# PRIME NONASSOCIATIVE RINGS WITH SKEW DERIVATIONS 

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Abstract. Let $R$ be a prime nonassociative ring, $G$ the nucleus of $R$ and $s, t$ be automorphisms
of $R$.
(I) Suppose that $\delta$ is an $s$-derivation of $R$ such that $s \delta=\delta s$ and $\lambda$ is an $t$-derivation of $R$. If $\lambda \delta^{n}=0$ and $\delta^{n}(R) \subseteq G$, where $n$ is a fixed positive integer, then $\lambda=0$ or $\delta^{3 n-1}=0$.
(II) Assume that $\delta$ and $\lambda$ are derivations of $R$. If there exists a fixed positive integer $n$ such that $\lambda^{n} \delta=0$, and $\delta(R) \subseteq G$ or $\lambda^{n}(R) \subseteq G$, then $\delta^{2}=0$ or $\lambda^{6 n-4}=0$.

## 1. Introduction

Let $R$ be a nonassociative ring. We adopt the usual notation for commutators and associators: $[x, y]=x y-y x$ and $(x, y, z)=(x y) z-x(y z)$ for $x, y, z \in R$. We shall denote the nucleus of $R$ by $G$. Thus $G$ consists of all elements $n$ in $R$ such that $(n, R, R)=$ $(R, n, R)=(R, R, n)=0$. Denote the group of all automorphsisms of $R$ by Aut $(R)$. An additive mapping $\delta$ from $R$ into $R$ is called a skew derivation or an $s$-derivation if $\delta(x y)=\delta(x) y+s(x) \delta(y)$ for all $x, y$ in $R$, where $s \in A u t(R)$. If $s$ is the identity automorphism of $R$ then $\delta$ is called a derivation of $R$. Let $\operatorname{Der}(R)$ be the Lie ring of derivations of $R$. A ring $R$ is called prime if the product of any two nonzero ideals of $R$ is nonzero.

Posner [3] proved that if $R$ is a prime associative ring of characteristic not two with derivations $\lambda$ and $\delta$ then $\lambda \delta \in \operatorname{Der}(R)$ implies $\lambda=0$ or $\delta=0$. Jensen [2] partially extended this result. Two of his results are as follows: If $R$ is a prime associative ring with derivations $\lambda, \delta$ and there exists a fixed positive integer $n$ such that $\lambda \delta^{n}=0\left(\lambda^{n} \delta=0\right)$ then $\lambda=0$ or $\delta^{4 n-1}=0\left(\delta^{2}=0\right.$ or $\left.\lambda^{12 n-9}=0\right)$. In this paper, we improve and generalize these results to the prime nonassociative rings with skew derivations.

In every ring $R$ we have the Teichmüller identity

$$
\begin{equation*}
(\omega x, y, z)-(\omega, x y, z)+(\omega, x, y z)=\omega(x, y, z)+(\omega, x, y) z \quad \text { for all } \quad \omega, x, y, z \in R \tag{1}
\end{equation*}
$$

Note that the associator $(x, y, z)$ is linear in each argument. Thus using (1), we have that $G$ is an associative subring of $R$.

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## 2. Resulits

Our first main result is the following Theorem 1, which improves and generalizes Jensen's Theorem 1.

Theorem 1. [5] Let $R$ be a prime nonassociative ring and let $s, t \in A u t(R)$. Suppose that $\delta$ is an s-derivation of $R$ such that $s \delta=\delta s$ and $\lambda$ is an $t$-derivation of $R$. If $\lambda \delta^{n}=0$ and $\delta^{n}(R) \subseteq G$, where $n$ is a fixed positive integer, then $\lambda=0$ or $\delta^{3 n-1}=0$.

To prove Theorem 1 we need a Lemma. The proof of the Lemma is the same as that of [4, lemma 1], except that the equation (4) of [4] is replaced by

$$
\delta^{n}(x y)=\sum_{i=0}^{n} d^{i}\left(s^{n-i}(x)\right) d^{n-i}(y) \in A
$$

Lemma. Let $A$ be subring of $R$. If $\delta^{n}(R) \subseteq A$ then $R \delta^{3 n-1}(R) \subseteq A$. Proof of Theorem 1.

Let $\operatorname{ker}(\lambda)=\{c \in R: \lambda(c)=0\}$. Then $\operatorname{ker}(\lambda)$ is the subring of constants of $R$ under $\lambda$. The hypothesis $\lambda \delta^{n}=0$ implies $\delta^{n}(R) \subseteq \operatorname{ker}(\lambda)$. By the Lemma, we get $R \delta^{3 n-1}(R) \subseteq$ $\operatorname{ker}(\lambda)$. Since $\delta^{n}(R) \subseteq G$ and $s \delta=\delta s$, using [4, Theorem] we obtain that $R$ is associative or $\delta^{3 n-1}=0$. Assume that $\delta^{3 n-1} \neq 0$. Then $R$ is associative. Because of $R \delta^{3 n-1}(R) \subseteq$ $\operatorname{ker}(\lambda)$ and $\lambda \delta^{n}=0$, for all $x, y, z$ in $R$ we have

$$
0=\lambda\left(x \delta^{3 n-1}(y)\right)=\lambda(x) \delta^{3 n-1}(y)+t(x) \lambda\left(\delta^{3 n-1}(y)\right)=\lambda(x) \delta^{3 n-1}(y)
$$

and so $\lambda(z x) \delta^{3 n-1}(y)=0$. The last two equalities imply

$$
\begin{aligned}
0 & =(\lambda(z) x+t(z) \lambda(x)) \delta^{3 n-1}(y) \\
& =\lambda(z) x \delta^{3 n-1}(y)+t(z) \lambda(x) \delta^{3 n-1}(y) \\
& =\lambda(z) x \delta^{3 n-1}(y)
\end{aligned}
$$

By the primeness of $R$, this implies $\lambda(z)=0$ or $\delta^{3 n-1}(y)=0$. In view of $\delta^{3 n-1} \neq 0$, we obtain $\lambda(z)=0$ for all $z$ in $R$. Thus $\lambda=0$, as desired.

Our second main result is the following Theorem 2, which improves and generalizes Jensen's Theorem 2.

Theorem 2. Let $R$ be a prime nonassociative ring and let $\delta$ and $\lambda$ be derivations $\lambda^{n}(R) \subseteq G$, then $\delta^{2}=0$ or $\lambda^{6 n-4}=0$.

Proof. The derivations of $R$ form a Lie ring under commutation. Therefore $[\delta, \lambda]=$ $\delta \lambda-\lambda \delta$ is a derivation, $[\delta \lambda-\lambda \delta, \lambda]=\delta \lambda^{2}-2 \lambda \delta \lambda+\lambda^{2} \delta$ is a derivation, and $\left[\delta \lambda^{2}-2 \lambda \delta \lambda+\right.$
$\left.\lambda^{2} \delta, \lambda\right]=\delta \lambda^{3}-3 \lambda \delta \lambda^{2}+3 \lambda^{2} \delta \lambda-\lambda^{3} \delta$ is also a derivation. Continuing we may conclude that

$$
\sum_{i=0}^{2 n-1}\binom{2 n-1}{i}(-1)^{i} \lambda^{i} \delta \lambda^{2 n-1-i}
$$

is a derivation. The coefficients are not germane to the rest of the proof, so we suppress them from here on out. Thus, using $\lambda^{n} \delta=0$ we have that

$$
\begin{equation*}
\delta \lambda^{2 n-1}+\lambda \delta \lambda^{2 n-2}+\cdots+\lambda^{n-1} \delta \lambda^{n} \text { is a derivation of } R \tag{2}
\end{equation*}
$$

Since $\delta(R) \subseteq G$ or $\lambda^{n}(R) \subseteq G$, applying [4, Theorem] we obtain that $R$ is associative, or $\delta^{2}=0$ or $\lambda^{3 n-1}=0$. If $\delta^{2}=0$ or $\lambda^{3 n-1}=0$, then we are done.

Suppose that $\delta^{2} \neq 0$ and $\lambda^{3 n-1} \neq 0$. Then $R$ is associative. Because of $\lambda^{n} \delta=0$, we get $\left(\delta \lambda^{2 n-1}+\lambda \delta \lambda^{2 n-1}+\cdots+\lambda^{n-1} \delta \lambda^{n}\right) \delta=0$. In view of $\delta^{2} \neq 0$, by (2) and Theorem 1 the last equality implies

$$
\begin{equation*}
\delta \lambda^{2 n-1}+\lambda \delta \lambda^{2 n-2}+\cdots+\lambda^{n-1} \delta \lambda^{n}=0 \tag{3}
\end{equation*}
$$

Premultiplying (3) by $\lambda^{n-1}$ and applying $\lambda^{n} \delta=0$, we obtain

$$
\begin{equation*}
\lambda^{n-1} \delta \lambda^{2 n-1}=0 \tag{4}
\end{equation*}
$$

Using (4) and premultiplying (3) by $\lambda^{n-2}$, it follows that $\lambda^{n-2} \delta \lambda^{2 n-1}+\lambda^{n-1} \delta \lambda^{2 n-2}=0$. Hence, we have $0=\left(\lambda^{n-2} \delta \lambda^{2 n-1}+\lambda^{n-1} \delta \lambda^{2 n-2}\right) \lambda$ and so by (4)

$$
\begin{equation*}
\lambda^{n-2} \delta \lambda^{2 n}=0 \tag{5}
\end{equation*}
$$

As the proof of [2, Theorem 2], we obtain $\lambda^{n-3} \delta \lambda^{2 n+1}=\lambda^{n-4} \delta \lambda^{2 n+2}=\cdots=\delta \lambda^{3 n-2}=0$. Combining (4) with (5) yields

$$
\begin{equation*}
\lambda^{n-2}[\delta, \lambda] \lambda^{2 n-1}=0 \tag{6}
\end{equation*}
$$

Since $\lambda^{n} \delta=0$, we get $\lambda^{n}[\delta, \lambda]=0$. Thus, replacing $\delta$ by $[\delta, \lambda]$ and comparing (4), (5) and (6), and as the last proof we have

$$
\begin{equation*}
\lambda^{n-3}[[\delta, \lambda], \lambda] \lambda^{2 n-1}=0 \tag{7}
\end{equation*}
$$

Continuing in this manner, we finally obtain

$$
\begin{equation*}
\mu \lambda^{2 n-1}=0, \text { where } \mu=[[\cdots[[\delta, \lambda], \lambda], \cdots], \lambda] \tag{8}
\end{equation*}
$$

Because of $\mu$ is a derivation of $R$, by (8) and Theorem 1, we get $\mu=0$ or $\lambda^{6 n-4}=$ $\lambda^{3(2 n-1)-1}=0$. If $\lambda^{6 n-4}=0$, then we are done. Assume that $\mu=0$. Thus, as the beginning of the proof, we may suppose that

$$
\begin{equation*}
\nu=\delta \lambda^{n-1}+\lambda \delta \lambda^{n-2}+\cdots+\lambda^{n-1} \delta=0 \tag{9}
\end{equation*}
$$

Using (9) repeatedly and $\lambda^{n} \delta=0$, we have $0=\lambda^{n-1} \nu=\lambda^{n-1} \delta \lambda^{n-1}, 0=\lambda^{n-2} \nu \lambda=$ $\lambda^{n-2} \delta \lambda^{n}, \ldots$, and finally we obtain

$$
\begin{equation*}
\delta \lambda^{2 n-1}=0 \tag{10}
\end{equation*}
$$

By Theorem 1 and $\delta \neq 0$, (10) implies $\lambda^{6 n-4}=\lambda^{3(2 n-1)-1}=0$, as desired.
Chung and Luh [1] showed that in a prime associative ring with characteristic 2 , the nilpotency of nilpotent derivation must be of the form $2^{k}$, where $k \in \mathbb{N}$. Therefore, when $R$ is not 2 -torsion free, the possible values for nilpotency in Theorem 1 and Theorem 2 are further limited. For example, if we assume in Theorem 1 or Theorem 2 that the characteristic of $R$ is $2, \delta \lambda^{21}=0$ and $\delta \neq 0$, or $\lambda^{11} \delta=0$ and $\delta^{2} \neq 0$, then the nilpotency of $\lambda$ must be $1,2,4,8,16$, or 32 .

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