. We consider that the following identities are satisfied:

$$\begin{aligned} \frac{\partial a_{220}}{\partial y} + a_{220}a_{121} - a_{120} &\equiv 0, & \frac{\partial a_{220}}{\partial y} + a_{220}a_{211} - a_{210} &\equiv 0, \\ \frac{\partial a_{121}}{\partial y} + a_{121}a_{211} - a_{111} &\equiv 0, & \frac{\partial a_{120}}{\partial y} + a_{120}a_{211} - a_{110} &\equiv 0. \end{aligned} \tag{12}$$

Then, it follows from [11] that the Riemann function has the form:

$$R(x, y, z, \zeta, \eta, \varsigma) = \exp \left[\int_{\zeta}^z a_{220}(\zeta, \eta, \gamma) d\gamma + \int_{\zeta}^x a_{121}(\alpha, \beta, z) d\alpha + \int_{\eta}^y a_{211}(\alpha, \beta, z) d\beta \right].$$

If the last identity (12) is non-zero but of the product $\lambda(x)\mu(y)\nu(z)$ and when

$$a_{220} = A(z) + \delta xy, \quad a_{121} = B(x) + \delta yz, \quad a_{211} = C(y) + \delta xz,$$

by using the formulas (18) and (25) from [11] we obtain the following

$$R(x, y, z, \zeta, \eta, \varsigma) = R_0(x, y, z, \zeta, \eta, \varsigma) {}_0F_2(1, 1, \omega),$$

where ${}_0F_2$ - is the generalized (distributed) hyper-geometrical function (see, [16] pp,20) while

$$\begin{aligned} R_0 &\equiv \exp \left[\int_{\zeta}^x B(\alpha) d\alpha + \int_{\eta}^y C(\beta) d\beta + \int_{\zeta}^z A(\gamma) d\gamma + \delta(xyz - \zeta\eta\varsigma) \right], \\ \omega &= \int_{\zeta}^x \lambda(\alpha) d\alpha \int_{\beta}^y \mu(\beta) d\beta \int_{\zeta}^z \nu(\gamma) d\gamma \end{aligned}$$

In the similar manner we can also calculate V in other cases when in (5) only one of coefficients $a_{\alpha\beta\gamma}$, having a defined structure, is different from the identical zero.

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