

**ASYMPTOTICALLY POWER SOLUTIONS OF HIGHER ORDER  
NEUTRAL FUNCTIONAL DIFFERENTIAL EQUATIONS**

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**Abstract.** Necessary and sufficient conditions are derived for the existence of asymptotically polynomial solutions of a class of neutral functional differential equations.

In [1, 2],  $n$ -th order neutral functional differential equations of the form

$$(x(t) + c(t)x(t-d))^{(n)} + f(t, x(g_1(t)), x(g_2(t)), \dots, x(g_m(t))) = 0, t \geq t_0, \quad (1)$$

are investigated and necessary and sufficient conditions for the existence of nonoscillatory solutions are derived. We observed that in these papers, the condition that  $c(t) \geq -1$  is assumed. The question then arises as to whether existence criteria can be established in case  $c(t) < -1$ .

In this note, we will show that under the basic assumptions that  $f$  is either superlinear or sublinear and that  $\lim_{t \rightarrow \infty} c(t) = c_0 < -1$ , necessary and sufficient conditions can be found for the existence of “asymptotically power” solutions.

More precisely, let  $d > 0$ ,  $h > 0$ ,  $m \in \{1, 2, \dots\}$  and  $n \in \{2, 3, \dots\}$ . Let  $c \in C([t_0, +\infty), R)$  and  $\lim_{t \rightarrow +\infty} c(t) = c_0$ . We assume that  $g_1, g_2, \dots, g_m \in C([t_0, +\infty), R)$  and satisfy  $g_1(t), \dots, g_m(t) \geq t - h$  for some constant  $h > 0$ ,  $f(t, x_1, x_2, \dots, x_m) \in C([t_0, +\infty) \times R^m, R)$ , and,

$$x_1 f(t, x_1, x_2, \dots, x_m) > 0, t \geq t_0,$$

if  $x_1 x_i > 0$  for  $i = 1, 2, \dots, m$ .

A function  $f(t, x_1, x_2, \dots, x_m)$  is said to be superlinear if there exist continuous functions  $p_i(t) \geq 0$  for  $i = 1, 2, \dots, m$ , satisfying  $\sum_{i=0}^m p_i(t) > 0$  and

$$\frac{f(t, y_1, y_2, \dots, y_m)}{\sum_{i=0}^m p_i(t) y_i} \geq \frac{f(t, x_1, x_2, \dots, x_m)}{\sum_{i=0}^m p_i(t) x_i} \quad (2)$$

when  $y_i \geq x_i > 0$  or  $y_i \leq x_i < 0$  for  $i = 1, 2, \dots, m$ . If the inequality  $\geq$  in (2) is changed into  $\leq$ , then the function  $f(t, x_1, x_2, \dots, x_m)$  is said to be sublinear.

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The following is shown in [1] which can also be shown easily.

**Lemma 1.** *Suppose that  $0 < a \leq x_i \leq b$  for  $i = 1, 2, \dots, m$ . If  $f$  is superlinear, then*

$$f(t, a, \dots, a) \leq f(t, x_1, \dots, x_m) \leq f(t, b, \dots, b), \quad t \geq t_0.$$

If  $f$  is sublinear, then

$$\frac{a}{b}f(t, b, \dots, b) \leq f(t, x_1, \dots, x_m) \leq \frac{b}{a}f(t, a, \dots, a), \quad t \geq t_0.$$

**Lemma 2.** *Suppose that  $\lim_{t \rightarrow +\infty} c(t) = c_0 \neq \pm 1$  and that  $x(t)/t^i$  is bounded and eventually positive or eventually negative, where  $i$  is a nonnegative integer. Let  $z(t) = x(t) + c(t)x(t-d)$ . If  $\lim_{t \rightarrow +\infty} z(t)/t^i = b$  exists, then  $\lim_{t \rightarrow +\infty} x(t)/t^i = b/(1+c_0)$ .*

The proof is similar to that of Lemma 2 in [1] and is omitted.

**Lemma 3.** (Krasnoselskii [1]) *Suppose  $B$  is a Banach space and  $X$  is a bounded, convex and closed subset of  $B$ . Let  $U, S : X \rightarrow B$  satisfy the following conditions:*

- (i)  $Ux + Sy$  for any  $x, y \in X$ ,
- (ii)  $U$  is a contraction mapping, and
- (iii)  $S$  is completely continuous.

Then  $U + S$  has a fixed point in  $X$ .

As usual, a solution  $x(t)$  of (1) is said to be nonoscillatory if it eventually positive or eventually negative. A nonoscillatory solution  $x(t)$  of (1) is said to be asymptotically constant or belong to  $T_0(a)$  if

$$\lim_{t \rightarrow +\infty} x(t) = a \neq 0.$$

Two natural extensions of the concept of an asymptotically constant solution can be stated as follows. A nonoscillatory solution  $x(t)$  of (1) is said to belong to  $T_r(\infty, a)$ , where  $r \in \{1, 2, \dots, n-1\}$ , if

$$\limsup_{t \rightarrow +\infty} \frac{|x(t)|}{t^{r-1}} = +\infty \text{ and } \limsup_{t \rightarrow +\infty} \frac{|x(t)|}{t^r} = a \neq 0,$$

and said to belong to  $T_r(a, 0)$ , where  $r \in \{1, 2, \dots, n-1\}$ , if

$$\limsup_{t \rightarrow +\infty} \frac{|x(t)|}{t^{r-1}} = a \neq 0 \text{ and } \limsup_{t \rightarrow +\infty} \frac{|x(t)|}{t^r} = 0.$$

We will be interested in finding necessary and sufficient conditions for the existence of solutions in  $T_0(a)$ ,  $T_r(\infty, a)$  and  $T_r(a, 0)$ .

**Theorem 1.** *Suppose  $\lim_{t \rightarrow +\infty} c(t) = c_0 < -1$  and  $f$  is either superlinear or sublinear. Then (1) has a nonoscillatory solution  $x(t) \in T_r(\infty, a)$  if, and only if, there is some  $K \neq 0$  such that*

$$\int_{t_0}^{+\infty} s^{n-r-1} |f(s, Kg_1^r(s), Kg_2^r(s), \dots, Kg_m^r(s))| ds < +\infty. \quad (3)$$

If  $r = 0$ ,  $T_r(\infty, a)$  can be replaced by  $T_0(a)$  in the above statement.

**Proof.** Let

$$G_x(t) = f(t, x(g_1(t)), x(g_2(t)), \dots, x(g_m(t))), \tag{4}$$

and

$$F_r(t) = f(t, Kg_1^r(t), Kg_2^r(t), \dots, Kg_m^r(t)). \tag{5}$$

Since

$$\int_{\alpha}^x (x - y)^n g(y) dy = n! \int_{\alpha}^x dy_n \int_{\alpha}^{y_n} dy_{n-1} \dots \int_{\alpha}^{y_2} dy_1 \int_{\alpha}^{y_1} g(y) dy,$$

(3) is equivalent to

$$\int_{t_0}^{+\infty} \int_{s_{n-r-1}}^{+\infty} \dots \int_{s_1}^{+\infty} |F_r(s)| ds ds_1 \dots ds_{n-r-1} < +\infty. \tag{6}$$

Let  $x(t)$  be an eventually positive solution of (1) in  $T_r(\infty, a)$ . Then without loss of generality, we may suppose there exists  $T > t_0$  such that  $x(t) > 0$ ,  $x(t - d) > 0$  and  $x(g_i(t)) > 0$  for  $t \geq T$  and  $i = 1, 2, \dots, m$ . Let

$$z(t) = x(t) + c(t)x(t - d).$$

Then, by (1), we have

$$z^{(n)}(t) = -f(t, x(g_1(t)), x(g_2(t)), \dots, x(g_m(t))). \tag{7}$$

In view of (1), we have  $z^{(n)}(t) < 0$  for  $t \geq T$ . Therefore  $z^{(i)}(t)$  is eventually monotonic for all  $i \in \{0, 1, 2, \dots, n - 1\}$ . Since  $\lim_{t \rightarrow +\infty} \frac{x(t)}{t^r} = a > 0$ , there exists  $T_1 \geq T$  such that

$$\frac{1}{2}at^r \leq x(t) \leq \frac{3}{2}at^r, t \geq T_1. \tag{8}$$

Noticing  $\lim_{t \rightarrow +\infty} \frac{z(t)}{t^r} = (1 + c_0)a$ , we have

$$\lim_{t \rightarrow +\infty} z^{(r)}(t) = (1 + c_0)ar!. \tag{9}$$

Invoking the monotonicity of  $z^{(i)}(t)$  and (9), we have

$$\lim_{t \rightarrow +\infty} z^{(i)}(t) = 0, i = r + 1, r + 2, \dots, n - 1. \tag{10}$$

After integrating (7)  $n - r - 1$  times, we obtain

$$z^{(r+1)}(t) = (-1)^{n-r} \int_t^{+\infty} \int_{s_{n-r-2}}^{+\infty} \dots \int_{s_1}^{+\infty} G_x(s) ds ds_1 \dots ds_{n-r-2}, t \geq T_1.$$

Then integrating the above formula from  $T_1$  to  $t$ , we obtain

$$z^{(r)}(t) = z^{(r)}(T) + (-1)^{n-r} \int_{T_1}^t \int_{s_{n-r-1}}^{+\infty} \int_{s_{n-r-2}}^{+\infty} \dots \int_{s_1}^{+\infty} G_x(s) ds ds_1 \dots ds_{n-r-1}.$$

In view of (9), we have

$$\int_{T_1}^{+\infty} \int_{s_{n-r-1}}^{+\infty} \int_{s_{n-r-2}}^{+\infty} \dots \int_{s_1}^{+\infty} G_x(s) ds ds_1 \dots ds_{n-r-1} < +\infty. \tag{11}$$

In view of Lemma 1 and (8), we see that  $F_r(t) \leq G_x(t)$  where we set  $K = a/2$  if  $f$  is superlinear, and  $F_r(t) \leq 3G_x(t)$  where we set  $K = 3a/2$  if  $f$  is sublinear. In view of (11), we see that (7) holds when  $x(t)$  is eventually positive.

The case that  $x(t)$  is eventually negative can be proved in a similar manner.

Conversely, suppose that  $K > 0$ . Let  $e = K/2$  if  $f$  is superlinear and  $e = K$  if  $f$  is sublinear. Set  $R(t) = t^r$  or  $R(t) \equiv 1$  when  $r = 0$ . Take  $c_1$  and  $c_2$  so that  $(-8c_0 - 1)/7 > c_2 > |c_0| > c_1 > 1$ . Then  $c_0 < -(7c_2 + 1)/8$ . Since

$$\lim_{t \rightarrow +\infty} \frac{7 - 7c_2 - 8c(t+d)}{8} = \frac{7 - 7c_2 - 8c_0}{8} > 1$$

and

$$\lim_{t \rightarrow +\infty} (c(t) + c_2) = c_0 + c_2 < \frac{1}{8}(c_2 - 1),$$

there exists a sufficiently large  $T > t_0 + h + d$  such that when  $t \geq T$ , we have

$$\frac{1}{|c(t+d)|} \frac{R^2(t+d)}{R^2(t-d-h)} \leq \frac{1}{c_1}, \tag{12}$$

$$|c(t)| \geq c_1, |c(t)| \leq c_2, \tag{13}$$

$$c(t) + c_2 \leq \frac{1}{8}(c_2 - 1), \tag{14}$$

$$\frac{R(t+d)}{R(t)} \leq \frac{7 - 7c_2 - 8c(t+d)}{8}, \tag{15}$$

and

$$\int_T^{+\infty} \int_{s_{n-r-1}}^{+\infty} \int_{s_{n-r-2}}^{+\infty} \dots \int_{s_1}^{+\infty} F_r(s) ds ds_1 \dots ds_{n-r-1} < \frac{c_2 - 1}{8} e. \tag{16}$$

Take  $\bar{T} = T - d - h$  and the linear space

$$C_R[\bar{T}, +\infty) = \left\{ x \in C([\bar{T}, +\infty), R) : \sup_{t \geq \bar{T}} \frac{|x(t)|}{R^2(t)} < +\infty \right\}$$

with norm  $\|x\|_R = \sup_{t \geq \bar{T}} \frac{|x(t)|}{R^2(t)}$ . Then  $C_R[\bar{T}, +\infty)$  is a Banach space. Set

$$X = \{x \in C[\bar{T}, +\infty) : eR(t) \leq x(t) \leq 2eR(t)\}.$$

Then it is obvious that  $X$  is a bounded convex and closed subset of  $C_R[\bar{T}, +\infty)$  and for any  $x \in X$  and  $t \geq \bar{T} + h$ ,

$$G_x(t) \leq 2F_r(t). \tag{17}$$

Define two operators on  $X$  as follows:

$$(Ux)(t) = \begin{cases} \frac{3eR(t)}{2c(T+d)} - \frac{1}{c(T+d)} \frac{x(T+d)}{R(T)} R(t) & \bar{T} \leq t < T \\ \frac{3eR(t)}{2c(t+d)} - \frac{1}{c(t+d)} x(t+d) & t \geq T \end{cases},$$

and

$$(Sx)(t) = \begin{cases} -\frac{3c_2eR(t)}{2c(T+d)} & \bar{T} \leq t < T \\ -\frac{3c_2eR(t)}{2c(t+d)} + \frac{(-1)^{n-r-1}}{c(t+d)} H(t) & t \geq T \end{cases}$$

where

$$H(t) = \int_{T+d}^{t+d} \int_T^{s_{n-1}} \dots \int_T^{s_{n-r+1}} \int_{s_{n-r}}^{+\infty} \dots \int_{s_1}^{+\infty} G_x(s) ds ds_1 \dots ds_{n-1}.$$

We will show that the operator  $U$  and  $S$  satisfy the conditions of the Krasnoselskii fixed point theorem.

(i) First we assert that  $Ux + Sy \in X$  for any  $x, y \in X$ . Indeed, for  $t \in [\bar{T}, T)$ , in view of (13) and (15), we have

$$\begin{aligned} (Ux)(t) + (Sy)(t) &= \left( \frac{3(1-c_2)}{2c(T+d)} eR(T) - \frac{x(T+d)}{c(T+d)} \right) \frac{R(t)}{R(T)} \\ &\geq \left( \frac{3(1-c_2)}{2c(T+d)} eR(T) - \frac{eR(T+d)}{c(T+d)} \right) \frac{R(t)}{R(T)} \\ &\geq eR(t), \end{aligned}$$

and

$$\begin{aligned} (Ux)(t) + (Sy)(t) &\leq \left( \frac{3(1-c_2)}{2c(T+d)} eR(T) - \frac{2eR(T+d)}{c(T+d)} \right) \frac{R(t)}{R(T)} \\ &= \left( \frac{3(1-c_2)}{2c(T+d)} - \frac{2}{c(T+d)} \frac{R(T+d)}{R(T)} \right) eR(t) \\ &\leq \left( \frac{3(1-c_2)}{2c(T+d)} - \frac{1}{c(T+d)} \frac{7-7c_2-8c(T+d)}{4} \right) \frac{R(t)}{R(T)} \\ &\leq 2eR(t). \end{aligned}$$

When  $t \in [T, +\infty)$ , in view of (16) and (17), we have

$$\int_T^t \int_T^{s_{n-1}} \dots \int_T^{s_{n-r+1}} \int_{s_{n-r}}^{+\infty} \dots \int_{s_1}^{+\infty} G_x(s) ds ds_1 \dots ds_{n-1} \leq \frac{(c_2-1)eR(t)}{4}. \tag{18}$$

Hence,

$$\begin{aligned}(Ux)(t) + (Sy)(t) &\geq \frac{3(1-c_2)}{2c(t+d)}eR(t) - \frac{x(t+d)}{c(t+d)} + \frac{(c_2-1)eR(t)}{4c(t+d)} \\ &\geq \left( \frac{3(1-c_2)}{2c(t+d)} - \frac{1}{c(t+d)} + \frac{c_2-1}{4c(t+d)} \right) eR(t) \\ &\geq eR(t).\end{aligned}$$

Again, in view of (15) and (18), we have

$$\begin{aligned}(Ux)(t) + (Sy)(t) &\leq \frac{3(1-c_2)}{2c(t+d)}eR(t) - \frac{x(t+d)}{c(t+d)} - \frac{(c_2-1)eR(t)}{4c(t+d)} \\ &= \frac{3(1-c_2)}{2c(t+d)}eR(t) - \frac{2e}{c(t+d)} \frac{R(t+d)}{R(t)} R(t) - \frac{(c_2-1)eR(t)}{4c(t+d)} \\ &\leq \left( \frac{3(1-c_2)}{2c(t+d)} - \frac{7-7c_2-8c(t+d)}{4c(t+d)} - \frac{(c_2-1)}{4c(t+d)} \right) eR(t) \\ &\leq 2eR(t).\end{aligned}$$

That is,  $Ux + Sy \in X$ .

(ii) In view of (12),  $U$  is a contraction mapping since it is easy to see that

$$\frac{1}{R^2(t)} |(Ux)(t) - (Uy)(t)| \leq \frac{1}{c_1} \sup_{t \geq T} \frac{|x(t) - y(t)|}{R^2(t)}$$

for any  $x, y \in X$ .

(iii) The operator  $S$  is a completely continuous mapping. Indeed, we first note that (13) implies  $-c_2/c(t) \geq 1$  and (14) implies  $-c_2/c(t) \leq 8/7$ . Hence when  $t \in [\bar{T}, T)$ ,  $(Sx)(t) \geq 3eR(t)/2$  and  $(Sx)(t) \leq (3/2)(8/7)eR(t) \leq 2eR(t)$ . For  $t \in [T, +\infty)$ ,

$$\begin{aligned}(Sx)(t) &\geq -\frac{3c_2}{2c(t+d)}eR(t) + \frac{(c_2-1)eR(t)}{4c(t+d)} \\ &\geq \frac{eR(t)}{4c(t+d)}(-1-5c_2) \geq eR(t),\end{aligned}$$

and

$$\begin{aligned}(Sx)(t) &\leq -\frac{3c_2}{2c(t+d)}eR(t) - \frac{(c_2-1)eR(t)}{4c(t+d)} \\ &\leq \frac{(-7c_2+1)eR(t)}{4c(t+d)} \leq 2eR(t).\end{aligned}$$

Therefore the operator  $S$  maps  $X$  into  $X$ . The fact that  $S$  is continuous and  $SX$  is relatively compact can be proved in a manner similar to that in [1] and is omitted.

By the Krasnoselskii fixed point theorem, there then exists  $x \in X$  such that  $(Ux)(t) + (Sx)(t) = x(t)$ . Therefore,

$$x(t) = \frac{3(1 - c_2)}{2c(t + d)}eR(t) - \frac{x(t + d)}{c(t + d)} + \frac{(-1)^{n-r-1}}{c(t + d)}H(t), \quad t \geq T.$$

It is now clear that  $x(t)$  is a nonoscillatory solution of (1) and satisfies

$$\lim_{t \rightarrow +\infty} \frac{z(t)}{t^r} = \frac{3}{2}(1 - c_2)e.$$

By Lemma 2, we have

$$\lim_{t \rightarrow +\infty} \frac{x(t)}{t^r} = \frac{3(1 - c_2)e}{2(1 + c_0)} \text{ and } \lim_{t \rightarrow +\infty} \frac{x(t)}{t^{r-1}} = +\infty.$$

So  $x(t) \in T_r(\infty, a)$ . In a similar way, we can prove the other case where  $K < 0$ . Our proof is complete.

**Theorem 2.** *Suppose  $\lim_{t \rightarrow \infty} c(t) = c_0 < -1$  and  $f$  is superlinear or sublinear. Then  $x(t) \in T_r(a, 0)$  is a nonoscillatory solution of (1) if, and only if, there is some  $K \neq 0$  such that*

$$\int_{t_0}^{+\infty} s^{n-r} |f(s, Kg_1^{r-1}(s), Kg_2^{r-1}(s), \dots, Kg_m^{r-1}(s))| ds < +\infty.$$

The proof is similar to that of Theorem 1, except that the operator  $S$  is taken as follows:

$$(Sx)(t) = \begin{cases} -\frac{3c_2eR(t)}{2c(T+d)} & \bar{T} \leq t < T \\ -\frac{3c_2eR(t)}{2c(t+d)} + \frac{(-1)^{n-r}}{c(t+d)}H(t) & t \geq T \end{cases},$$

where  $H(t) = \int_{T+d}^{t+d} \int_T^{s_{n-1}} \dots \int_T^{s_{n-r+2}} \int_{s_{n-r+1}}^{+\infty} \dots \int_{s_1}^{+\infty} G_x(s) ds ds_1 \dots ds_{n-1}$  and  $R(t) = t^{r-1}$  if  $r > 1$  and  $R(t) \equiv 1$  if  $r = 1$ .

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