# THREE-DIMENSIONAL CR-SUBMANIFOLDS IN THE NEARLY KAEHLER SIX-SPHERE SATISFYING B.Y. CHEN'S BASIC EQUALITY 

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#### Abstract

B. Y. Chen introduced in [3] an important Riemannian invariant for a Riemannian manifold and obtained a sharp inequality between his invariant and the squared mean curvature for arbitrary submanifolds in real space forms. In this paper we investigate 3-dimensional CRsubmanifolds in the nearly Kaehler 6 -sphere which realize the equality case of the inequality.


## 1. Introduction

Let $M^{n}$ be an $n$-dimensional submanifold $M^{n}$ in an $m$-dimensional real space form $\tilde{M}^{m}(c)$ of constant sectional curvature $c$. In [3] B. Y. Chen introduces a Riemannian invariant $\delta_{M}$ on $M^{n}$ defined by $\delta_{M}(p)=\tau(p)-\inf K(p)$, where $\inf K(p)$ is the infimum of the sectional curvature $K(\pi)$ at $p, \pi$ runs over all planes in the tangent space $T_{p} M^{n}$ and $\tau$ is the scalar curvature given by $\tau=\sum_{i<j} K\left(e_{i} \wedge e_{j}\right)$ for an orthonormal basis $e_{1}, \ldots, e_{n}$ of $T_{p} M^{n}$. Chen's invariant vanishes trivially when $n=2$.

In [3] he proves the following basic inequality for arbitrary submanifolds $M^{n}$ in a real space form $\tilde{M}^{m}(c)$ :

$$
\begin{equation*}
\delta_{M} \leq \frac{n^{2}(n-2)}{2(n-1)}\|H\|^{2}+\frac{1}{2}(n+1)(n-2) c \tag{1.1}
\end{equation*}
$$

where $\|H\|^{2}$ is the squared mean curvature. It is a natural and very interesting problem to investigate and to understand submanifolds of dimension $\geq 3$ satisfying the equality case of the inequality, i.e.

$$
\begin{equation*}
\delta_{M}=\frac{n^{2}(n-2)}{2(n-1)}\|H\|^{2}+\frac{1}{2}(n+1)(n-2) c, \tag{1.2}
\end{equation*}
$$

which is known as Chen's basic equality (see, for instance [10]). For such submanifolds there is a canonical distribution defined by

$$
\mathcal{D}(p)=\left\{X \in T_{p} M^{n} \mid(n-1) h(X, Y)=n\langle X, Y\rangle H, \forall Y \in T_{p} M^{n}\right\}
$$

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where $h$ is the second fundamental form of $M^{n}$ in $\tilde{M}^{m}(c)$. If the dimension of $\mathcal{D}(p)$ is constant, it is shown in [3] that the distribution $\mathcal{D}$ is completely integrable.

When $M$ is a submanifold of an almost Hermitian manifold $\tilde{M}$, a subspace $V$ of $T_{p} M$ is called totally real if $J V$ is contained in the normal space $T_{p}^{\perp} M$ of $M$ at $p$. The submanifold $M$ is called totally real if each tangent space of $M$ is totally real; and $M$ is called a $C R$-submanifold if there exists a differential holomorphic distribution $\mathcal{H}$ on $M$ such that the orthogonal complement $\mathcal{H}^{\perp}$ of $\mathcal{H}$ in $T M$ is a totally real distribution [1]. A $C R$-submanifold is called proper if it is neither totally real (i.e., $\mathcal{H}^{\perp}=T M$ ) nor holomorphic (i.e., $\mathcal{H}=T M$ ).

Submanifolds satisfying equality (1.2) have been studied recently by many geometers (see, for instance [2-6, 8-11]). In particular, 3-dimensional totally real submanifolds satisfying Chen's basic equality in the nearly Kaehler 6 -sphere $S^{6}(1)$ have been completely classified in [11] by F. Dillen and L. Vrancken.

In [5] Chen also established the basic inequality for arbitrary submanifolds in complex space forms of constant holomorphic sectional curvature $4 c$ as follows:

$$
\begin{aligned}
& \delta_{M} \leq \frac{n^{2}(n-2)}{2(n-1)}\|H\|^{2}+\frac{1}{2}\left(n^{2}+2 n-2\right) c \quad(\text { for } \quad c>0) \\
& \delta_{M} \leq \frac{n^{2}(n-2)}{2(n-1)}\|H\|^{2}+\frac{1}{2}(n+1)(n-2) c \quad(\text { for } \quad c<0) .
\end{aligned}
$$

He proved that a submanifold of complex projective space satisfies Chen's basic equality if and only if the submanifold is a totally geodesic complex submanifold. Moreover in [7] he and L. Vrancken completely classified proper $C R$-submanifolds of complex hyperbolic spaces which satisfy the basic equality.

In complex hyperbolic space, the canonical distribution $\mathcal{D}$ of submanifolds satisfying Chen's basic equality is totally real.

In this paper, we investigate 3-dimensional $C R$-submanifolds in the nearly Kaehler 6 -sphere $S^{6}(1)$ satisfying Chen's basic equality (1.2) under the condition that $\mathcal{D}$ is totally real. Our main result is the following.

Main Theorem. There exist no 3-dimensional proper CR-submanifold in $S^{6}(1)$ satisfying Chen's basic equality under the condition that $\mathcal{D}$ is totally real.

## 2. The Nearly Kaehler Structure of $S^{6}(1)$

We give a brief explanation how the standard nearly Kaehler structure on $S^{6}(1)$ arises in a natural manner from Cayley multiplication. For elementary facts about Cayley numbers and their automorphism group $G_{2}$, we refer the reader to [14] and [17].

The multiplication on Cayley numbers $\vartheta$ may be used to define a vector cross product on purely imaginary Cayley numbers $\mathbb{R}^{7}$ by using the formula

$$
\begin{equation*}
u \times v=\frac{1}{2}(u v-v u), \tag{2.1}
\end{equation*}
$$

while the standard inner product on $\mathbb{R}^{7}$ is given by

$$
\begin{equation*}
\langle u, v\rangle=-\frac{1}{2}(u v+v u) \tag{2.2}
\end{equation*}
$$

It is elementary [12] to show that the triple scalar product $\langle u \times v, w\rangle$ is skew symmetric in $u, v, w$.

Let $J$ be the automorphism of the tangent bundle $T S^{6}$ of $S^{6}(1)$ defined by

$$
J u=x \times u, \quad u \in T_{x} S^{6}(1), \quad x \in S^{6}(1)
$$

It is clear that $J$ is an almost complex structure on $S^{6}(1)$ and $J$ is in fact a nearly Kaehler structure on $S^{6}(1)$ in the sense that $\left(\tilde{\nabla}_{u} J\right) u=0$, for any vector $u$ tangent to $S^{6}(1)$, where $\tilde{\nabla}$ denotes the metric connection of $S^{6}(1)$. We define the corresponding skew-symmetric (2,1)-tensor field $G$ by

$$
G(X, Y)=\left(\tilde{\nabla}_{X} J\right)(Y)
$$

We know from [16] that this tensor field satisfies the following property:

$$
\begin{equation*}
G(X, J Y)+J G(X, Y)=0 \tag{2.3}
\end{equation*}
$$

For further information on the properties of $G$, we refer to [6] and [16].

## 3. Proof of the Main Theorem

We need the following lemmas.
Lemma 3.1. Let $M$ be a CR-submanifold of a nearly Kaehler manifold $\tilde{M}$. Denote by $T^{\perp} M=J \mathcal{H}^{\perp} \oplus \nu$ the orthogonal decomposition of the normal bundle, where $\mathcal{H}^{\perp}$ is the totally real distribution and $\nu$ a complex subbundle of $T^{\perp} M$. Then the shape operator $A$ satisfies

$$
\begin{equation*}
\left\langle A_{\xi} J X, X\right\rangle=-\left\langle A_{J \xi} X, X\right\rangle \tag{3.1}
\end{equation*}
$$

for any vector field $X$ in the holomorphic distribution $\mathcal{H}$ and $\xi$ in $\nu$.
Proof. For any vector field $X$ in the holomorphic distribution $\mathcal{H}$, we have

$$
0=\left(\tilde{\nabla}_{X} J\right)(X)=\nabla_{X} J X+h(X, J X)-J\left(\nabla_{X} X\right)-J h(X, X)
$$

where $\nabla$ is the metric connection of $M$ with respect to the induced metric. Hence we obtain $\langle h(X, J X), \xi\rangle=\langle J h(X, X), \xi\rangle$ for any vector field $\xi \in \nu$.

Lemma 3.2. Let $M$ be a 3-dimensional proper minimal CR-submanifold in $S^{6}(1)$. If $M$ satisfies equality (1.2) and $\mathcal{D}$ is totally real, then $\mathcal{D}^{\perp}$ is integrable.

Proof. Since $\mathcal{D}^{\perp}$ is a complex plane $\left(i . e, \mathcal{D}^{\perp}=\mathcal{H}\right)$, we can choose an orthonormal frame field $\left\{E_{1}, E_{2}\right\}$ on $\mathcal{D}^{\perp}$ such that $J E_{1}=E_{2}$. By the minimality of $M$ and lemma
3.2 of [3], the second fundamental $h$ satisfies $h\left(E_{1}, J E_{2}\right)=h\left(J E_{1}, E_{2}\right)$. Moreover from (2.3) we have $G\left(E_{1}, E_{2}\right)=0$. Hence, by virtue of [1, page 26], $\mathcal{D}^{\perp}$ is integrable.

A submanifold is said to be linearlyfull in $S^{m}(1)$ if it does not lie in any totally geodesic submanifold of $S^{m}(1)$.

Lemma 3.3. Let $M$ be a 3-dimensional proper minimal $C R$-submanifold in $S^{6}(1)$. If $M$ satisfies equality (1.2) and $\mathcal{D}$ is totally real, then $M$ is linearly full in a totally geodesic $S^{5}(1)$.

Proof. Let $\left\{E_{1}, E_{2}, E_{3}\right\}$ be an orthonormal frame field on $M$ such that $\left\{E_{1}, E_{2}\right\} \in \mathcal{H}$, $E_{3} \in \mathcal{H}^{\perp}$ which diagonalize the shape operator $A_{J E_{3}}$. We may assume $J E_{1}=E_{2}$. For any $X \in T M$, we have

$$
\begin{equation*}
-A_{J E_{3}} X+\nabla_{X}^{\perp} J E_{3}=\tilde{\nabla}_{X} J E_{3}=\left(\tilde{\nabla}_{X} J\right)\left(E_{3}\right)+J \nabla_{X} E_{3}+J h\left(X, E_{3}\right) \tag{3.2}
\end{equation*}
$$

From (3.2) and lemma 3.2 of [3], we have

$$
\begin{equation*}
\nabla{\stackrel{\rightharpoonup}{E_{3}}}_{\perp}^{E_{3}}=J\left(\nabla_{E_{3}} E_{3}\right)=0 \tag{3.3}
\end{equation*}
$$

Further from (3.2) and lemma 3.2 of [3], we have

$$
\begin{equation*}
-A_{J E_{3}} E_{1}+\nabla_{E_{1}}^{\perp} J E_{3}=\left(\tilde{\nabla}_{E_{1}} J\right)\left(E_{3}\right)+J\left(\nabla_{E_{1}} E_{3}\right) \tag{3.4}
\end{equation*}
$$

Since $G$ is skew-symmetric, we find

$$
\begin{align*}
\left(\tilde{\nabla}_{E_{1}} J\right)\left(E_{3}\right) & =-\left(\tilde{\nabla}_{E_{3}} J\right)\left(E_{1}\right) \\
& =-\nabla_{E_{3}} E_{2}+J\left(\nabla_{E_{3}} E_{1}\right) \tag{3.5}
\end{align*}
$$

From (3.4) and (3.5), we obtain $\nabla \frac{\perp}{E_{1}} J E_{3} \in J \mathcal{H}^{\perp}$ which implies $\nabla \frac{E_{1}}{E_{1}} J E_{3}=0$ because $J \mathcal{H}^{\perp}$ is of rank one and $J E_{3}$ is of unit length. Similarly, we also have $\nabla_{E_{2}}^{\perp} J E_{3}=0$ Hence, $J E_{3}$ is a parallel normal vector field. Thus, from the equation of Ricci, we have $\left[A_{J E_{3}}, A_{\xi}\right]=0$.

If $A_{J E_{3}} \equiv 0$, the first normal space $\nu$ is parallel i.e. $\nabla^{\perp} \xi \in \nu, \xi \in \nu$ by the parallelism of $J E_{3}$. Therefore, by Erbacher's theorem [12], $M$ must be contained in a totally geodesic $S^{5}(1)$.

If $A_{J E_{3}} \not \equiv 0$, we put $V=\left\{p \in M: \operatorname{det} A_{J E_{3}} \neq 0\right\}$. In this case, the shape operators take the following form on $V$ :

$$
\begin{gather*}
A_{J E_{3}}=\left(\begin{array}{ccc}
a & 0 & 0 \\
0 & -a & 0 \\
0 & 0 & 0
\end{array}\right), \quad A_{\xi_{i}}=\left(\begin{array}{ccc}
h_{11}^{i} & 0 & 0 \\
0 & -h_{11}^{i} & 0 \\
0 & 0 & 0
\end{array}\right),  \tag{3.6}\\
\xi_{i} \in \nu, \quad i=1,2 .
\end{gather*}
$$

Combining (3.1) with (3.6) yields $A_{\xi_{1}}=A_{\xi_{2}}=0$ which imply that $V$ is contained in a totally geodesic $S^{4}(1)$, since $J E_{3}$ is a parallel normal vector field. Therefore, $\left.T S^{4}(1)\right|_{V}$ is spanned by $\left\{E_{1}, E_{2}, E_{3}, J E_{3}\right\}$. A result of Gray in [13] shows that this is impossible.

For a given orthonormal frame field $\left\{E_{1}, E_{2}, E_{3}\right\}$, define local functions $\gamma_{i j}^{k}$ by $\gamma_{i j}^{k}=$ $\left\langle\nabla_{E_{i}} E_{j}, E_{k}\right\rangle$.

Lemma 3.4. Let $M$ be a 3 -dimensional proper minimal $C R$-submanifold in $S^{6}(1)$. If $M$ satisfies equality (1.2) and $\mathcal{D}$ is totally real, then, with respect to some suitable orthonormal frame field $\left\{E_{1}, E_{2}, E_{3}\right\}$ on $M$, we have

$$
\begin{align*}
& \gamma_{33}^{1}=\gamma_{33}^{2}=0  \tag{3.7}\\
& \gamma_{11}^{3}=\gamma_{22}^{3}  \tag{3.8}\\
& \gamma_{12}^{3}=-\gamma_{21}^{3} \tag{3.9}
\end{align*}
$$

Proof. Let $\left\{E_{1}, E_{2}, E_{3}\right\}$ be an orthonormal frame field mentioned in lemma 3.3. From $A_{J E_{3}}=0$ and (3.1), we know that the second fundamental form satisfies

$$
\begin{aligned}
& h\left(E_{1}, E_{1}\right)=\phi \xi, \quad h\left(E_{2}, E_{2}\right)=-\phi \xi, \quad h\left(E_{3}, E_{3}\right)=0, \\
& h\left(E_{1}, E_{2}\right)=\phi J \xi, \quad h\left(E_{1}, E_{3}\right)=0, \quad h\left(E_{2}, E_{3}\right)=0
\end{aligned}
$$

where $\phi$ is a function and $\xi \in \nu$. Thus, from $(\nabla h)\left(E_{1}, E_{3}, E_{3}\right)=(\nabla h)\left(E_{3}, E_{1}, E_{3}\right)$, we obtain $\nabla_{E_{3}} E_{3}=0$. Also from $(\nabla h)\left(E_{3}, E_{1}, E_{1}\right)=(\nabla h)\left(E_{1}, E_{3}, E_{1}\right)$, we obtain (3.8). Finally from $(\nabla h)\left(E_{1}, E_{2}, E_{3}\right)=(\nabla h)\left(E_{2}, E_{1}, E_{3}\right)$, we obtain (3.9).

From lemma 3.2, we know that the distribution $\mathcal{D}^{\perp}$ locally spanned by $E_{1}$ and $E_{2}$ is an integrable distribution. Hence we get $\gamma_{12}^{3}=\gamma_{21}^{3}=0$.

Similarly as [6], we have the following lemmas using lemma 3.4.
Lemma 3.5. The local function $\gamma_{11}^{3}$ satisfies the following system of differential equations:

$$
E_{1}\left(\gamma_{11}^{3}\right)=0, \quad E_{2}\left(\gamma_{11}^{3}\right)=0
$$

Lemma 3.6. Under the hypothesis of Lemma 3.4. Then, on a neighborhood of a given point $p \in M, M$ is the warped product of an open interval $(-\epsilon, \epsilon)$ and $N^{2}, N^{2}$ the leaf of the distribution $\mathcal{D}^{\perp}$ through $p$.

From lemma 3.6 we may prove the following lemma.
Lemma 3.7. Let $M$ be a 3-dimensional minimal CR-submanifold in $S^{6}(1)$. If $M$ satisfies equality (1.2) and $\mathcal{D}$ is totally real, then $M$ is a totally real submanifold.

Proof. If $M$ is proper, we obtain from Lemma 3.6 that $M$ is locally a warped product and that the distribution on $M$ determined by the product structure coincide with $\mathcal{D}$ and $\mathcal{D}^{\perp}$. Moreover, since $h\left(\mathcal{D}, \mathcal{D}^{\perp}\right)=0$, locally $M$ is immersed as a warped product; furthermore, the first factor is totally geodesic, and therefore we can assume that the first factor of the corresponding warped product decomposition is 1-dimensional. Since the decomposition into a warped product with one-dimensional first factor is unique up to isometries, $M$ is thus immersed as follows [6]:

Let $S_{+}^{1}(1)=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2} \mid\|x\|=1\right.$ and $\left.x_{1}>0\right\}$ be a half circle, $S^{5}(1)$ the unit hypersphere of $\mathbb{R}^{6}$, and $N$ the unit vector orthogonal to the hyperplane containing $S^{5}(1)$. We parametrize the half circle $S_{+}^{1}(1)$ by $\left(-\frac{\pi}{2}, \frac{\pi}{2}\right) \rightarrow S_{+}^{1}(1), \quad t \mapsto(\cos (t), \sin (t))$. Let $f: M^{2} \rightarrow S^{5}(1)$ be a minimal immersion of a surface into $S^{5}(1)$. Then the associated warped product immersion is given by

$$
x:\left(-\frac{\pi}{2}, \frac{\pi}{2}\right) \times_{\cos (t)} M^{2} \rightarrow S^{6}(1), \quad(t, p) \mapsto \sin (t) N+\cos (t) f(p)
$$

Let $X$ be a vector field tangent to $M^{2}$. Then

$$
x_{*}\left(\frac{\partial}{\partial t}\right)=\cos (t) N-\sin (t) f(p), \quad x_{*}(X)=\cos (t) f_{*}(X)
$$

and

$$
J x_{*}\left(\frac{\partial}{\partial t}\right)=N \times f(p), \quad J x_{*}(X)=\cos (t) \sin (t) N \times f_{*}(X)+\cos ^{2}(t) J f_{*}(X)
$$

Since $\mathcal{D}=\operatorname{span}\left\{\frac{\partial}{\partial t}\right\}$ is totally real, we have

$$
\begin{equation*}
\left\langle N \times f(p), f_{*}(X)\right\rangle=0 \tag{3.10}
\end{equation*}
$$

Differentiating (3.10) yields

$$
\begin{equation*}
\left\langle N \times f_{*}(Y), f_{*}(X)\right\rangle+\langle N \times p, h(X, Y)\rangle=0 \tag{3.11}
\end{equation*}
$$

for any vector fields $X$ and $Y$ tangent to $M^{2}$. Because the first term in (3.11) is skew symmetric and the second is symmetric, both terms must vanish. Hence we obtain

$$
\left\langle N \times f_{*}(X), f_{*}(Y)\right\rangle=0
$$

which implies $\mathcal{D}^{\perp}$ is not a complex plane. This is a contradiction. Hence, $M$ must be nonproper.

Lemma 3.8. Let $M$ be a 3-dimensional nonminimal CR-submanifold in $S^{6}(1)$ which satisfies equality (1.2). If $\mathcal{D}$ is totally real, then $H \in J \mathcal{D}$.

Proof Let $\left\{E_{1}, E_{2}, E_{3}\right\}$ be an orthonormal frame field on $M$ such that $\left\{E_{1}, E_{2}\right\} \in \mathcal{H}$. Without loss of generality we may assume $J E_{1}=E_{2}$. Thus, (3.1) gives

$$
\left\langle A_{\xi} E_{1}, E_{1}\right\rangle+\left\langle A_{\xi} J E_{1}, J E_{1}\right\rangle=\left\langle A_{J \xi} J E_{1}, E_{1}\right\rangle-\left\langle A_{J \xi} E_{1}, J E_{1}\right\rangle=0
$$

for every vector field $\xi \in \nu$. Therefore, the mean curvature vector $H$ lies in $J \mathcal{D}$.
From lemma 3.8 we have the following.
Lemma 3.9. Let $M$ be a 3-dimensional nonminimal proper $C R$-submanifold in $S^{6}(1)$ which satisfies equality (1.2). Then $\mathcal{D}$ is not totally real.

Proof. If $\mathcal{D}$ is totally real, we have $H \in J \mathcal{D}$ from lemma 3.8. Without loss of generality we may assume $J E_{3}$ is parallel to the mean curvature vector. By (3.2), we obtain that $J E_{3}$ is a parallel normal vector field. Further, form the equation of Ricci we have $\left[A_{J E_{3}}, A_{\xi}\right]=0$ for any $\xi \in \nu$. By lemma 3.2 of [3], this implies that, with respect to a suitable orthonormal frame field with $E_{2}=J E_{1}$, the shape operators either take the form:

$$
A_{J E_{3}}=\left(\begin{array}{ccc}
a & 0 & 0  \tag{3.12}\\
0 & a & 0 \\
0 & 0 & 2 a
\end{array}\right), \quad A_{\xi_{i}}=\left(\begin{array}{ccc}
h_{11}^{i} & h_{12}^{i} & 0 \\
h_{12}^{i} & -h_{11}^{i} & 0 \\
0 & 0 & 0
\end{array}\right), \quad i=1,2
$$

or take the form:

$$
A_{J E_{3}}=\left(\begin{array}{ccc}
b & 0 & 0  \tag{3.13}\\
0 & c & 0 \\
0 & 0 & b+c
\end{array}\right), \quad A_{\xi_{i}}=\left(\begin{array}{ccc}
h_{11}^{i} & 0 & 0 \\
0 & -h_{11}^{i} & 0 \\
0 & 0 & 0
\end{array}\right), \quad i=1,2
$$

where $a, b, c$ are functions such that $b \neq c$ and $\xi_{i} \in \nu$.
If the shape operators take the form (3.13), then by combining (3.1) with (3.13), we obtain $A_{\xi_{1}}=A_{\xi_{2}}=0$. Since $J E_{3}$ is a parallel normal vector field, this implies that $M$ is contained in a totally geodesic $S^{4}(1)$. Since the tangent space of this sphere $S^{4}(1)$ is spanned by $\left\{E_{1}, E_{2}, E_{3}, J E_{3}\right\}, S^{4}(1)$ is an almost complex submanifold in $S^{6}(1)$ which is a contradiction. Hence the shape operators must take the form (3.12). Therefore, the second fundamental form satisfies

$$
\begin{align*}
& h\left(E_{1}, E_{1}\right)=a J E_{3}+\phi \xi, \quad h\left(E_{2}, E_{2}\right)=a J E_{3}-\phi \xi, \quad h\left(E_{3}, E_{3}\right)=2 a J E_{3} \\
& h\left(E_{1}, E_{3}\right)=0, \quad h\left(E_{1}, E_{2}\right)=\phi J \xi, \quad h\left(E_{2}, E_{3}\right)=0 \tag{3.14}
\end{align*}
$$

for some function $\phi$ and some $\xi \in \nu$. From (3.14) we find

$$
\begin{align*}
& (\nabla h)\left(E_{1}, E_{2}, E_{3}\right)=-\gamma_{12}^{3} a J E_{3}-\gamma_{13}^{1} \phi J \xi+\gamma_{13}^{2} \phi \xi,  \tag{3.15}\\
& (\nabla h)\left(E_{2}, E_{1}, E_{3}\right)=-\gamma_{21}^{3} a J E_{3}-\gamma_{23}^{2} \phi J \xi-\gamma_{23}^{1} \phi \xi . \tag{3.16}
\end{align*}
$$

If we put $W_{1}=\{p \in M: a(p) \neq 0\}$ and $W_{2}=\{q \in M: \phi(q) \neq 0\}$, then the equation of Codazzi, (3.15) and (3.16) yield

$$
\gamma_{12}^{3}=\gamma_{21}^{3}=0 \quad \text { on } \quad W_{1} \cap W_{2}
$$

which implies that $\mathcal{D}^{\perp}$ is integrable on $W_{1} \cap W_{2}$. Hence by virtue of [1, page 26], we conclude that $W_{1} \cap W_{2}$ is minimal, which is a contradiction. Hence, $\mathcal{D}$ cannot be totally real.

The main theorem follows from Lemma 3.7 and Lemma 3.9.

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