



# The Split feasibility problems with multiple output sets in real Banach spaces

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**Abstract.** This paper aims to present a new iterative method for solving the split feasibility problem with multiple output sets for generalized demimetric mappings and solution sets of a generalized equilibrium problem in the real Banach spaces. The strong convergence of the sequence generated by our method is proven under certain conditions. We also give a numerical example to support our main result. The results of this paper extend and improve some recent corresponding results announced by many other authors.

**Keywords.** Split feasibility problem with multiple output set, generalized demimetric mappings, fixed point problem, generalized equilibrium problem

## 1 Introduction

Suppose that  $C$  is a closed and convex subset of a real Banach space  $E$ , and let  $E^*$  denote its dual space. Consider two bifunctions  $f : C \times C \rightarrow \mathbb{R}$  and  $\phi : C \times C \rightarrow \mathbb{R}$ , and a nonlinear mapping  $B : C \rightarrow 2^{E^*}$ . We focus on the generalized equilibrium problem (GEP), which consists of finding a point  $u \in C$  such that

$$f(u, y) + \langle x^*, y - u \rangle + \phi(u, y) - \phi(u, u) \geq 0, \quad \forall y \in C, \forall x^* \in Bu. \quad (1.1)$$

The solution set of (1.1) is denoted by  $GEP(f, B, \phi)$ . If  $\phi \equiv 0$ , problem (1.1) reduces to finding  $u \in C$  such that

$$f(u, y) + \langle x^*, y - u \rangle \geq 0, \quad \forall y \in C, \forall x^* \in Bu, \quad (1.2)$$

whose solution set is written as  $GEP(f, B)$ . When  $f \equiv 0$  and  $\phi \equiv 0$ , problem (1.1) becomes the problem of finding  $u \in C$  such that

$$\langle x^*, y - u \rangle \geq 0, \quad \forall y \in C, \forall x^* \in Bu,$$

which was introduced by Hartman and Stampacchia [10].

Suppose  $C$  and  $Q$  are nonempty, closed, and convex subsets of real Banach spaces  $E_1$  and  $E_2$ , respectively, and let  $E_1^*$  and  $E_2^*$  denote their dual spaces. Let  $A : E_1 \rightarrow E_2$  be a bounded linear operator. The split feasibility problem (SFP) [6] consists of finding a point

$$x^* \in C \text{ such that } Ax^* \in Q. \quad (1.3)$$

To solve the SFP, Schöphér et al. [23] proposed the following algorithm in the setting of  $p$ -uniformly convex and uniformly smooth real Banach spaces: for  $x_1 \in E_1$ , define

$$x_{n+1} = \Pi_C J_{E_1^*}^q [J_{E_1}^p x_n - \gamma_n A^* J_{E_2}^p (Ax_n - P_Q(x_n))], \quad n \geq 1, \quad (1.4)$$

where  $\Pi_C$  denotes the Bregman projection of  $E_1$  onto  $C$ , and  $J_E^p$  represents the duality mapping. Under the assumption that  $E_1$  is  $p$ -uniformly convex, uniformly smooth, and the duality mapping of  $E_1$  is sequentially weak-to-weak continuous, the authors showed that algorithm (1.4) converges weakly. Given two nonlinear mappings  $T : E_1 \rightarrow E_1$  and  $S : E_2 \rightarrow E_2$ , and a nonzero bounded linear operator  $A : E_1 \rightarrow E_2$ , the split common fixed point problem (SCFP) [8] is formulated as follows:

$$\text{Find } x^* \in F(S) \text{ such that } Ax^* \in F(T). \quad (1.5)$$

We denote by  $\Omega$  the solution set of this SCFP for the mappings  $T$  and  $S$ ; That is,  $\Omega = \{x^* \in F(S) : Ax^* \in F(T)\}$ .

In the literature, there are several extensions and generalizations of the SFP, and one notable example is the split feasibility problem with multiple output sets (SFP MOS) [20, 21, 22], which is defined as follows:

$$\text{Find } x^* \in \Omega = C \cap \left( \bigcap_{i=1}^N A_i^{-1}(Q_i) \right), \quad (1.6)$$

where for each  $i = 1, 2, \dots, N$ ,  $Q_i$  is a closed and convex subset of a real Hilbert space  $H_i$ , and  $A_i : H \rightarrow H_i$  is a bounded linear operator. Recently, Wang [26] studied the following generalization of SFP MOS in a Hilbert space:

$$\text{Find } x^* \in \Omega = F(T_0) \cap \left( \bigcap_{i=1}^N A_i^{-1}(F(T_i)) \right), \quad (1.7)$$

where, for each  $i = 0, 1, \dots, N$ ,  $T_i$  is a nonlinear mapping from  $H_i$  into itself. To solve problem (1.7), Wang [26] introduced a new iterative method and established its weak and strong convergence under suitable conditions.

Consider a Banach space  $E$  with a subset  $C \subseteq E$ . A nonlinear mapping  $B : C \rightarrow 2^{E^*}$  is said to be:

- (i) Monotone, if  $\langle x - y, x^* - y^* \rangle \geq 0$ ,  $\forall x, y \in C$ ,  $\forall x^* \in Bx$ ,  $\forall y^* \in By$ .
- (ii)  $\alpha$ -inverse strongly monotone if there exists a constant  $\alpha > 0$  such that

$$\langle x - y, x^* - y^* \rangle \geq \alpha \|x^* - y^*\|^2, \quad \forall x^* \in Bx, \quad \forall y^* \in By.$$

Motivated by the aforementioned research, this paper focuses on the following problem within the framework of  $p$ -uniformly convex Banach spaces:

$$\text{Find } x^* \in \Omega = GEP(B, f, \phi) \cap \Gamma, \quad (1.8)$$

where  $\Gamma$  is the solution set of the following generalization SFP MOS: Find  $x^*$  so that

$$x^* \in \bigcap_{j=1}^M F(S_j) \text{ and } x^* \in \bigcap_{i=1}^N A_i^{-1}(F(T_i)), \quad (1.9)$$

with the following specifications:

- For each  $i = 1, 2, \dots, N$ ,  $T_i : E_i \rightarrow E_i$  is a finite family of  $\xi_i$ -generalized demimetric mappings;
- For each  $j = 1, 2, \dots, M$ ,  $S_j : E \rightarrow E$  is a finite family of  $\mu_j$ -generalized demimetric mappings;
- $B : C \rightarrow E^*$  is an  $\alpha$ -inverse strongly monotone mapping.

We propose a self-adaptive algorithm to solve problem (1.8) and establish the strong convergence of the generated sequences under appropriate conditions on the parameters.

## 2 Preliminaries

Let  $E$  be a real Banach space and let  $E^*$  be its dual. We denote the value of  $y^* \in E^*$  at  $x \in E$  by  $\langle x, y^* \rangle$ . We will show the strong convergence of  $\{x_n\}$  to  $x$  by  $x_n \rightarrow x$  and the weak convergence by  $x_n \rightharpoonup x$ .

Let  $1 < q \leq 2 \leq p$  and  $\frac{1}{p} + \frac{1}{q} = 1$ . A Banach space  $E$  is said to be strictly convex if  $\frac{\|x+y\|}{2} < 1$  for all  $x, y \in U_E = \{x \in E : \|x\| = 1\}$  with  $x \neq y$ . The modulus of convexity, denoted as  $\delta$ , is defined for a Banach space  $E$  by:

$$\delta_E(\epsilon) = \inf\left\{1 - \frac{\|x+y\|}{2} : \|x\| \leq 1, \|y\| \leq 1, \|x-y\| \geq \epsilon\right\},$$

for every  $\epsilon \in (0, 2]$ .

A Banach space  $E$  is said to be uniformly convex if  $\delta_E(\epsilon) > 0$  for every  $\epsilon > 0$ , and  $p$ -uniformly convex if there is a  $c_p > 0$  so that  $\delta_E(\epsilon) \geq c_p \epsilon^p$  for any  $\epsilon \in (0, 2]$ . The modulus of smoothness  $\rho_E : [0, \infty) \rightarrow [0, \infty)$  is defined by

$$\rho_E(\tau) = \sup\left\{\frac{\|x+\tau y\| + \|x-\tau y\|}{2} - 1; \|x\| = \|y\| = 1\right\}.$$

A Banach space  $E$  is called uniformly smooth if  $\lim_{\tau \rightarrow 0} \frac{\rho_E(\tau)}{\tau} = 0$ , and  $E$  is called  $q$ -uniformly smooth if there exists a  $c_q > 0$  so that  $\rho_E(\tau) \leq c_q \tau^q$  for all  $\tau > 0$ . It is known that every  $p$ -uniformly convex space is also a uniformly convex space. Moreover, a Banach space  $E$  is  $p$ -uniformly convex if and only if its dual space  $E^*$  is  $q$ -uniformly smooth [2]. For instance,  $L_p$  spaces are  $\min\{p, 2\}$ -uniformly smooth for each  $p > 1$ . Further details can be found in [27].

For  $p > 1$ , the definition of the generalized duality mapping  $J_E^p : E \rightarrow 2^{E^*}$  is given by

$$J_E^p(x) = \{x^* \in E^* : \langle x, x^* \rangle = \|x\|^p, \|x^*\| = \|x\|^{p-1}\}, \quad \forall x \in E.$$

In particular,  $J_E^2 = J$  is called the normalized duality mapping. In this case, we assume that  $E$  is a  $p$ -uniformly convex and uniformly smooth, which implies that its dual space  $E^*$  is  $q$ -uniformly smooth and uniformly convex. In this setting, the duality mapping  $J_E^p$  is one-to-one, single-valued and satisfies  $J_E^p = (J_{E^*}^q)^{-1}$  where  $J_{E^*}^q$  is the generalized duality mapping of  $E^*$  (see [2]).

**Lemma 2.1.** [27] *A uniformly smooth Banach space  $E$  has a modulus of smoothness of power type  $q > 1$  if and only if there exists a constant  $C_q > 0$  such that*

$$\|x-y\|^q \leq \|x\|^q - q\langle y, J_E^q x \rangle + C_q \|y\|^q,$$

for all  $x, y \in E$ .

**Lemma 2.2.** [27] *Let  $p > 1$  and  $r > 0$  be two fixed real numbers, and let  $E$  be a Banach space. Then  $E$  is uniformly convex if and only if there exists a continuous, strictly increasing and convex function  $g : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ ,  $g(0) = 0$  such that for all  $x, y \in B_r = \{x \in E : \|x\| \leq r\}$  and  $0 \leq \alpha \leq 1$ ,*

$$\|\alpha x + (1 - \alpha)y\|^p \leq \alpha\|x\|^p + (1 - \alpha)\|y\|^p - W_p(\alpha)g(\|x - y\|),$$

where  $W_p(\alpha) := \alpha^p(1 - \alpha) + \alpha(1 - \alpha)^p$ .

Let  $1 < p, q < \infty$  be two real numbers such that  $\frac{1}{p} + \frac{1}{q} = 1$ . Let  $f_p : E \rightarrow \mathbb{R}$  be a function given by  $f_p(x) = \frac{1}{p}\|x\|^p$ . The Bregman distance with respect to  $f_p$  is defined as follows:

$$\Delta_p(x, y) = \frac{1}{q}\|x\|^p - \langle J_E^p x, y \rangle + \frac{1}{p}\|y\|^p, \quad \forall x, y \in E. \quad (2.1)$$

In the case of Hilbert spaces, where the duality mapping  $J$  is the identity operator, we have  $\Delta_2(x, y) = \|x - y\|^2$ .

According to [3, 7], we utilize the function  $V_p : E \times E^* \rightarrow [0, \infty)$  associated with  $f_p$ , which is defined as follows:

$$V_p(x, \tilde{x}) = \Delta_p(x, J_{E^*}^q(\tilde{x})), \quad (2.2)$$

for all  $x \in E$  and  $\tilde{x} \in E^*$ . In addition, using the subdifferential inequality, we have

$$V_p(x, \tilde{x}) + \langle (J_{E^*}^q)(\tilde{x}) - x, \tilde{y} \rangle \leq V_p(x, \tilde{x} + \tilde{y}), \quad (2.3)$$

for all  $x \in E$  and  $\tilde{x}, \tilde{y} \in E^*$  [14]. In addition, the function  $V_p$  is convex in the second variable. Thus, for all  $z \in E$ ,

$$\Delta_p(z, J_{E^*}^q(\sum_{i=1}^N t_i J_E^p(x_i))) \leq \sum_{i=1}^N t_i \Delta_p(z, x_i), \quad (2.4)$$

where  $\{x_i\}_{i=1}^N \subset E$ , and  $\{t_i\}_{i=1}^N \subset (0, 1)$  with  $\sum_{i=1}^N t_i = 1$ .

**Lemma 2.3.** [19] *Let  $E$  be a uniformly convex and uniformly smooth Banach space. If  $x_1 \in E$  and the sequence  $\{\Delta_p(x_n, x_1)\}$  is bounded, then the sequence  $\{x_n\}$  is bounded.*

**Lemma 2.4.** [11] *Let  $E$  be a uniformly convex and smooth Banach space and let  $\{y_n\}, \{z_n\}$  be two sequences of  $E$ . If  $\Delta_p(y_n, z_n) \rightarrow 0$  and either  $\{y_n\}$  or  $\{z_n\}$  is bounded, then  $y_n - z_n \rightarrow 0$ .*

**Lemma 2.5.** [23] *Let  $E$  be a  $p$ -uniformly convex Banach space. Then for  $x, y \in E$ , there exists a fixed constant  $\tau_p > 0$  such that*

$$\tau_p \|x - y\|^p \leq \Delta_p(x, y) \leq \langle x - y, J_E^p x - J_E^p y \rangle.$$

Let  $C$  be a nonempty, closed, and convex subset of  $E$ . The metric projection

$$P_C x := \arg \min_{y \in C} \|x - y\|, \quad x \in E,$$

is the unique minimizer of the norm distance, which can be characterized by a variational inequality:

$$\langle J_E^p(x - P_C x), z - P_C x \rangle \leq 0, \quad \forall z \in C.$$

The Bregman projection, introduced by Bregman [5], is a mapping  $\Pi_C$  from  $E$  onto  $C$  is defined by

$$\Delta_p(\Pi_C(x), x) = \min_{y \in C} \Delta_p(y, x).$$

In Hilbert spaces, the Bregman projection  $\Pi_C$  reduces to the metric projection.

For any  $x \in E$ , then Bregman projections can be characterized by a variational inequality [19]:

$$\langle y - \Pi_C x, J_E^p x - J_E^p(\Pi_C x) \rangle \leq 0, \quad \forall y \in C. \quad (2.5)$$

Moreover, this variational inequality is equivalent to the following inequality

$$\Delta_p(y, \Pi_C x) + \Delta_p(\Pi_C x, x) \leq \Delta_p(y, x), \quad \forall y \in C.$$

Let  $E$  be a smooth Banach space and let  $\eta$  be a real number with  $\eta \in (-\infty, 1)$ . A mapping  $U : E \rightarrow E$  with  $F(U) \neq \emptyset$  is called  $\eta$ -demimetric [25] if, for any  $x \in E$  and  $p \in F(U)$ ,

$$\langle x - p, J_E(x - Ux) \rangle \geq \frac{1 - \eta}{2} \|x - Ux\|^2$$

where  $J_E$  is the duality mapping on  $E$ . We have from [25] that  $F(U)$  is nonempty, closed, and convex.

Recently, Kawasaki and Takahashi [12] generalized the concept of demimetric mappings as follows: Let  $E$  be a smooth, strictly convex, and reflexive Banach space. Let  $\xi$  be a real number with  $\xi \neq 0$ . A mapping  $U : C \rightarrow E$  with  $F(U) \neq \emptyset$  is called  $\xi$ -generalized demimetric if the following inequality holds:

$$\xi \langle x - q, J_E(x - Ux) \rangle \geq \|x - Ux\|^2,$$

for all  $x \in C$  and  $q \in F(U)$ .

Let  $E$  be a  $p$ -uniformly convex and uniformly smooth Banach space. Shahzad et al., [24] introduced the following modifications of demimetric mappings: A mapping  $U : E \rightarrow E$  with  $F(U) \neq \emptyset$  is called  $\eta$ -demimetric if, for any  $x \in E$  and  $p \in F(U)$ ,

$$\langle x - p, J_E^p(x - Ux) \rangle \geq \frac{1 - \eta}{2} \|x - Ux\|^p$$

In this paper, we adopt the following concept of demimetric mappings in a  $p$ -uniformly convex Banach:

Let  $E$  be a  $p$ -uniformly convex and uniformly smooth, and let  $\xi \neq 0$  be a real number. A mapping  $U : E \rightarrow E$  with  $F(U) \neq \emptyset$  is called  $\xi$ -generalized demimetric if the following inequality holds:

$$\xi \langle x - q, J_E^p(x - Ux) \rangle \geq \|x - Ux\|^p,$$

for all  $x \in C$  and  $q \in F(U)$  (see [9]).

**Example 1.** Let  $E$  be a  $p$ -uniformly convex Banach space which is uniformly smooth and  $B$  be a maximal monotone mapping with  $B^{-1}(0) \neq \emptyset$ . Then, for any  $\lambda > 0$ , the metric resolvent  $J_\lambda = (J_E + \lambda B)^{-1} J_E$  is a 1-generalized demimetric mapping [25].

**Example 2.** Let  $E$  be a  $p$ -uniformly convex Banach space and uniformly smooth and let  $C$  be a nonempty, closed and convex subset of  $E$ . Then,  $P_C$  is a 1-generalized demimetric mapping.

**Lemma 2.6.** [18] Let  $\{\Gamma_n\}$  be a sequence of real numbers that does not decrease at infinity, in the sense that there exists a subsequence  $\{\Gamma_{n_k}\}_{k \geq 0}$  of  $\{\Gamma_n\}$  which satisfies  $\Gamma_{n_k} \leq \Gamma_{n_k+1}$  for all  $k \geq 0$ . Also, consider a sequence of integers  $\{\tau(n)\}_{n \geq n_0}$  defined by

$$\tau(n) := \max\{k \leq n \mid \Gamma_{n_k} \leq \Gamma_{n_k+1}\}.$$

Then  $\{\tau(n)\}_{n \geq n_0}$  is a nondecreasing sequence satisfying  $\lim_{n \rightarrow \infty} \tau(n) = \infty$ . Moreover, if  $\Gamma_{\tau(n)} \leq \Gamma_{\tau(n)+1}$  for all  $n \geq n_0$ , then we have

$$\Gamma_{\tau(n)} \leq \Gamma_{\tau(n)+1}$$

**Lemma 2.7.** [17] Let  $\{a_n\}$ ,  $\{b_n\}$ , and  $\{c_n\}$ , be sequences of nonnegative real numbers satisfying

$$a_{n+1} \leq (1 - \delta_n)a_n + b_n + c_n, \quad \forall n \geq 0,$$

where  $\{\delta_n\}$  is a sequence in  $(0, 1)$ . Assume that  $\sum_{n=1}^{\infty} c_n < \infty$ . Then the following results hold:

(a) If there exists  $M > 0$  such that  $\frac{b_n}{\delta_n} < M$  for all  $n$ , then  $\{a_n\}$  is bounded.

(b) If  $\sum_{n=1}^{\infty} \delta_n = \infty$  and  $\limsup_{n \rightarrow \infty} \frac{b_n}{\delta_n} < \infty$ , then  $\lim_{n \rightarrow \infty} a_n = 0$ .

Suppose that the bifunction  $f : C \times C \rightarrow \mathbb{R}$  satisfies the following assumptions:

- (i)  $f(x, x) = 0$ , for all  $x \in C$ ;
- (ii)  $f$  is monotone, i.e.,  $f(x, y) + f(y, x) \leq 0$ , for all  $x, y \in C$ ;
- (iii)  $\limsup_{t \rightarrow 0} f(tz + (1-t)x, y) \leq f(x, y)$ , for all  $x, y, z \in C$ ;
- (iv) For each  $x \in C$ ,  $y \rightarrow f(x, y)$  is convex and lower semicontinuous. Let  $\phi : C \times C \rightarrow \mathbb{R}$  be a bifunction satisfying the following assumptions:
  - (i)  $\phi$  is skew-symmetric, i.e.,  $\phi(x, x) - \phi(x, y) - \phi(y, x) + \phi(y, y) \geq 0$ , for all  $x, y \in C$ ;
  - (ii)  $\phi$  is convex in the second argument;
  - (iii)  $\phi$  is continuous.

**Lemma 2.8.** Let  $C$  be a nonempty, closed, and convex subset of a real reflexive Banach space  $E$ . Let  $f : C \times C \rightarrow \mathbb{R}$  satisfy Assumption 2 and  $\phi : C \times C \rightarrow \mathbb{R}$  satisfy Assumption 2. Assume that  $B : C \rightarrow E^*$  is an  $\alpha$ -inverse-strongly monotone mapping. Define the resolvent  $K^{f, \phi}$  associated with  $f$  and  $\phi$  by

$$K^{f, \phi}(x) = \{z \in C : f(z, y) + \langle Bz, y - z \rangle + \langle y - z, J_E^p z - J_E^p x \rangle + \phi(z, y) - \phi(z, z) \geq 0\},$$

for all  $x \in E$ . Then, the following properties hold:

- (a)  $K^{f, \phi}$  is single-valued.
- (b)  $K^{f, \phi}$  is a Bregman firmly nonexpansive type mapping, i.e., for all  $x, y \in E$ ,

$$\langle K^{f, \phi} x - K^{f, \phi} y, J_E^p(K^{f, \phi} x) - J_E^p(K^{f, \phi} y) \rangle \leq \langle K^{f, \phi} x - K^{f, \phi} y, J_E^p(x) - J_E^p(y) \rangle.$$

- (c)  $F(K^{f, \phi}) = GEP(f, B, \phi)$  is closed and convex;
- (d)  $\Delta_p(q, K^{f, \phi} x) + \Delta_p(K^{f, \phi} x, x) \leq \Delta_p(q, x)$ , for all  $q \in F(K^{f, \phi})$ , and  $x \in E$ ;
- (e)  $K^{f, \phi}$  is Bregman quasi-nonexpansive.

*Proof.* Define a bifunction  $F : C \times C \rightarrow \mathbb{R}$  by

$$F(x, y) = f(x, y) + \langle Bx, y - x \rangle, \quad \forall x, y \in C.$$

It is straightforward to verify that  $F$  satisfies Assumption 2. Therefore, the results can be deduced immediately from Lemma 2.2 in [13].  $\square$

### 3 Main result

In this section, we propose a self-adaptive algorithm to solve the SFP MOS in Banach spaces and establish a strong convergence theorem for the sequences generated by the proposed method.

- (i) Let  $E$  and  $E_i$  ( $i = 0, 1, 2, \dots, N$ ), be  $p$ -uniformly convex and uniformly smooth Banach and let  $C$  and  $C_i$  be nonempty, closed, and convex subsets of  $E$  and  $E_i$  respectively.
- (ii) Let  $A_i : E \rightarrow E_i$ ,  $i = 1, 2, \dots, N$  be nonzero bounded linear operators and  $A_i^*$  be the adjoint of  $A_i$ .
- (iii) For each  $j \in \{1, 2, \dots, M\}$  with  $\mu_j \neq 0$ , let  $S_j : C \rightarrow C$  be a finite family of  $\mu_j$ -generalized demimetric and demiclosed mappings. Similarly, for each  $i \in \{1, 2, \dots, N\}$  with  $\xi_i \neq 0$ , let  $T_i : C_i \rightarrow C_i$  be a finite family of  $\xi_i$ -generalized demimetric and demiclosed mappings.
- (iv) Let  $f : C \times C \rightarrow \mathbb{R}$  and  $\phi : C \times C \rightarrow \mathbb{R}$  be bifunctions satisfying Assumptions 2 and 2 respectively, and let  $B : C \rightarrow E^*$  be an  $\alpha$ -inverse-strongly monotone mapping.
- (v)  $\Omega = \Gamma \cap GEP(B, f, \phi) \neq \emptyset$ , where  $\Gamma$  is the solution set of the split common fixed point problem.

**Theorem 3.1.** *Let  $\{v_n\}$  be a sequence in  $C$  such that  $v_n \rightarrow v$ . For a given  $x_1 \in C$ , let  $\{x_n\}$  be a sequence generated by the following iterative algorithm:*

$$\begin{cases} u_n \in C \text{ s.t. } f(u_n, y) + \langle Bu_n, y - u_n \rangle + \langle y - u_n, J_E^p u_n - J_E^p x_n \rangle \\ \quad + \phi(u_n, y) - \phi(u_n, u_n) \geq 0, \quad \forall y \in C, \\ y_n = \Pi_C J_{E^*}^q \left[ \sum_{j=1}^M b_{n,j} (J_E^p u_n - \sigma_{n,j} r_j J_E^p (u_n - S_j u_n)) \right], \\ z_n = \Pi_C J_{E^*}^q \left[ \sum_{i=1}^N a_{n,i} (J_E^p y_n - \tau_{n,i} l_i A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)) \right], \\ x_{n+1} = \Pi_C J_{E^*}^q [\beta_n J_E^p x_n + (1 - \beta_n)(\alpha_n J_E^p v_n + (1 - \alpha_n) J_E^p z_n)], \end{cases} \quad (3.1)$$

where  $l_i = \frac{\xi_i}{|\xi_i|}$ ,  $r_j = \frac{\mu_j}{|\mu_j|}$ , and the stepsizes are chosen as follows:

$$\tau_{n,i} = \frac{\rho_{n,i} \|A_i y_n - T_i A_i y_n\|^{p(p-1)}}{\bar{\tau}_{n,i}^p}, \text{ for } i = 1, 2, \dots, N,$$

with

$$\bar{\tau}_{n,i} := \max\{\|A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)\|, \gamma\}$$

where  $\gamma > 0$ ,  $\{\rho_{n,i}\} \subset (0, (\frac{q}{|\xi_i| C_q})^{\frac{1}{q-1}})$ , and  $\{\sigma_{n,j}\} \subset (0, (\frac{q}{|\mu_j| C_q})^{\frac{1}{q-1}})$ . Let the sequences  $\{\alpha_n\}$ ,  $\{\beta_n\}$ ,  $\{a_{n,i}\}$ , and  $\{b_{n,j}\}$  satisfy the following conditions:

- (i)  $\{\alpha_n\} \subseteq (0, 1)$ ,  $\lim_{n \rightarrow \infty} \alpha_n = 0$ , and  $\sum_{n=1}^{\infty} \alpha_n = \infty$ .
- (ii)  $\lim_{n \rightarrow \infty} a_{n,i} \rho_{n,i} (\frac{1}{|\xi_i|} - \frac{C_q \rho_{n,i}^{q-1}}{q}) > 0$ , and  $\lim_{n \rightarrow \infty} b_{n,j} \sigma_{n,j} (\frac{1}{|\mu_j|} - \frac{C_q \sigma_{n,j}^{q-1}}{q}) > 0$ .
- (iii)  $\{a_{n,i}\}_{i=1}^N, \{b_{n,j}\}_{j=1}^M \subset (0, 1]$ ,  $\sum_{i=1}^N a_{n,i} = \sum_{j=1}^M b_{n,j} = 1$ ;
- (iv)  $0 < \liminf \beta_n \leq \limsup \beta_n < 1$ .

Then, the sequence  $\{x_n\}$  converges strongly to a point  $x^* \in \Omega$ , where  $x^* = \Pi_{\Omega}v$ .

*Proof.* Let  $x^* \in \Omega$ . Then, using (3.1), (2.1), and Lemma 2.1, we obtain

$$\begin{aligned}
\Delta_p(x^*, z_n) &\leq \Delta_p\left(x^*, J_E^q \left[ \sum_{i=1}^N a_{n,i} (J_{E_i}^p y_n - \tau_{n,i} l_i A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)) \right] \right) \\
&\leq \frac{1}{p} \|x^*\|^p - \langle x^*, J_E^p y_n \rangle + \sum_{i=1}^N \tau_{n,i} a_{n,i} l_i \langle A_i x^*, J_{E_i}^p (A_i y_n - T_i A_i y_n) \rangle \\
&\quad + \frac{1}{q} \left\| \sum_{i=1}^N a_{n,i} (J_{E_i}^p y_n - \tau_{n,i} l_i A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)) \right\|^q \\
&\leq \frac{1}{p} \|x^*\|^p - \langle x^*, J_E^p y_n \rangle + \sum_{i=1}^N \tau_{n,i} a_{n,i} l_i \langle A_i x^*, J_{E_i}^p (A_i y_n - T_i A_i y_n) \rangle \\
&\quad + \frac{1}{q} \sum_{i=1}^N a_{n,i} \|J_{E_i}^p y_n - \tau_{n,i} l_i A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)\|^q \\
&\leq \frac{1}{p} \|x^*\|^p - \langle x^*, J_E^p y_n \rangle + \frac{\|y_n\|^p}{q} - \sum_{i=1}^N \tau_{n,i} a_{n,i} l_i \langle A_i y_n - A_i x^*, J_{E_i}^p (A_i y_n - T_i A_i y_n) \rangle \\
&\quad + \frac{C_q}{q} \sum_{i=1}^N \tau_{n,i}^q a_{n,i} \|A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)\|^q \\
&\leq \Delta_p(x^*, y_n) - \sum_{i=1}^N \tau_{n,i} a_{n,i} l_i \frac{1}{|\xi_i|} \|A_i y_n - T_i A_i y_n\|^p \\
&\quad + \frac{C_q}{q} \sum_{i=1}^N \tau_{n,i}^q a_{n,i} \|A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)\|^q \\
&\leq \Delta_p(x^*, y_n) - \sum_{i=1}^N \frac{a_{n,i} \rho_{n,i} \|A_i y_n - T_i A_i y_n\|^{p(p-1)}}{|\xi_i| \bar{\tau}_{n,i}^p} \|A_i y_n - T_i A_i y_n\|^p \\
&\quad + \frac{C_q}{q} \sum_{i=1}^N a_{n,i} \frac{\rho_{n,i}^q \|A_i y_n - T_i A_i y_n\|^{pq(p-1)}}{\bar{\tau}_{n,i}^{pq}} \bar{\tau}_{n,i}^q \\
&\leq \Delta_p(x^*, y_n) - \sum_{i=1}^N a_{n,i} \rho_{n,i} \left( \frac{1}{|\xi_i|} - \frac{C_q \rho_{n,i}^{q-1}}{q} \right) \frac{\|A_i y_n - T_i A_i y_n\|^{p^2}}{\bar{\tau}_{n,i}^p}. \tag{3.2}
\end{aligned}$$

In the same way, we deduce that

$$\Delta_p(x^*, y_n) \leq \Delta_p(x^*, u_n) - \sum_{j=1}^M b_{n,j} \sigma_{n,j} \left( \frac{1}{|\mu_j|} - \frac{C_q \sigma_{n,j}^{q-1}}{q} \right) \|u_n - S_j u_n\|^p. \tag{3.3}$$

From (3.1) and condition (d) of Lemma 2.8, we obtain

$$\Delta_p(x^*, u_n) \leq \Delta_p(x^*, K^{f,\phi} x_n) \leq \Delta_p(x^*, x_n). \tag{3.4}$$

By substituting (3.4) and (3.3) into (3.2), we get

$$\begin{aligned} \Delta_p(x^*, z_n) &\leq \Delta_p(x^*, x_n) - \sum_{j=1}^M b_{n,j} \sigma_{n,j} \left( \frac{1}{|\mu_j|} - \frac{C_q \sigma_{n,j}^{q-1}}{q} \right) \|u_n - S_j u_n\|^p \\ &\quad - \sum_{i=1}^N a_{n,i} \rho_{n,i} \left( \frac{1}{|\xi_i|} - \frac{C_q \rho_{n,i}^{q-1}}{q} \right) \frac{\|A_i y_n - T_i A_i y_n\|^{p^2}}{\bar{\tau}_{n,i}^p}. \end{aligned} \quad (3.5)$$

Since  $\{\sigma_{n,j}\} \subset (0, (\frac{q}{|\mu_j| C_q})^{\frac{1}{q-1}})$  and  $\{\rho_{n,i}\} \subset (0, (\frac{q}{|\xi_i| C_q})^{\frac{1}{q-1}})$ , we have

$$\Delta_p(x^*, z_n) \leq \Delta_p(x^*, x_n). \quad (3.6)$$

Let  $t_n = J_{E^*}^q [\alpha_n J_E^p v_n + (1 - \alpha_n) J_E^p z_n]$ , then

$$\begin{aligned} \Delta_p(x^*, t_n) &\leq \Delta_p(x^*, J_{E^*}^q [\alpha_n J_E^p v_n + (1 - \alpha_n) J_E^p z_n]) \\ &\leq \alpha_n \Delta_p(x^*, v_n) + (1 - \alpha_n) \Delta_p(x^*, z_n) \\ &\leq \alpha_n \Delta_p(x^*, v_n) + (1 - \alpha_n) \Delta_p(x^*, x_n) \end{aligned}$$

It follows that

$$\begin{aligned} \Delta_p(x^*, x_{n+1}) &\leq \Delta_p(x^*, J_{E^*}^q [\beta_n J_E^p x_n + (1 - \beta_n) J_E^p t_n]) \\ &\leq \beta_n \Delta_p(x^*, x_n) + (1 - \beta_n) \Delta_p(x^*, t_n) \\ &\leq \beta_n \Delta_p(x^*, x_n) + (1 - \beta_n) \alpha_n \Delta_p(x^*, v_n) + (1 - \alpha_n)(1 - \beta_n) \Delta_p(x^*, x_n) \\ &\leq (1 - \alpha_n(1 - \beta_n)) \Delta_p(x^*, x_n) + \alpha_n(1 - \beta_n) \Delta_p(x^*, v_n). \end{aligned}$$

Since  $\{v_n\}$  is bounded,  $\{\Delta_p(x^*, v_n)\}$  is also bounded. Hence, by Lemma 2.7,  $\{x_n\}$  is bounded. Consequently,  $\{z_n\}$ ,  $\{y_n\}$ , and  $\{u_n\}$  are bounded.

We now prove that the sequence  $\{x_n\}$  converges strongly to an element of the solution set. From (2.2) and (2.3), we have

$$\begin{aligned} \Delta_p(x^*, t_n) &= \Delta_p(x^*, J_{E^*}^q [\alpha_n J_E^p v_n + (1 - \alpha_n) J_E^p z_n]) \\ &= V_p(x^*, \alpha_n J_E^p v_n + (1 - \alpha_n) J_E^p z_n) \\ &\leq V_p(x^*, \alpha_n J_E^p v_n + (1 - \alpha_n) J_E^p z_n - \alpha_n (J_E^p v_n - J_E^p x^*)) \\ &\quad + \langle t_n - x^*, \alpha_n (J_E^p v_n - J_E^p x^*) \rangle \\ &= \alpha_n \Delta_p(x^*, x^*) + (1 - \alpha_n) \Delta_p(x^*, z_n) + \alpha_n \langle t_n - x^*, J_E^p v_n - J_E^p x^* \rangle \\ &= (1 - \alpha_n) \Delta_p(x^*, x_n) - (1 - \alpha_n) \sum_{j=1}^M b_{n,j} \sigma_{n,j} \left( \frac{1}{|\mu_j|} - \frac{C_q \sigma_{n,j}^{q-1}}{q} \right) \|u_n - S_j u_n\|^p \\ &\quad - (1 - \alpha_n) \sum_{i=1}^N a_{n,i} \rho_{n,i} \left( \frac{1}{|\xi_i|} - \frac{C_q \rho_{n,i}^{q-1}}{q} \right) \frac{\|A_i y_n - T_i A_i y_n\|^{p^2}}{\bar{\tau}_{n,i}^p} \\ &\quad + \alpha_n \langle t_n - x^*, J_E^p v_n - J_E^p x^* \rangle. \end{aligned} \quad (3.7)$$

Consequently,

$$\Delta_p(x^*, x_{n+1}) \leq \beta_n \Delta_p(x^*, x_n) + (1 - \alpha_n) \Delta_p(x^*, t_n)$$

$$\begin{aligned}
&\leq (1 - \alpha_n(1 - \beta_n))\Delta_p(x^*, x_n) \\
&- (1 - \alpha_n)(1 - \beta_n) \sum_{j=1}^M b_{n,j} \sigma_{n,j} \left( \frac{1}{|\mu_j|} - \frac{C_q \sigma_{n,j}^{q-1}}{q} \right) \|u_n - S_j u_n\|^p \\
&- (1 - \alpha_n)(1 - \beta_n) \sum_{i=1}^N a_{n,i} \rho_{n,i} \left( \frac{1}{|\xi_i|} - \frac{C_q \rho_{n,i}^{q-1}}{q} \right) \frac{\|A_i y_n - T_i A_i y_n\|^{p^2}}{\bar{\tau}_{n,i}^p} \\
&+ \alpha_n(1 - \beta_n) \langle t_n - x^*, J_E^p v_n - J_E^p v \rangle \\
&+ \alpha_n(1 - \beta_n) \langle t_n - x^*, J_E^p v - J_E^p x^* \rangle.
\end{aligned} \tag{3.8}$$

Let  $\Gamma_n = \Delta_p(x^*, x_n)$  for all  $n \geq 1$ . From (3.8), we have

$$\begin{aligned}
&(1 - \alpha_n)(1 - \beta_n) \sum_{j=1}^M b_{n,j} \sigma_{n,j} \left( \frac{1}{|\mu_j|} - \frac{C_q \sigma_{n,j}^{q-1}}{q} \right) \|u_n - S_j u_n\|^p \\
&+ (1 - \alpha_n)(1 - \beta_n) \sum_{i=1}^N a_{n,i} \rho_{n,i} \left( \frac{1}{|\xi_i|} - \frac{C_q \rho_{n,i}^{q-1}}{q} \right) \frac{\|A_i y_n - T_i A_i y_n\|^{p^2}}{\bar{\tau}_{n,i}^p} \\
&\leq \Gamma_n - \Gamma_{n+1} \\
&+ \alpha_n(1 - \beta_n) \langle t_n - x^*, J_E^p v_n - J_E^p v \rangle \\
&+ \alpha_n(1 - \beta_n) \langle t_n - x^*, J_E^p v - J_E^p x^* \rangle.
\end{aligned}$$

**Case 1:** Suppose that the sequence  $\{\Gamma_n\}_{n=n_0}^\infty$  is nonincreasing for some  $n_0 \in \mathbb{N}$ . Then  $\{\Gamma_n\}$  is convergent. Hence,

$$\Gamma_n - \Gamma_{n+1} \rightarrow 0$$

Now, by conditions (i) and (iv), we obtain

$$\lim_{n \rightarrow \infty} \|u_n - S_j u_n\| = 0, \quad j = 1, 2, \dots, M, \tag{3.9}$$

and

$$\lim_{n \rightarrow \infty} \|A_i y_n - T_i A_i y_n\| = 0, \quad i = 1, 2, \dots, N. \tag{3.10}$$

Using (3.9), we have

$$\|J_E^p(y_n) - J_E^p(u_n)\| \leq \sum_{j=1}^M b_{n,j} \sigma_{n,j} \|J_E^p(u_n - S_j u_n)\| \rightarrow 0, \tag{3.11}$$

By the uniform continuity of  $J_E^q$  on bounded subsets of  $E^*$  and (3.11), we get

$$\lim_{n \rightarrow \infty} \|y_n - u_n\| = 0. \tag{3.12}$$

Moreover, (3.1) and (3.10) yield

$$\|J_E^p z_n - J_E^p y_n\| \leq \sum_{i=1}^N a_{n,i} \tau_{n,i} \|A_i\| \|J_{E_i}^p(A_i y_n - T_i A_i y_n)\| \rightarrow 0, \quad \text{as } n \rightarrow \infty. \tag{3.13}$$

By the uniform continuity of  $J_{E^*}^q$  on bounded subsets of  $E^*$  and (3.13), we obtain

$$\lim_{n \rightarrow \infty} \|z_n - y_n\| = 0. \quad (3.14)$$

Let  $\eta = \sup_{n \in \mathbb{N}} \{\|x_n\|, \|t_n\|\}$ . Then, by Lemma 2.2, there exists a continuous, strictly increasing, and convex function  $g : [0, 2\eta] \rightarrow \mathbb{R}^+$  with  $g(0) = 0$  such that

$$\begin{aligned} \Delta_p(x^*, x_{n+1}) &= \Delta_p(x^*, J_{E^*}^q [\beta_n J_E^p x_n + (1 - \beta_n) J_E^p t_n]) \\ &= \frac{1}{p} \|x^*\|^p - \langle x^*, \beta_n J_E^p x_n + (1 - \beta_n) J_E^p t_n \rangle \\ &\quad + \frac{1}{q} \|\beta_n J_E^p x_n + (1 - \beta_n) J_E^p t_n\|^q \\ &= \frac{1}{p} \|x^*\|^p - \beta_n \langle x^*, J_E^p x_n \rangle + (1 - \beta_n) \langle x^*, J_E^p t_n \rangle \\ &\quad + \frac{1}{q} \beta_n \|x_n\|^p + \frac{1}{q} (1 - \beta_n) \|t_n\|^p \\ &\quad - \frac{1}{q} (\beta_n^q (1 - \beta_n) + \beta_n (1 - \beta_n)^q) g(\|J_E^p x_n - J_E^p t_n\|) \\ &= \beta_n \Delta_p(x^*, x_n) + (1 - \beta_n) \Delta_p(x^*, t_n) \\ &\quad - \frac{1}{q} (\beta_n^q (1 - \beta_n) + \beta_n (1 - \beta_n)^q) g(\|J_E^p x_n - J_E^p t_n\|) \\ &\leq (1 - \alpha_n (1 - \beta_n)) \Delta_p(x^*, x_n) + \alpha_n (1 - \beta_n) \Delta_p(x^*, v_n) \\ &\quad - \frac{1}{q} (\beta_n^q (1 - \beta_n) + \beta_n (1 - \beta_n)^q) g(\|J_E^p x_n - J_E^p t_n\|). \end{aligned} \quad (3.15)$$

Therefore,

$$\begin{aligned} &\frac{1}{q} (\beta_n^q (1 - \beta_n) + \beta_n (1 - \beta_n)^q) g(\|J_E^p x_n - J_E^p t_n\|) \leq \alpha_n \Delta_p(x^*, v_n) \\ &\quad + \Delta_p(x^*, x_n) - \Delta_p(x^*, x_{n+1}). \end{aligned}$$

Using conditions (i) and (iv), we conclude that  $\lim_{n \rightarrow \infty} g(\|J_E^p x_n - J_E^p t_n\|) = 0$ . Therefore,

$$\lim_{n \rightarrow \infty} \|J_E^p x_n - J_E^p t_n\| = 0.$$

By the uniform continuity of  $J_{E^*}^q$  on bounded subsets of  $E^*$ , we obtain

$$\lim_{n \rightarrow \infty} \|x_n - t_n\| = 0. \quad (3.16)$$

This, together with Lemma 2.5 implies that

$$\lim_{n \rightarrow \infty} \Delta_p(x_n, t_n) = 0.$$

It follows that

$$\Delta_p(z_n, t_n) \leq \alpha_n \Delta_p(z_n, v_n) + (1 - \alpha_n) \Delta_p(z_n, z_n) \rightarrow 0, \text{ as } n \rightarrow \infty.$$

Hence, by Lemma 2.5, we obtain

$$\lim_{n \rightarrow \infty} \|z_n - t_n\| = 0.$$

Consequently,

$$\|z_n - x_n\| \leq \|z_n - t_n\| + \|t_n - x_n\| \rightarrow 0, \text{ as } n \rightarrow \infty. \quad (3.17)$$

Now, using (3.12), (3.14), and (3.17), we get

$$\|u_n - x_n\| \leq \|u_n - y_n\| + \|y_n - z_n\| + \|z_n - x_n\| \rightarrow 0. \quad (3.18)$$

Now, since  $E$  is a reflexive Banach space and  $\{x_n\}$  is bounded, there exists a subsequence  $\{x_{n_k}\}$  of  $\{x_n\}$  such that  $x_{n_k} \rightharpoonup z$ . From (3.18), there exists a subsequence  $\{u_{n_k}\}$  of  $\{u_n\}$  such that  $u_{n_k} \rightharpoonup z$ . Then, by (3.9) and the demiclosedness of  $S_j$ ,  $j = 1, 2, \dots, M$ , we have  $z \in \bigcap_{j=1}^M F(S_j)$ . Moreover, from (3.17), we have  $z_{n_k} \rightharpoonup z$ . By the continuity of  $A_i$ , we obtain  $A_i y_{n_k} \rightarrow A_i z$ . Hence, using (3.11) and the demiclosedness of  $I - T_i$ , we conclude that  $A_i z \in \bigcap_{i=1}^N F(T_i)$ .

Next, we show that  $z \in GEP(f, B, \phi)$ . Using (3.18) and uniformly norm-to-norm continuity of  $J_E^p$  on bounded sets, we obtain

$$\lim_{n \rightarrow \infty} \|J_E^p u_n - J_E^p x_n\| = 0.$$

According to the definition of  $u_n = K^{F, \phi} x_n$ , we get

$$F(u_n, y) + \langle y - u_n, J_E^p u_n - J_E^p x_n \rangle + \phi(u_n, y) - \phi(u_n, u_n) \geq 0, \quad \forall y \in C, \quad (3.19)$$

where  $F(u_n, y) = f(u_n, y) + \langle B u_n, y - u_n \rangle$ . It is clear that  $y \rightarrow f(x, y) + \langle Bx, y - x \rangle$  is lower semicontinuous and convex. Hence, the bifunction  $F : C \times C \rightarrow \mathbb{R}$  satisfies Assumption 2. It follows from (3.19) that

$$\begin{aligned} \langle y - u_{n_k}, J_E^p u_{n_k} - J_E^p x_{n_k} \rangle &\geq -F(u_{n_k}, y) - \phi(u_{n_k}, y) + \phi(u_{n_k}, u_{n_k}) \\ &\geq F(y, u_{n_k}) - \phi(u_{n_k}, y) + \phi(u_{n_k}, u_{n_k}) \end{aligned}$$

for all  $y \in C$ . Taking the limit inferior on both sides of the last inequality and using the continuity of  $\phi$ , we deduce that

$$F(y, z) - \phi(z, y) + \phi(z, z) \leq 0, \quad \forall y \in C.$$

Let  $y_t = ty + (1-t)z$  for all  $y \in C$  and all  $0 < t < 1$ , by the convexity of  $C$ , we have  $y_t \in C$  and hence

$$F(y_t, z) - \phi(z, y_t) + \phi(z, z) \leq 0.$$

Now,

$$\begin{aligned} 0 = F(y_t, y_t) &\leq tF(y_t, y) + (1-t)F(y_t, z) \\ &\leq tF(y_t, y) + (1-t)[\phi(z, y_t) - \phi(z, z)] \\ &\leq tF(y_t, y) + (1-t)t[\phi(z, y) - \phi(z, z)]. \end{aligned}$$

As  $t > 0$ , we have

$$F(z, y) + \phi(z, y) - \phi(z, z) \geq 0, \quad \forall y \in C.$$

Therefore,

$$f(z, y) + \langle Bz, y - z \rangle + \phi(z, y) - \phi(z, z) \geq 0, \quad \forall y \in C.$$

So  $z \in GEP(f, B, \phi)$ . Hence  $z \in \Omega$ . Next, we show that

$$\limsup_{n \rightarrow \infty} \langle t_n - x^*, J_E^p v - J_E^p x^* \rangle \leq 0$$

To derive this inequality, choose a subsequence  $\{x_{n_k}\}$  of  $\{x_n\}$  such that

$$\limsup_{n \rightarrow \infty} \langle t_n - x^*, J_E^p v - J_E^p x^* \rangle = \lim_{k \rightarrow \infty} \langle t_{n_k} - x^*, J_E^p v - J_E^p x^* \rangle.$$

Since  $x_{n_k} \rightarrow z$  and by (3.16), we also have  $t_{n_k} \rightarrow z$ . Hence,

$$\limsup_{n \rightarrow \infty} \langle t_n - x^*, J_E^p v - J_E^p x^* \rangle = \langle z - x^*, J_E^p v - J_E^p x^* \rangle \leq 0. \quad (3.20)$$

Since  $v_n \rightarrow v$ , it follows that  $\lim_{n \rightarrow \infty} \langle t_n - x^*, J_E^p v_n - J_E^p v \rangle = 0$ . Combining this with (3.8) and (3.20), we deduce by Lemma 2.7 that  $\Gamma_n \rightarrow 0$  as  $n \rightarrow \infty$ . Hence,  $x_n \rightarrow x^*$ .

**Case 2:** Let  $\tau : \mathbb{N} \rightarrow \mathbb{N}$  be a mapping defined by  $\tau(n) := \max\{k \in \mathbb{N} : k \leq n, \Gamma_k \leq \Gamma_{k+1}\}$  for all  $n \geq n_0$ . Then, by Lemma 2.6 we have  $\tau(n) \rightarrow \infty$  and  $0 \leq \Gamma_{\tau(n)} \leq \Gamma_{\tau(n)+1}$  for all  $n \geq n_0$ . Following the same argument as in case 1, we have

$$\lim_{n \rightarrow \infty} \|A_i y_{\tau(n)} - T_i A_i y_{\tau(n)}\| = \lim_{n \rightarrow \infty} \|u_{\tau(n)} - S_j u_{\tau(n)}\| = 0.$$

Moreover, we can show that

$$\limsup_{n \rightarrow \infty} \langle t_{\tau(n)} - x^*, J_E^p v - J_E^p x^* \rangle \leq 0.$$

Also, from (3.8) and  $0 \leq \Gamma_{\tau(n)} \leq \Gamma_{\tau(n)+1}$ , we have

$$\Gamma_{\tau(n)} \leq \langle t_{\tau(n)} - x^*, J_E^p v_{\tau(n)} - J_E^p x^* \rangle + \langle t_{\tau(n)} - x^*, J_E^p v - J_E^p x^* \rangle. \quad (3.21)$$

Therefore,  $\limsup_{n \rightarrow \infty} \Gamma_{\tau(n)} \leq 0$  and hence  $\lim_{n \rightarrow \infty} \Gamma_{\tau(n)} = 0$ . Again, from (3.8), we have

$$\begin{aligned} \Gamma_{\tau(n)+1} - \Gamma_{\tau(n)} &\leq \alpha_{\tau(n)}(1 - \beta_{\tau(n)}) \langle t_{\tau(n)} - x^*, J_E^p v_{\tau(n)} - J_E^p x^* \rangle \\ &\quad + \alpha_{\tau(n)}(1 - \beta_{\tau(n)}) \langle t_{\tau(n)} - x^*, J_E^p v - J_E^p x^* \rangle \\ &\rightarrow 0. \end{aligned}$$

It follows from (3.21) that  $\lim_{n \rightarrow \infty} \Gamma_{\tau(n)+1} = 0$ . Hence,

$$0 \leq \Gamma_n \leq \max\{\Gamma_{\tau(n)}, \Gamma_n\} \leq \Gamma_{\tau(n)+1} \rightarrow 0.$$

Thus,  $\lim_{n \rightarrow \infty} \Delta_p(x^*, x_n) = 0$ , and therefore,  $x_n \rightarrow x^*$ . This completes the proof.  $\square$

**Remark 1.** It is worth comparing the structure of our proposed algorithm (15) with that of recent inertial CQ algorithms, such as the one introduced by Jolaoso and Shehu [16]. Although both algorithms are iterative and use self-adaptive step sizes, their structures differ in several important aspects.

- 1 The algorithm in [16] is designed for Hilbert spaces, while our algorithm operates in the more general framework of  $p$ -uniformly convex and uniformly smooth Banach spaces. This structural difference allows our method to address problems that cannot be formulated in the Hilbert space setting.

- 2 The method in [16] solves the classical split feasibility problem (SFP) with a single output set, incorporating inertial and correction terms for acceleration. Our algorithm addresses the more general split feasibility problem with multiple output sets (SFP MOS). Its structure includes a resolvent operator  $K^{f,\phi}$  for the generalized equilibrium problem and two families of  $\xi_i$ -generalized demimetric mappings  $\{T_i\}$  and  $\eta_j$ -generalized demimetric mappings  $\{S_j\}$  for multiple fixed point constraints.
- 3 The convergence analysis in [16] relies on firmly nonexpansive mappings in Hilbert spaces, while our proof depends on Banach space tools such as Bregman distance inequalities and properties of generalized duality mappings.

**Theorem 3.2.** *Let  $\{v_n\}$  be a sequence in  $C$  such that  $v_n \rightarrow v$ . For a given  $x_1 \in C$ , let  $\{x_n\}$  be a sequence generated by the following iterative algorithm:*

$$\begin{cases} u_n \in C \text{ s.t. } \langle Bu_n, y - u_n \rangle + \langle y - u_n, J_E^p u_n - J_E^p x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = \Pi_C J_{E^*}^q \left[ \sum_{j=1}^M b_{n,j} (J_E^p u_n - \sigma_{n,j} r_j J_E^p (u_n - S_j u_n)) \right], \\ z_n = \Pi_C J_{E^*}^q \left[ \sum_{i=1}^N a_{n,i} (J_E^p y_n - \tau_{n,i} l_i A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)) \right], \\ x_{n+1} = \Pi_C J_{E^*}^q [\beta_n J_E^p x_n + (1 - \beta_n)(\alpha_n J_E^p v_n + (1 - \alpha_n) J_E^p z_n)], \end{cases} \quad (3.22)$$

where  $l_i = \frac{\xi_i}{|\xi_i|}$ ,  $r_j = \frac{\mu_j}{|\mu_j|}$ , and the step-sizes are chosen as follows:

$$\tau_{n,i} = \frac{\rho_{n,i} \|A_i y_n - T_i A_i y_n\|^{p(p-1)}}{\bar{\tau}_{n,i}^p}, \text{ for } i = 1, 2, \dots, N,$$

with

$$\bar{\tau}_{n,i} := \max\{\|A_i^* J_{E_i}^p (A_i y_n - T_i A_i y_n)\|, \gamma\}$$

where  $\gamma > 0$ ,  $\{\rho_{n,i}\} \subset (0, (\frac{q}{|\xi_i| |C_q|})^{\frac{1}{q-1}})$ , and  $\{\sigma_{n,j}\} \subset (0, (\frac{q}{|\mu_j| |C_q|})^{\frac{1}{q-1}})$ . Let the sequences  $\{\alpha_n\}$ ,  $\{\beta_n\}$ ,  $\{a_{n,i}\}$ , and  $\{b_{n,j}\}$  satisfy the following conditions:

- (i)  $\{\alpha_n\} \subseteq (0, 1)$ ,  $\lim_{n \rightarrow \infty} \alpha_n = 0$ , and  $\sum_{n=1}^{\infty} \alpha_n = \infty$ .
- (ii)  $\lim_{n \rightarrow \infty} a_{n,i} \rho_{n,i} (\frac{1}{|\xi_i|} - \frac{C_q \rho_{n,i}^{q-1}}{q}) > 0$ , and  $\lim_{n \rightarrow \infty} b_{n,j} \sigma_{n,j} (\frac{1}{|\mu_j|} - \frac{C_q \sigma_{n,j}^{q-1}}{q}) > 0$ .
- (iii)  $\{a_{n,i}\}_{i=1}^N, \{b_{n,j}\}_{j=1}^M \subset (0, 1]$ ,  $\sum_{i=1}^N a_{n,i} = \sum_{j=1}^M b_{n,j} = 1$ ;
- (iv)  $0 < \liminf \beta_n \leq \limsup \beta_n < 1$ .

Then, the sequence  $\{x_n\}$  converges strongly to a point  $x^* \in \Omega$ , where  $x^* = \Pi_{\Omega} v$ .

*Proof.* Letting  $f = 0$  and  $\phi = 0$  in Theorem 3.1, we obtain the desired result.  $\square$

## 4 Applications

In this section, we present some applications of our main result.

Let  $\{C_j\}_{j=1}^M$ , and  $\{Q_i\}_{i=1}^N$  be nonempty, closed, and convex subsets of  $E$  and  $E_i$ , respectively. Consider the following problem:

$$\Omega = \Gamma \cap \text{Sol}(B, f, \phi), \quad (4.1)$$

where  $\Gamma$  denotes the solution set of the following generalized SFP MOS: find  $x^*$  so that

$$x^* \in \bigcap_{j=1}^M C_j \quad \text{and} \quad x^* \in \bigcap_{i=1}^N A_i^{-1} Q_i.$$

Let  $S_j = P_{C_j}$  for all  $j = 1, \dots, M$  and  $T_i = P_{Q_i}$  for all  $i = 1, \dots, N$ . Then  $T_j$  and  $S_i$  are 1-generalized demimetric mappings (see [9, 24] for details). Now, if the solution set  $\Omega$  of problem (4.1) is nonempty, then by applying Theorem 3.1 we obtain the following theorem

**Theorem 4.1.** *Let  $\{v_n\}$  be a sequence in  $C$  such that  $v_n \rightarrow v$ . For a given  $x_1 \in C$ , let  $\{x_n\}$  be a sequence generated by the following iterative algorithm:*

$$\begin{cases} u_n \in C \quad \text{s.t.} \quad f(u_n, y) + \langle Bu_n, y - u_n \rangle + \langle y - u_n, J_E^p u_n - J_E^p x_n \rangle \\ \quad + \phi(u_n, y) - \phi(u_n, u_n) \geq 0, \quad \forall y \in C, \\ y_n = \Pi_C J_{E^*}^q \left[ \sum_{j=1}^M b_{n,j} (J_E^p u_n - \sigma_{n,j} r_j J_E^p (u_n - P_{C_j} u_n)) \right], \\ z_n = \Pi_C J_{E^*}^q \left[ \sum_{i=1}^N a_{n,i} (J_E^p y_n - \tau_{n,i} l_i A_i^* J_{E_i}^p (A_i y_n - P_{Q_i} A_i y_n)) \right], \\ x_{n+1} = \Pi_C J_{E^*}^q [\beta_n J_E^p x_n + (1 - \beta_n)(\alpha_n J_p^E v_n + (1 - \alpha_n) J_E^p z_n)], \end{cases} \quad (4.2)$$

where the stepsizes are chosen as follows:

$$\tau_{n,i} = \frac{\rho_{n,i} \|A_i y_n - P_{Q_i} A_i y_n\|^{p(p-1)}}{\bar{\tau}_{n,i}^p}, \quad \text{for } i = 1, 2, \dots, N,$$

with

$$\bar{\tau}_{n,i} := \max\{\|A_i^* J_{E_i}^p (A_i y_n - P_{Q_i} A_i y_n)\|, \gamma\}$$

where  $\gamma > 0$ ,  $\{\rho_{n,i}\} \subset (0, (\frac{q}{C_q})^{\frac{1}{q-1}})$ , and  $\{\sigma_{n,j}\} \subset (0, (\frac{q}{C_q})^{\frac{1}{q-1}})$ . Let the sequences  $\{\alpha_n\}$ ,  $\{\beta_n\}$ ,  $\{a_{n,i}\}$ , and  $\{b_{n,j}\}$  satisfy the following conditions:

- (i)  $\{\alpha_n\} \subseteq (0, 1)$ ,  $\lim_{n \rightarrow \infty} \alpha_n = 0$ , and  $\sum_{n=1}^{\infty} \alpha_n = \infty$ .
- (ii)  $\lim_{n \rightarrow \infty} a_{n,i} \rho_{n,i} (1 - \frac{C_q \rho_{n,i}^{q-1}}{q}) > 0$ , and  $\lim_{n \rightarrow \infty} b_{n,j} \sigma_{n,j} (1 - \frac{C_q \sigma_{n,j}^{q-1}}{q}) > 0$ .
- (iii)  $\{a_{n,i}\}_{i=1}^N, \{b_{n,j}\}_{j=1}^M \subset (0, 1]$ ,  $\sum_{i=1}^N a_{n,i} = \sum_{j=1}^M b_{n,j} = 1$ ;
- (iv)  $0 < \liminf \beta_n \leq \limsup \beta_n < 1$ .

Then, the sequence  $\{x_n\}$  converges strongly to a point  $x^* \in \Omega$ , where  $x^* = \Pi_{\Omega} v$ .

Let  $B : E \rightarrow 2^E$  be a set-valued mapping. The effective domain of  $B$  is denoted by  $D(B)$ , i.e.,  $D(B) = \{x \in E : Bx \neq \emptyset\}$ . The mapping  $B$  on  $E$  is said to be monotone if

$$\langle u - v, x - y \rangle \geq 0 \quad \text{for all } x, y \in D(B), u \in Bx, v \in By.$$

A monotone mapping  $B$  on  $E$  is called maximal if its graph is not properly contained in the graph of any other monotone mapping on  $E$ .

Now, let  $E$  be a  $p$ -uniformly convex and uniformly smooth Banach space, and let  $B : E \rightarrow E^*$  be a maximal monotone mapping. For each  $r > 0$ , the resolvent of  $B$  is defined by

$$J_r^B(x) = (J_p^E + rB)^{-1} J_p^E x, \quad \text{for each } x \in E.$$

It is easy to verify that  $F(J_r^B) = B^{-1}(0)$ , where  $B^{-1}(0) := \{x \in E : 0 \in Bx\}$  (see [15]). For each  $x \in E$  and  $\mu > 0$ , we define the metric resolvent of  $B$  by

$$Q_\mu^B(x) = (I + \mu(J_E^p)^{-1}B)^{-1}(x), \quad \text{for all } x \in E,$$

(see [4]).

Let  $M_j : E \rightarrow E^*$ ,  $1 \leq j \leq M$  and  $N_i : E_i \rightarrow E_i^*$ ,  $1 \leq i \leq N$  be maximal monotone mappings. Let  $S_j = J_{r_j}^{M_j}$  be resolvent operators of  $M_j$  for  $r_j > 0$ , and  $1 \leq j \leq M$ , and let  $T_i = Q_{\mu_i}^{N_i}$  be metric resolvent operators of  $N_i$  for  $\mu_i > 0$  and  $1 \leq i \leq N$ . Then  $S_j$  and  $T_i$  are 1-demimetric and demiclosed (see [9, 24] for details).

Assume that  $\Omega = \Gamma \cap \text{Sol}(B, f, \phi)$  is a nonempty set, where

$$\Omega = (\cap_{j=1}^M M_j^{-1}(0)) \cap (\cap_{i=1}^N A_i^{-1}(N_i^{-1}(0))).$$

Then by applying Theorem 3.1 we have the following theorem.

**Theorem 4.2.** *Let  $\{v_n\}$  be a sequence in  $C$  such that  $v_n \rightarrow v$ . For a given  $x_1 \in C$ , let  $\{x_n\}$  be a sequence generated by the following iterative algorithm:*

$$\left\{ \begin{array}{l} u_n \in C \text{ s.t. } f(u_n, y) + \langle Bu_n, y - u_n \rangle + \langle y - u_n, J_E^p u_n - J_E^p x_n \rangle \\ \quad + \phi(u_n, y) - \phi(u_n, u_n) \geq 0, \quad \forall y \in C, \\ y_n = J_{E^*}^q \left[ \sum_{j=1}^M b_{n,j} (J_E^p u_n - \sigma_{n,j} J_E^p (u_n - J_{r_j}^{M_j} u_n)) \right], \\ z_n = J_{E^*}^q \left[ \sum_{i=1}^N a_{n,i} (J_E^p y_n - \tau_{n,i} A_i^* J_{E_i}^p (A_i y_n - Q_{\mu_i}^{N_i} A_i y_n)) \right], \\ x_{n+1} = J_{E^*}^q \left[ \alpha_n J_E^p u + (1 - \alpha_n) (\beta_n J_E^p x_n + (1 - \beta_n) J_E^p z_n) \right], \end{array} \right. \quad (4.3)$$

where the stepsizes are chosen in such a way that

$$\tau_{n,i} = \frac{\rho_{n,i} \|A_i y_n - Q_{\mu_i}^{N_i} A_i y_n\|^{p(p-1)}}{\bar{\tau}_{n,i}^p}, \quad \text{for } i = 1, 2, \dots, N,$$

where

$$\bar{\tau}_{n,i} := \max\{\|A_i^* J_{E_i}^p (A_i y_n - Q_{\mu_i}^{N_i} A_i y_n)\|, \gamma\}$$

for  $\gamma > 0$ ,  $\rho_{n,i} \in (0, (\frac{q}{C_q})^{\frac{1}{q-1}})$ , and  $\sigma_{n,j} \in (0, (\frac{q}{C_q})^{\frac{1}{q-1}})$ . Let the sequences  $\{\alpha_n\}$ ,  $\{\beta_n\}$ ,  $\{a_{n,i}\}$ , and  $\{b_{n,j}\}$  satisfy the following conditions:

- (i)  $\{\alpha_n\} \subseteq (0, 1)$ ,  $\lim_{n \rightarrow \infty} \alpha_n = 0$ , and  $\sum_{n=1}^{\infty} \alpha_n = \infty$ .
- (ii)  $\lim_{n \rightarrow \infty} a_{n,j} \rho_{n,j} (1 - \frac{C_q \rho_{n,j}^{q-1}}{q}) > 0$ , and  $\lim_{n \rightarrow \infty} b_{n,j} \sigma_{n,j} (1 - \frac{C_q \sigma_{n,j}^{q-1}}{q}) > 0$ .
- (iii)  $\{a_{n,i}\}_{i=1}^N, \{b_{n,j}\}_{j=1}^M \subset (0, 1]$ ,  $\sum_{i=1}^N a_{n,i} = \sum_{j=1}^M b_{n,j} = 1$ ;
- (iv)  $0 < \liminf \beta_n \leq \limsup \beta_n < 1$ .

Then, the sequence  $\{x_n\}$  converges strongly to a point  $x^* \in \Omega$ , where  $x^* = \Pi_\Omega v$ .

## 5 Numerical example

In Theorem 3.1, let  $M = N = 1$ ,  $E = \mathbb{R}$  and  $E_i = \mathbb{R}^2$ . We define  $f : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  by  $f(x, y) = -3x^2 + xy + 2y^2$ ,  $\phi : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$   $\phi(x, y) = x^2 - xy$ , and  $B : \mathbb{R} \rightarrow \mathbb{R}$  by  $Bx = x$ . Through some basic computations, we obtain that  $u = K^{f, \phi} x = \frac{x}{6}$ . Now we define  $T : \mathbb{R} \rightarrow \mathbb{R}$  by  $Tx = 3x$ . Clearly,  $x^* = 0$  is the only fixed point of  $T$  and we have

$$-2(x-0)(-2x) = -2\langle x-p, x-Tx \rangle = 4x^2 = \|x-Tx\|^2$$

Thus  $T$  is  $(-2)$ -generalized demimetric. Note that if we put  $x^* = 0$  and  $x = 1$ , we see that  $T$  is not strictly pseudo-contractive and is not quasinonexpansive. Let  $S : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be defined by  $S(x_1, x_2) = (3x_1, x_2)$ . Clearly  $F(S) = \{(0, a) : \forall a \in \mathbb{R}\}$  and  $S$  is  $(-2)$ -generalized demimetric. Define  $A : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by  $Ax = (x, 0)$ . Clearly  $A$  is a bounded linear operator and  $A^*(x_1, x_2) = x_1$ .

Assume that

$$\alpha_n = \frac{1}{n+10}, \beta_n = \frac{3}{4}, \sigma_{n,j} = \frac{1}{4}, \quad \text{and} \quad \rho_{n,i} = \frac{1}{4}.$$

Figure 1 illustrates the convergence behavior of the sequences  $\{x_n\}$ ,  $\{y_n\}$ , and  $\{z_n\}$ , for the starting points  $x_1 = 3.5$  and  $x_1 = -4$ . Tables 1 shows the numerical values of these sequences for  $x_1 = 3.5$ . The computations were performed using MATLAB.

Table 1: Numerical results for the sequences  $\{x_n\}$ ,  $\{y_n\}$ , and  $\{z_n\}$  in Algorithm 3.1 with initial point  $x_1 = 3.5$

$n$	$x_n$	$y_n$	$z_n$
1	3.5	0.29167	0.14583
2	2.6627	0.22189	0.11095
3	2.0266	0.16888	0.084442
4	1.5433	0.12861	0.064304
5	1.1760	0.097997	0.067882
6	0.90115	0.075096	0.061544
-	-	-	-
-	-	-	-
-	-	-	-
97	0.002127	0.00017725	0.00017725
98	0.0021065	0.00017554	0.00017554
99	0.0020863	0.00017386	0.00017386
100	0.0020665	0.00017221	0.00017221

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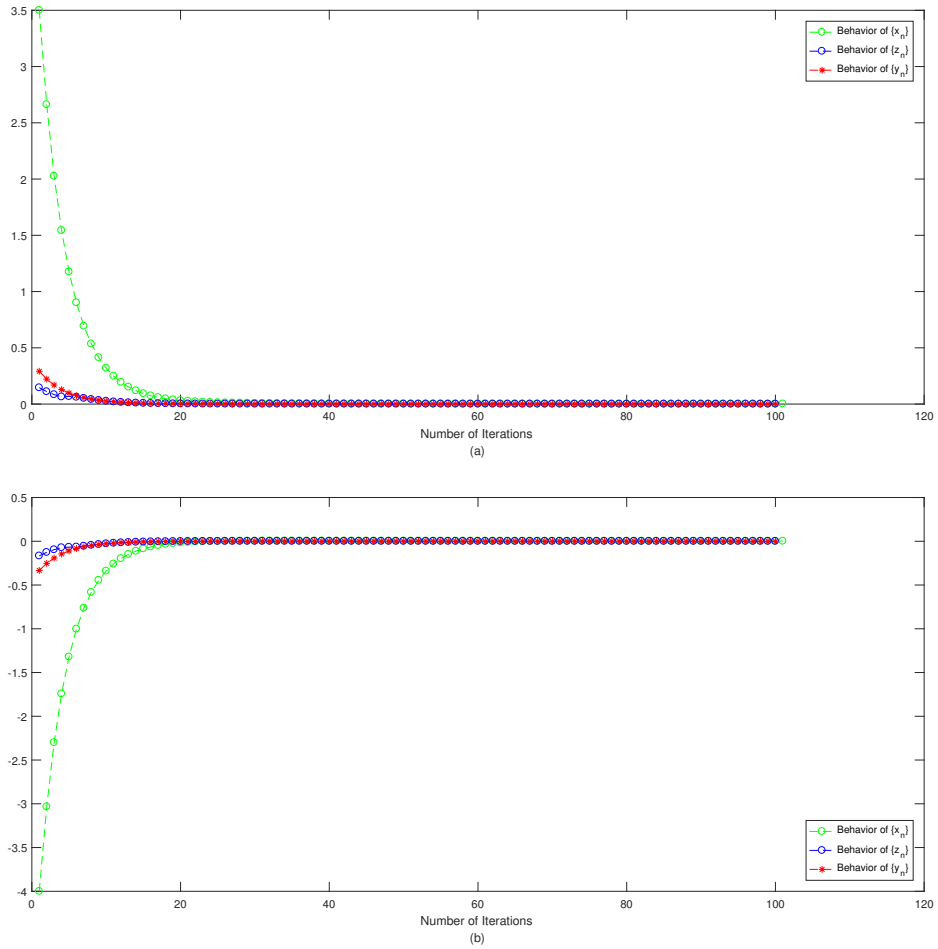


Figure 1: Figure 1 the convergence behavior of Algorithm 3.1 with different choices of starting points: (a)  $x_1 = 3.5$ , and (b)  $x_1 = -4$ .

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