# THREE-DIMENSIONAL CR-SUBMANIFOLDS IN THE NEARLY KAEHLER SIX-SPHERE SATISFYING B.Y. CHEN'S BASIC EQUALITY

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**Abstract**. B. Y. Chen introduced in [3] an important Riemannian invariant for a Riemannian manifold and obtained a sharp inequality between his invariant and the squared mean curvature for arbitrary submanifolds in real space forms. In this paper we investigate 3-dimensional CR-submanifolds in the nearly Kaehler 6-sphere which realize the equality case of the inequality.

### 1. Introduction

Let  $M^n$  be an *n*-dimensional submanifold  $M^n$  in an *m*-dimensional real space form  $\tilde{M}^m(c)$  of constant sectional curvature *c*. In [3] B. Y. Chen introduces a Riemannian invariant  $\delta_M$  on  $M^n$  defined by  $\delta_M(p) = \tau(p) - \inf K(p)$ , where  $\inf K(p)$  is the infimum of the sectional curvature  $K(\pi)$  at  $p, \pi$  runs over all planes in the tangent space  $T_p M^n$  and  $\tau$  is the scalar curvature given by  $\tau = \sum_{i < j} K(e_i \wedge e_j)$  for an orthonormal basis  $e_1, \ldots, e_n$  of  $T_p M^n$ . Chen's invariant vanishes trivially when n = 2.

In [3] he proves the following basic inequality for arbitrary submanifolds  $M^n$  in a real space form  $\tilde{M}^m(c)$ :

$$\delta_M \le \frac{n^2(n-2)}{2(n-1)} ||H||^2 + \frac{1}{2}(n+1)(n-2)c, \tag{1.1}$$

where  $||H||^2$  is the squared mean curvature. It is a natural and very interesting problem to investigate and to understand submanifolds of dimension  $\geq 3$  satisfying the equality case of the inequality, i.e.

$$\delta_M = \frac{n^2(n-2)}{2(n-1)} ||H||^2 + \frac{1}{2}(n+1)(n-2)c, \qquad (1.2)$$

which is known as Chen's basic equality (see, for instance [10]). For such submanifolds there is a canonical distribution defined by

$$\mathcal{D}(p) = \{ X \in T_p M^n \,|\, (n-1)h(X,Y) = n \langle X,Y \rangle H, \forall Y \in T_p M^n \},\$$

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where h is the second fundamental form of  $M^n$  in  $\tilde{M}^m(c)$ . If the dimension of  $\mathcal{D}(p)$  is constant, it is shown in [3] that the distribution  $\mathcal{D}$  is completely integrable.

When M is a submanifold of an almost Hermitian manifold M, a subspace V of  $T_pM$  is called *totally real* if JV is contained in the normal space  $T_p^{\perp}M$  of M at p. The submanifold M is called *totally real* if each tangent space of M is totally real; and M is called a CR-submanifold if there exists a differential holomorphic distribution  $\mathcal{H}$  on M such that the orthogonal complement  $\mathcal{H}^{\perp}$  of  $\mathcal{H}$  in TM is a totally real distribution [1]. A CR-submanifold is called *proper* if it is neither totally real (i.e.,  $\mathcal{H}^{\perp} = TM$ ) nor holomorphic (i.e.,  $\mathcal{H} = TM$ ).

Submanifolds satisfying equality (1.2) have been studied recently by many geometers (see, for instance [2-6, 8-11]). In particular, 3-dimensional totally real submanifolds satisfying Chen's basic equality in the nearly Kaehler 6-sphere  $S^6(1)$  have been completely classified in [11] by F. Dillen and L. Vrancken.

In [5] Chen also established the basic inequality for arbitrary submanifolds in complex space forms of constant holomorphic sectional curvature 4c as follows:

$$\delta_M \le \frac{n^2(n-2)}{2(n-1)} ||H||^2 + \frac{1}{2}(n^2 + 2n - 2)c \quad (for \quad c > 0),$$
  
$$\delta_M \le \frac{n^2(n-2)}{2(n-1)} ||H||^2 + \frac{1}{2}(n+1)(n-2)c \quad (for \quad c < 0).$$

He proved that a submanifold of complex projective space satisfies Chen's basic equality if and only if the submanifold is a totally geodesic complex submanifold. Moreover in [7] he and L. Vrancken completely classified proper CR-submanifolds of complex hyperbolic spaces which satisfy the basic equality.

In complex hyperbolic space, the canonical distribution  $\mathcal{D}$  of submanifolds satisfying Chen's basic equality is totally real.

In this paper, we investigate 3-dimensional CR-submanifolds in the nearly Kaehler 6-sphere  $S^6(1)$  satisfying Chen's basic equality (1.2) under the condition that  $\mathcal{D}$  is totally real. Our main result is the following.

**Main Theorem.** There exist no 3-dimensional proper CR-submanifold in  $S^6(1)$  satisfying Chen's basic equality under the condition that  $\mathcal{D}$  is totally real.

# 2. The Nearly Kaehler Structure of $S^6(1)$

We give a brief explanation how the standard nearly Kaehler structure on  $S^6(1)$  arises in a natural manner from Cayley multiplication. For elementary facts about Cayley numbers and their automorphism group  $G_2$ , we refer the reader to [14] and [17].

The multiplication on Cayley numbers  $\vartheta$  may be used to define a vector cross product on purely imaginary Cayley numbers  $\mathbb{R}^7$  by using the formula

$$u \times v = \frac{1}{2}(uv - vu), \tag{2.1}$$

while the standard inner product on  $\mathbb{R}^7$  is given by

$$\langle u, v \rangle = -\frac{1}{2}(uv + vu). \tag{2.2}$$

It is elementary [12] to show that the triple scalar product  $\langle u \times v, w \rangle$  is skew symmetric in u, v, w.

Let J be the automorphism of the tangent bundle  $TS^6$  of  $S^6(1)$  defined by

 $Ju = x \times u, \quad u \in T_x S^6(1), \quad x \in S^6(1).$ 

It is clear that J is an almost complex structure on  $S^6(1)$  and J is in fact a nearly Kaehler structure on  $S^6(1)$  in the sense that  $(\tilde{\nabla}_u J)u = 0$ , for any vector u tangent to  $S^6(1)$ , where  $\tilde{\nabla}$  denotes the metric connection of  $S^6(1)$ . We define the corresponding skew-symmetric (2,1)-tensor field G by

$$G(X,Y) = (\tilde{\nabla}_X J)(Y).$$

We know from [16] that this tensor field satisfies the following property:

$$G(X, JY) + JG(X, Y) = 0.$$
 (2.3)

For further information on the properties of G, we refer to [6] and [16].

#### 3. Proof of the Main Theorem

We need the following lemmas.

**Lemma 3.1.** Let M be a CR-submanifold of a nearly Kaehler manifold  $\tilde{M}$ . Denote by  $T^{\perp}M = J\mathcal{H}^{\perp} \oplus \nu$  the orthogonal decomposition of the normal bundle, where  $\mathcal{H}^{\perp}$  is the totally real distribution and  $\nu$  a complex subbundle of  $T^{\perp}M$ . Then the shape operator Asatisfies

$$\langle A_{\xi}JX, X \rangle = -\langle A_{J\xi}X, X \rangle, \tag{3.1}$$

for any vector field X in the holomorphic distribution  $\mathcal{H}$  and  $\xi$  in  $\nu$ .

**Proof.** For any vector field X in the holomorphic distribution  $\mathcal{H}$ , we have

$$0 = (\nabla_X J)(X) = \nabla_X JX + h(X, JX) - J(\nabla_X X) - Jh(X, X),$$

where  $\nabla$  is the metric connection of M with respect to the induced metric. Hence we obtain  $\langle h(X, JX), \xi \rangle = \langle Jh(X, X), \xi \rangle$  for any vector field  $\xi \in \nu$ .

**Lemma 3.2.** Let M be a 3-dimensional proper minimal CR-submanifold in  $S^6(1)$ . If M satisfies equality (1.2) and  $\mathcal{D}$  is totally real, then  $\mathcal{D}^{\perp}$  is integrable.

**Proof.** Since  $\mathcal{D}^{\perp}$  is a complex plane  $(i.e, \mathcal{D}^{\perp} = \mathcal{H})$ , we can choose an orthonormal frame field  $\{E_1, E_2\}$  on  $\mathcal{D}^{\perp}$  such that  $JE_1 = E_2$ . By the minimality of M and lemma

3.2 of [3], the second fundamental h satisfies  $h(E_1, JE_2) = h(JE_1, E_2)$ . Moreover from (2.3) we have  $G(E_1, E_2) = 0$ . Hence, by virtue of [1, page 26],  $\mathcal{D}^{\perp}$  is integrable.

A submanifold is said to be *linearlyfull* in  $S^m(1)$  if it does not lie in any totally geodesic submanifold of  $S^m(1)$ .

**Lemma 3.3.** Let M be a 3-dimensional proper minimal CR-submanifold in  $S^6(1)$ . If M satisfies equality (1.2) and  $\mathcal{D}$  is totally real, then M is linearly full in a totally geodesic  $S^5(1)$ .

**Proof.** Let  $\{E_1, E_2, E_3\}$  be an orthonormal frame field on M such that  $\{E_1, E_2\} \in \mathcal{H}$ ,  $E_3 \in \mathcal{H}^{\perp}$  which diagonalize the shape operator  $A_{JE_3}$ . We may assume  $JE_1 = E_2$ . For any  $X \in TM$ , we have

$$-A_{JE_3}X + \nabla_X^{\perp}JE_3 = \tilde{\nabla}_X JE_3 = (\tilde{\nabla}_X J)(E_3) + J\nabla_X E_3 + Jh(X, E_3).$$
(3.2)

From (3.2) and lemma 3.2 of [3], we have

$$\nabla_{E_3}^{\perp} J E_3 = J(\nabla_{E_3} E_3) = 0. \tag{3.3}$$

Further from (3.2) and lemma 3.2 of [3], we have

$$-A_{JE_3}E_1 + \nabla_{E_1}^{\perp}JE_3 = (\tilde{\nabla}_{E_1}J)(E_3) + J(\nabla_{E_1}E_3).$$
(3.4)

Since G is skew-symmetric, we find

$$(\tilde{\nabla}_{E_1} J)(E_3) = -(\tilde{\nabla}_{E_3} J)(E_1) = -\nabla_{E_3} E_2 + J(\nabla_{E_3} E_1)$$
(3.5)

From (3.4) and (3.5), we obtain  $\nabla_{E_1}^{\perp}JE_3 \in J\mathcal{H}^{\perp}$  which implies  $\nabla_{E_1}^{\perp}JE_3 = 0$  because  $J\mathcal{H}^{\perp}$  is of rank one and  $JE_3$  is of unit length. Similarly, we also have  $\nabla_{E_2}^{\perp}JE_3 = 0$  Hence,  $JE_3$  is a parallel normal vector field. Thus, from the equation of Ricci, we have  $[A_{JE_3}, A_{\xi}] = 0$ .

If  $A_{JE_3} \equiv 0$ , the first normal space  $\nu$  is parallel i.e.  $\nabla^{\perp} \xi \in \nu$ ,  $\xi \in \nu$  by the parallelism of  $JE_3$ . Therefore, by Erbacher's theorem [12], M must be contained in a totally geodesic  $S^5(1)$ .

If  $A_{JE_3} \neq 0$ , we put  $V = \{p \in M : \det A_{JE_3} \neq 0\}$ . In this case, the shape operators take the following form on V:

$$A_{JE_3} = \begin{pmatrix} a & 0 & 0 \\ 0 & -a & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad A_{\xi_i} = \begin{pmatrix} h_{11}^i & 0 & 0 \\ 0 & -h_{11}^i & 0 \\ 0 & 0 & 0 \end{pmatrix},$$
(3.6)  
$$\xi_i \in \nu, \quad i = 1, 2.$$

Combining (3.1) with (3.6) yields  $A_{\xi_1} = A_{\xi_2} = 0$  which imply that V is contained in a totally geodesic  $S^4(1)$ , since  $JE_3$  is a parallel normal vector field. Therefore,  $TS^4(1)|_V$  is spanned by  $\{E_1, E_2, E_3, JE_3\}$ . A result of Gray in [13] shows that this is impossible.

For a given orthonormal frame field  $\{E_1, E_2, E_3\}$ , define local functions  $\gamma_{ij}^k$  by  $\gamma_{ij}^k = \langle \nabla_{E_i} E_j, E_k \rangle$ .

**Lemma 3.4.** Let M be a 3-dimensional proper minimal CR-submanifold in  $S^6(1)$ . If M satisfies equality (1.2) and  $\mathcal{D}$  is totally real, then, with respect to some suitable orthonormal frame field  $\{E_1, E_2, E_3\}$  on M, we have

$$\gamma_{33}^1 = \gamma_{33}^2 = 0 \tag{3.7}$$

$$\gamma_{11}^3 = \gamma_{22}^3 \tag{3.8}$$

$$\gamma_{12}^3 = -\gamma_{21}^3 \tag{3.9}$$

**Proof.** Let  $\{E_1, E_2, E_3\}$  be an orthonormal frame field mentioned in lemma 3.3. From  $A_{JE_3} = 0$  and (3.1), we know that the second fundamental form satisfies

$$h(E_1, E_1) = \phi\xi, \quad h(E_2, E_2) = -\phi\xi, \quad h(E_3, E_3) = 0,$$
  
$$h(E_1, E_2) = \phi J\xi, \quad h(E_1, E_3) = 0, \quad h(E_2, E_3) = 0,$$

where  $\phi$  is a function and  $\xi \in \nu$ . Thus, from  $(\nabla h)(E_1, E_3, E_3) = (\nabla h)(E_3, E_1, E_3)$ , we obtain  $\nabla_{E_3} E_3 = 0$ . Also from  $(\nabla h)(E_3, E_1, E_1) = (\nabla h)(E_1, E_3, E_1)$ , we obtain (3.8). Finally from  $(\nabla h)(E_1, E_2, E_3) = (\nabla h)(E_2, E_1, E_3)$ , we obtain (3.9).

From lemma 3.2, we know that the distribution  $\mathcal{D}^{\perp}$  locally spanned by  $E_1$  and  $E_2$  is an integrable distribution. Hence we get  $\gamma_{12}^3 = \gamma_{21}^3 = 0$ .

Similarly as [6], we have the following lemmas using lemma 3.4.

**Lemma 3.5.** The local function  $\gamma_{11}^3$  satisfies the following system of differential equations:

$$E_1(\gamma_{11}^3) = 0, \quad E_2(\gamma_{11}^3) = 0.$$

**Lemma 3.6.** Under the hypothesis of Lemma 3.4. Then, on a neighborhood of a given point  $p \in M$ , M is the warped product of an open interval  $(-\epsilon, \epsilon)$  and  $N^2$ ,  $N^2$  the leaf of the distribution  $\mathcal{D}^{\perp}$  through p.

From lemma 3.6 we may prove the following lemma.

**Lemma 3.7.** Let M be a 3-dimensional minimal CR-submanifold in  $S^6(1)$ . If M satisfies equality (1.2) and  $\mathcal{D}$  is totally real, then M is a totally real submanifold.

**Proof.** If M is proper, we obtain from Lemma 3.6 that M is locally a warped product and that the distribution on M determined by the product structure coincide with  $\mathcal{D}$ and  $\mathcal{D}^{\perp}$ . Moreover, since  $h(\mathcal{D}, \mathcal{D}^{\perp}) = 0$ , locally M is immersed as a warped product; furthermore, the first factor is totally geodesic, and therefore we can assume that the first factor of the corresponding warped product decomposition is 1-dimensional. Since the decomposition into a warped product with one-dimensional first factor is unique up to isometries, M is thus immersed as follows [6]:

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Let  $S^1_+(1) = \{(x_1, x_2) \in \mathbb{R}^2 | ||x|| = 1 \text{ and } x_1 > 0\}$  be a half circle,  $S^5(1)$  the unit hypersphere of  $\mathbb{R}^6$ , and N the unit vector orthogonal to the hyperplane containing  $S^5(1)$ . We parametrize the half circle  $S^1_+(1)$  by  $(-\frac{\pi}{2}, \frac{\pi}{2}) \to S^1_+(1)$ ,  $t \mapsto (\cos(t), \sin(t))$ . Let  $f: M^2 \to S^5(1)$  be a minimal immersion of a surface into  $S^5(1)$ . Then the associated warped product immersion is given by

$$x: \left(-\frac{\pi}{2}, \frac{\pi}{2}\right) \times_{\cos(t)} M^2 \to S^6(1), \quad (t, p) \mapsto \sin(t)N + \cos(t)f(p).$$

Let X be a vector field tangent to  $M^2$ . Then

$$x_*(\frac{\partial}{\partial t}) = \cos(t)N - \sin(t)f(p), \quad x_*(X) = \cos(t)f_*(X),$$

and

$$Jx_*(\frac{\partial}{\partial t}) = N \times f(p), \quad Jx_*(X) = \cos(t)\sin(t)N \times f_*(X) + \cos^2(t)Jf_*(X).$$

Since  $\mathcal{D} = \operatorname{span}\{\frac{\partial}{\partial t}\}$  is totally real, we have

$$\langle N \times f(p), f_*(X) \rangle = 0. \tag{3.10}$$

Differentiating (3.10) yields

$$\langle N \times f_*(Y), f_*(X) \rangle + \langle N \times p, h(X, Y) \rangle = 0, \qquad (3.11)$$

for any vector fields X and Y tangent to  $M^2$ . Because the first term in (3.11) is skew symmetric and the second is symmetric, both terms must vanish. Hence we obtain

$$\langle N \times f_*(X), f_*(Y) \rangle = 0$$

which implies  $\mathcal{D}^{\perp}$  is not a complex plane. This is a contradiction. Hence, M must be nonproper.

**Lemma 3.8.** Let M be a 3-dimensional nonminimal CR-submanifold in  $S^6(1)$  which satisfies equality (1.2). If  $\mathcal{D}$  is totally real, then  $H \in J\mathcal{D}$ .

**Proof** Let  $\{E_1, E_2, E_3\}$  be an orthonormal frame field on M such that  $\{E_1, E_2\} \in \mathcal{H}$ . Without loss of generality we may assume  $JE_1 = E_2$ . Thus, (3.1) gives

$$\langle A_{\xi}E_1, E_1 \rangle + \langle A_{\xi}JE_1, JE_1 \rangle = \langle A_{J\xi}JE_1, E_1 \rangle - \langle A_{J\xi}E_1, JE_1 \rangle = 0$$

for every vector field  $\xi \in \nu$ . Therefore, the mean curvature vector H lies in  $J\mathcal{D}$ .

From lemma 3.8 we have the following.

**Lemma 3.9.** Let M be a 3-dimensional nonminimal proper CR-submanifold in  $S^{6}(1)$  which satisfies equality (1.2). Then  $\mathcal{D}$  is not totally real.

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**Proof.** If  $\mathcal{D}$  is totally real, we have  $H \in J\mathcal{D}$  from lemma 3.8. Without loss of generality we may assume  $JE_3$  is parallel to the mean curvature vector. By (3.2), we obtain that  $JE_3$  is a parallel normal vector field. Further, form the equation of Ricci we have  $[A_{JE_3}, A_{\xi}] = 0$  for any  $\xi \in \nu$ . By lemma 3.2 of [3], this implies that, with respect to a suitable orthonormal frame field with  $E_2 = JE_1$ , the shape operators either take the form:

$$A_{JE_3} = \begin{pmatrix} a \ 0 \ 0 \\ 0 \ a \ 0 \\ 0 \ 0 \ 2a \end{pmatrix}, \quad A_{\xi_i} = \begin{pmatrix} h_{11}^i \ h_{12}^i \ 0 \\ h_{12}^i - h_{11}^i \ 0 \\ 0 \ 0 \ 0 \end{pmatrix}, \quad i = 1, 2,$$
(3.12)

or take the form:

$$A_{JE_3} = \begin{pmatrix} b \ 0 & 0 \\ 0 \ c & 0 \\ 0 \ 0 \ b + c \end{pmatrix}, \quad A_{\xi_i} = \begin{pmatrix} h_{11}^i & 0 & 0 \\ 0 & -h_{11}^i & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad i = 1, 2,$$
(3.13)

where a, b, c are functions such that  $b \neq c$  and  $\xi_i \in \nu$ .

If the shape operators take the form (3.13), then by combining (3.1) with (3.13), we obtain  $A_{\xi_1} = A_{\xi_2} = 0$ . Since  $JE_3$  is a parallel normal vector field, this implies that M is contained in a totally geodesic  $S^4(1)$ . Since the tangent space of this sphere  $S^4(1)$  is spanned by  $\{E_1, E_2, E_3, JE_3\}$ ,  $S^4(1)$  is an almost complex submanifold in  $S^6(1)$  which is a contradiction. Hence the shape operators must take the form (3.12). Therefore, the second fundamental form satisfies

$$h(E_1, E_1) = aJE_3 + \phi\xi, \quad h(E_2, E_2) = aJE_3 - \phi\xi, \quad h(E_3, E_3) = 2aJE_3$$
  
$$h(E_1, E_3) = 0, \quad h(E_1, E_2) = \phi J\xi, \quad h(E_2, E_3) = 0, \quad (3.14)$$

for some function  $\phi$  and some  $\xi \in \nu$ . From (3.14) we find

$$(\nabla h)(E_1, E_2, E_3) = -\gamma_{12}^3 a J E_3 - \gamma_{13}^1 \phi J \xi + \gamma_{13}^2 \phi \xi, \qquad (3.15)$$

$$(\nabla h)(E_2, E_1, E_3) = -\gamma_{21}^3 a J E_3 - \gamma_{23}^2 \phi J \xi - \gamma_{23}^1 \phi \xi.$$
(3.16)

If we put  $W_1 = \{p \in M : a(p) \neq 0\}$  and  $W_2 = \{q \in M : \phi(q) \neq 0\}$ , then the equation of Codazzi, (3.15) and (3.16) yield

$$\gamma_{12}^3 = \gamma_{21}^3 = 0 \quad on \quad W_1 \cap W_2$$

which implies that  $\mathcal{D}^{\perp}$  is integrable on  $W_1 \cap W_2$ . Hence by virtue of [1, page 26], we conclude that  $W_1 \cap W_2$  is minimal, which is a contradiction. Hence,  $\mathcal{D}$  cannot be totally real.

The main theorem follows from Lemma 3.7 and Lemma 3.9.

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