



## A NEW OSCILLATION CRITERION FOR TWO-DIMENSIONAL DYNAMIC SYSTEMS ON TIME SCALES

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**Abstract.** Consider the linear dynamic system on time scales

$$u^\Delta = pv, \quad v^\Delta = -qu^\sigma \tag{0.1}$$

where  $p > 0$  and  $q$  are rd-continuous functions on a time scale  $\mathbb{T}$  such that  $\sup \mathbb{T} = \infty$ . When  $q(t)$  is allowed to take on negative values, we establish an oscillation criterion for system (0.1). Our result improves a main result of Fu and Lin [S. C. Fu and M. L. Lin, Oscillation and nonoscillation criteria for linear dynamic systems on time scales, Computers and Mathematics with Applications, 59(2010), 2552-2565].

### 1. Introduction

Consider the linear dynamic system on time scales

$$u^\Delta = pv, \quad v^\Delta = -qu^\sigma \tag{1.1}$$

where  $p(t) > 0$  and  $q(t)$  are rd-continuous functions on a time scale  $\mathbb{T}$  such that  $\sup \mathbb{T} = \infty$ . For convenience, we put  $P(t) = \int_{t_0}^t p(s)\Delta s$ . A solution  $(x(t), y(t))$  of system (1.1) is called oscillatory if both  $x(t)$  and  $y(t)$  are oscillatory functions, and otherwise it will be called nonoscillatory. System (1.1) will be called oscillatory if its solutions are oscillatory. System (1) can be reduced to a single dynamic equation

$$\left(\frac{1}{p}u^\Delta\right)^\Delta + qu^\sigma = 0. \tag{1.2}$$

In [1], the following oscillation theorem is obtained.

**Theorem 1.1.** *Suppose that  $p(t)$  and  $q(t)$  are nonnegative and  $\int_{t_0}^\infty p(s)\Delta s = \infty$ ,  $\lim_{t \rightarrow \infty} \frac{\mu(t)p(t)}{P(t)} = 0$ . Suppose also that there exists  $\lambda \in (0, 1)$  such that*

$$\int_{t_0}^\infty P^\lambda(t)q(t)\Delta t = \infty,$$

*then system (1.1) is oscillatory.*

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In this paper, we prove the above Theorem 1.1 when  $q(t)$  is allowed to take on negative values. As applications, we get that the linear differential system

$$x' = t^{a-1}y, \quad y' = -\left(\frac{b}{t^{\frac{a}{2}+1}} + \frac{\sin ct}{t^{\frac{a}{2}}}\right)x \tag{1.3}$$

and the linear difference system

$$\Delta x(n) = ny(n), \quad \Delta y(n) = -\left(\frac{b}{n^2} + \frac{(-1)^n}{n}\right)x(n+1) \tag{1.4}$$

where  $a > 0, b > 0, c \in \mathbb{R}$ , are oscillatory.

### 2. Some lemmas

**Lemma 2.1.** *If  $(u(t), v(t))$  is a nonoscillatory solution of system (1.1), then the component  $u(t)$  is also nonoscillatory.*

**Proof.** Assume that  $(u(t), v(t))$  is a solution of system (1.1) and  $u(t)$  is oscillatory, but  $v(t)$  is nonoscillatory. Without loss of generality, we let  $v(t) > 0$  on  $[t_0, \infty)_{\mathbb{T}}$ . In view of the first equation of system (1.1), we have  $u^\Delta(t) > 0$  on  $[t_0, \infty)_{\mathbb{T}}$ . Thus,  $u(t) > 0$  or  $u(t) < 0$  for all large  $t$ , which leads to a contradiction. So, the oscillation of  $u(t)$  implies that of  $v(t)$  as well.  $\square$

The following two lemmas may also be found in [3].

**Lemma 2.2.** *Assume  $a \in \mathbb{T}$ , let  $\omega = \sup \mathbb{T}$ . If  $\omega < \infty$ , then we assume  $\rho(\omega) = \omega$ . If equation (1.2) is nonoscillatory on  $[a, \omega)$ , then there is a solution  $u_1$ , called a recessive solution at  $\omega$ , such that for any second linearly independent solution  $u_2$ , called a dominant solution at  $\omega$ , we have*

$$\lim_{t \rightarrow \omega^-} \frac{u_1(t)}{u_2(t)} = 0, \quad \int_b^\omega \frac{p(t)}{u_1(t)u_1^\sigma(t)} \Delta t = \infty, \quad \text{and} \quad \int_b^\omega \frac{p(t)}{u_2(t)u_2^\sigma(t)} \Delta t < \infty, \tag{2.1}$$

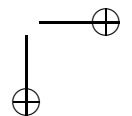
where  $b < \omega$  is sufficiently close. Furthermore,

$$\frac{u_2^\Delta(t)}{p(t)u_2(t)} > \frac{u_1^\Delta(t)}{p(t)u_1(t)} \tag{2.2}$$

for  $t < \omega$  sufficiently close.

**Lemma 2.3.** *(Picone's Identity). Assume  $u(t)$  is a positive solution of (1.2),  $z(t) = \frac{u^\Delta(t)}{p(t)u(t)}$  on  $[a, \infty)$  and assume  $h : \mathbb{T} \rightarrow \mathbb{R}$  is a continuously differentiable function. Then we have for all  $t \in [a, \infty)$ ,*

$$[zh^\Delta]^\Delta(t) = -q(t)h^2(\sigma(t)) + \frac{[h^\Delta(t)]^2}{p(t)} - \left[ \frac{z(t)h^\sigma(t)}{\sqrt{\frac{1}{p(t)} + \mu(t)z(t)}} - \sqrt{\frac{1}{p(t)} + \mu(t)z(t)}h^\Delta(t) \right]^2.$$



The following theorem may be found in [6], Theorem 11, Page 17-18.

**Theorem 2.4.** *The equation  $(\frac{1}{p(t)}u'(t))' + q(t)u(t) = 0$  is oscillatory on the interval  $[t_0, \infty)$ , if  $\int_{t_0}^{\infty} p(t)dt = \infty$  and there exists a continuously differentiable function  $h(t) > 0$  such that*

$$\int_{t_0}^{\infty} \left[ q(t)h^2(t) - \frac{1}{p(t)}(h'(t))^2 \right] dt = +\infty.$$

Analogous to the above theorem, we may obtain a corresponding time scales version which we state as follows:

**Lemma 2.5.** *If  $\int_{t_0}^{\infty} p(t)\Delta t = \infty$  and there exists a function  $h \in C_{rd}^1[t_0, \infty)$  such that  $h(t) > 0$  on  $[t_0, \infty)$  and*

$$\int_{t_0}^{\infty} \left[ q(t)h^2(\sigma(t)) - \frac{1}{p(t)}[h^\Delta(t)]^2 \right] \Delta t = +\infty. \tag{2.3}$$

*Then the dynamic equation (1.2) is oscillatory on  $[t_0, \infty)_\mathbb{T}$ .*

**Proof.** Assume that (1.2) is nonoscillatory. By Lemma 2.2, there is a dominant solution  $u_2(t) > 0$  at  $\infty$  such that for  $t_1 > t_0$ , sufficiently large,

$$\int_{t_1}^{\infty} \frac{p(t)}{u_2(t)u_2^\sigma(t)} \Delta t < \infty. \tag{2.4}$$

Let  $z(t) = \frac{u_2^\Delta(t)}{p(t)u_2(t)}$ . We have

$$z^\Delta(t) = -q(t) - \frac{z^2(t)}{\frac{1}{p(t)} + \mu(t)z(t)},$$

and

$$\frac{1}{p(t)} + \mu(t)z(t) = \frac{u_2(\sigma(t))}{p(t)u_2(t)} > 0.$$

From lemma 2.3, we get

$$\begin{aligned} [zh^2]^\Delta(t) &= -q(t)h^2(\sigma(t)) + \frac{[h^\Delta(t)]^2}{p(t)} \\ &\quad - \left[ \frac{z(t)h^\sigma(t)}{\sqrt{\frac{1}{p(t)} + \mu(t)z(t)}} - \sqrt{\frac{1}{p(t)} + \mu(t)z(t)}h^\Delta(t) \right]^2 \\ &\leq -q(t)h^2(\sigma(t)) + \frac{[h^\Delta(t)]^2}{p(t)}. \end{aligned}$$

Integrating from  $t_1$  to  $t$ , we get

$$z(t)h^2(t) \leq z(t_1)h^2(t_1) - \int_{t_1}^t \left[ q(t)h^2(\sigma(t)) - \frac{[h^\Delta(t)]^2}{p(t)} \right] \Delta t.$$

By (2.3), we obtain

$$\lim_{t \rightarrow \infty} z(t)h^2(t) = -\infty.$$

So there exists a large  $t_2 > t_1$  such that for  $t > t_2$ , we have

$$z(t) = \frac{u_2^\Delta(t)}{p(t)u_2(t)} < 0.$$

This implies  $u_2^\Delta(t) < 0$  for  $t > t_2$ . Hence

$$\begin{aligned} \int_{t_2}^{\infty} p(t)\Delta t &= u_2(t_2)u(\sigma(t_2)) \int_{t_2}^{\infty} \frac{p(t)}{u_2(t_2)u_2(\sigma(t_2))} \Delta t \\ &\leq u_2(t_2)u(\sigma(t_2)) \int_{t_2}^{\infty} \frac{p(t)}{u_2(t)u_2(\sigma(t))} \Delta t \\ &< \infty. \end{aligned}$$

which is a contradiction. □

From Lemma 2.1 and Lemma 2.5, we can get the following

**Lemma 2.6.** *Under the assumption of Lemma 2.5, the system (1.1) is oscillatory.*

Let  $\hat{\mathbb{T}} := \{t \in \mathbb{T} : \mu(t) > 0\}$  and let  $\chi$  denote the characteristic function of  $\hat{\mathbb{T}}$ . The following condition, which will be needed later, imposes a lower bound on the graininess function  $\mu(t)$ , for  $t \in \hat{\mathbb{T}}$ . More precisely, we introduce the following (see [4] and [5]).

**Condition (C).** We say that  $\mathbb{T}$  satisfies condition C if there is an  $M > 0$  such that

$$\chi(t) \leq M\mu(t), \quad t \in \mathbb{T}.$$

We note that if  $\mathbb{T}$  satisfies condition (C), then the set

$$\check{\mathbb{T}} = \{t \in \mathbb{T} \mid t > 0 \text{ is isolated or right-scattered or left-scattered}\}$$

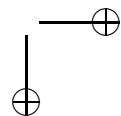
is necessarily countable.

**Lemma 2.7.** *Assume that  $\mathbb{T}$  satisfies condition C. Then for all  $\lambda \in [0, 1)$ , we have*

$$\int_{t_0}^t \frac{p(s)}{P^{2-\lambda}(\sigma(s))} \Delta s \leq \frac{[P(t_0)]^{-1+\lambda}}{1-\lambda}.$$

**Proof.** For any  $t \in \mathbb{T}$ , if  $t = t' < t'' = \sigma(t)$ , from  $P^\Delta(s) = p(s) > 0$ , we get that

$$\int_t^{\sigma(t)} \frac{p(s)}{P^{2-\lambda}(\sigma(s))} \Delta s = \frac{\mu(t)P^\Delta(t)}{P^{2-\lambda}(\sigma(t))}$$



$$\begin{aligned}
 &= \frac{P(\sigma(t)) - P(t)}{P^{2-\lambda}(\sigma(t))} \\
 &\leq \int_{P(t)}^{P(\sigma(t))} \frac{1}{v^{2-\lambda}} dv.
 \end{aligned}
 \tag{2.5}$$

If the real interval  $[t', t''] \subset \mathbb{T}$ , then

$$\int_{t'}^{t''} \frac{p(s)}{P^{2-\lambda}(\sigma(s))} \Delta s = \int_{t'}^{t''} \frac{p(s)}{P^{2-\lambda}(s)} ds = \int_{P(t')}^{P(t'')} \frac{1}{v^{2-\lambda}} dv.
 \tag{2.6}$$

Note that since  $\mathbb{T}$  satisfies condition C, we have from (2.5), (2.6) and the additivity of the integral that

$$\begin{aligned}
 \int_{t_0}^t \frac{p(s)}{P^{2-\lambda}(\sigma(s))} \Delta s &\leq \int_{P(t_0)}^{P(t)} \frac{1}{v^{2-\lambda}} dv \\
 &= \frac{[P(t)]^{-1+\lambda} - [P(t_0)]^{-1+\lambda}}{-1 + \lambda} \\
 &\leq \frac{[P(t_0)]^{-1+\lambda}}{1 - \lambda}.
 \end{aligned}
 \tag{2.7}$$

□

### 3. Main Theorem

**Theorem 3.1.** Assume that  $\mathbb{T}$  satisfies condition C and  $\lim_{t \rightarrow \infty} \frac{\mu(t)p(t)}{P(t)} = 0$ ,  $\int_{t_0}^{\infty} p(t) \Delta t = \infty$ . Suppose also that there exists  $\lambda \in [0, 1)$  such that

$$\int_{t_0}^{\infty} P^\lambda(\sigma(t))q(t) \Delta t = \infty.
 \tag{3.1}$$

Then system (0.1) is oscillatory.

**Proof.** Take  $h(t) = [P(t)]^{\frac{\lambda}{2}}$ . Using the Pötzsche chain rule [3, Theorem 1.90], we get

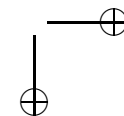
$$h^\Delta(t) = \frac{\lambda}{2} \int_0^1 [(1-\tau)P(t) + \tau P(\sigma(t))]^{\frac{\lambda}{2}-1} d\tau p(t).
 \tag{3.2}$$

Since  $\lim_{t \rightarrow \infty} \frac{\mu(t)p(t)}{P(t)} = 0$ , it follows that  $\lim_{t \rightarrow \infty} \frac{P(\sigma(t))}{P(t)} = 1$  so given  $\epsilon$  with  $0 < \epsilon < 1$ , there exists  $t_1$  sufficiently large so that for  $t \geq t_1$  we have

$$P(t) \geq (1 - \epsilon)P(\sigma(t)).
 \tag{3.3}$$

From (3.2), (3.3) and Lemma 2.7, we get

$$\begin{aligned}
 \int_{t_1}^{\infty} \frac{[h^\Delta(t)]^2}{p(t)} \Delta t &\leq \left(\frac{\lambda}{2}\right)^2 \int_{t_1}^{\infty} p(t)[P(\sigma(t))]^{\lambda-2} \left\{ \int_0^1 [(1-\tau)(1-\epsilon) + \tau]^{\frac{\lambda}{2}-1} d\tau \right\}^2 \Delta t \\
 &= \frac{1}{\epsilon^2} [1 - (1-\epsilon)^{\frac{\lambda}{2}}]^2 \int_{t_1}^{\infty} p(t)[P(\sigma(t))]^{\lambda-2} \Delta t
 \end{aligned}$$



$$< +\infty. \tag{3.4}$$

From (3.1) and (3.4), we obtain

$$\int_{t_1}^{\infty} \left[ q(t)h^2(\sigma(t)) - \frac{1}{p(t)}[h^\Delta(t)]^2 \right] \Delta t = +\infty. \tag{3.5}$$

From (3.5) and Lemma 2.6, the system (1.1) is oscillatory. □

**Remark 3.2.** From the proof of the Theorem 3.1, it is easy to see that the assumption “ $\lim_{t \rightarrow \infty} \frac{\mu(t)p(t)}{P(t)} = 0$ ” in Theorem 3.1 can be replaced by “ $\frac{P(\sigma(t))}{P(t)}$  is bounded for all  $t \in \mathbb{T}$ ”.

Let  $\mathbb{T} = \mathbb{N}$ . Consider the linear difference system

$$\Delta x(n) = 2^n y(n), \quad \Delta y(n) = -\frac{\alpha + \beta(-1)^n}{[2^{n+1} - 1]^{\frac{1}{2}}} x(n+1) \tag{3.6}$$

where  $\beta > \alpha > 0$ . It is easy to see that  $P(t) = \int_0^t p(t)\Delta t = 2^t - 1$ .  $\lim_{t \rightarrow \infty} \frac{p(t)}{P(t)} = 1 \neq 0$ .  $\frac{P(\sigma(t))}{P(t)} = \frac{2^{t+1}-1}{2^t-1}$  is bounded for  $t \geq 1$ . Choose  $\lambda = 1/2$ . We have

$$\int_0^{\infty} P^{\frac{1}{2}}(\sigma(t))q(t)\Delta t = \sum_{n=1}^{\infty} (\alpha + \beta(-1)^n) = \infty.$$

So by Remark 3.2, (3.6) is oscillatory, but do not follow from Theorem 3.1.

#### 4. Example

**Example 4.1.** Consider the linear differential system

$$x' = t^{a-1}y, \quad y' = -\left(\frac{b}{t^{\frac{a}{2}+1}} + \frac{\sin ct}{t^{\frac{a}{2}}}\right)x \tag{4.1}$$

where  $a > 0, b > 0, c \in R$ .

Take  $\lambda = \frac{1}{2}$ . It is easy to see that

$$P(t) = \int_1^t p(s)ds = \frac{1}{a}(t^a - 1),$$

$$\int_1^{\infty} P^{\frac{1}{2}}(t)q(t)dt = \frac{b}{\sqrt{a}} \int_1^{\infty} \left[ \frac{t^a - 1}{t^{a+2}} \right]^{\frac{1}{2}} dt + \frac{1}{\sqrt{a}} \int_1^{\infty} (1 - t^{-a})^{\frac{1}{2}} \sin ctdt.$$

By using Taylor’s expansion, there exists a positive integer  $m$  such that  $ma > 1$  and

$$(1 - t^{-a})^{\frac{1}{2}} = 1 - 2^{-1}t^{-a} + \frac{2^{-1}(2^{-1} - 1)}{2!}t^{-2a} + \dots$$

$$+ (-1)^m \frac{2^{-1}(2^{-1} - 1) \dots (2^{-1} - m + 1)}{m!}t^{-ma} + o(t^{-ma}).$$

Note that for  $k = 1, 2, \dots, m - 1$ ,  $\int_1^{\infty} t^{-ka} \sin ctdt$  and  $\int_1^{\infty} o(t^{-ma})dt$  are convergent. It is obvious that  $\int_1^{\infty} \left[ \frac{t^a - 1}{t^{a+2}} \right]^{\frac{1}{2}} dt = +\infty$ . So we have  $\int_1^{\infty} P^{\frac{1}{2}}(t)q(t)dt = +\infty$ . By Theorem 3.1, the system (4.1) is oscillatory.

**Example 4.2.** Consider the linear difference system

$$\Delta x(n) = ny(n), \quad \Delta y(n) = -\left(\frac{b}{n^2} + \frac{(-1)^n}{n}\right)x(n+1) \tag{4.2}$$

where  $b > 0$ .

Take  $\lambda = \frac{1}{2}$ . It is easy to see that  $P(n) = \frac{n(n-1)}{2}$ ,

$$\int_1^\infty P^{\frac{1}{2}}(t)q(t)\Delta t = \frac{1}{\sqrt{2}} \sum_{n=1}^\infty [n(n-1)]^{\frac{1}{2}} \left(\frac{b}{n^2} + \frac{(-1)^n}{n}\right).$$

Using Taylor’s formula, we have

$$\left(1 - \frac{1}{n}\right)^{\frac{1}{2}} = 1 - \frac{1}{2n} + \frac{2^{-1}(2^{-1}-1)}{2} \frac{1}{n^2} + o(n^{-2}).$$

So for any  $m$ ,  $\sum_{n=1}^m (-1)^n(1 - \frac{1}{n})^{\frac{1}{2}}$  is bounded. Therefore  $\int_1^\infty P^{\frac{1}{2}}(t)q(t)dt = +\infty$ . By Theorem 3.1, the system (4.2) is oscillatory.

**Example 4.3.** Consider the  $q$ -difference system

$$x^\Delta(t) = t^{a-1}y(t), \quad y^\Delta(t) = -\left(\frac{b+(-1)^n}{t^{\frac{a}{2}}}\right)x(qt). \tag{4.3}$$

where  $a > 0, 0 < b < 1, t = q^n \in \mathbb{T} = q^{\mathbb{N}_0}, q > 1$ .

Take  $\lambda = \frac{1}{2}$ . It is easy to see that  $P(t) = \frac{(q-1)(t^a-1)}{q^a-1}, P(\sigma(t)) = \frac{(q-1)[(qt)^a-1]}{q^a-1}$ . So  $\lim_{t \rightarrow \infty} \frac{P(\sigma(t))}{P(t)} = q^a$ , which implies  $\frac{P(\sigma(t))}{P(t)}$  is bounded.

$$\int_1^\infty P^{\frac{1}{2}}(t)q(t)\Delta t = \left(\frac{q-1}{q^a-1}\right)^{\frac{1}{2}} \sum_{i=1}^\infty \left(\frac{q^{(i-1)a}-1}{q^{(i-1)a}}\right)^{\frac{1}{2}} [b+(-1)^i] = +\infty.$$

By Theorem 3.1 and Remark 3.2, the system (4.3) is oscillatory.

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