AN INVERSE SPECTRAL PROBLEM FOR DIFFERENTIAL OPERATORS WITH INTEGRAL DELAY

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Abstract. The uniqueness theorem is proved for the solution of the inverse spectral problem for second-order integro-differential operators on a finite interval. These operators are perturbations of the Sturm-Liouville operator with convolution and one-dimensional operators. The main tool is an integral transform connected with solutions of integrodifferential operators.

1. Introduction

Consider the problem L = L(q, M, R, V) of the form

$$\ell y(x) := -y''(x) + q(x)y(x) + \int_0^x M(x-t)y(t) dt + R(x) \int_0^\pi V(t)y(t) dt = \lambda y(x), \ 0 \le x \le \pi, \ (1)$$

$$y(0) = y'(0) = 0,$$
(2)

where λ is the spectral parameter, and q, M, R, V are continuous functions. The operator ℓ is a perturbation of the Sturm-Liouville operator with convolution and one-dimensional operators. We study the inverse spectral problem for *L*. Inverse problems of spectral analysis consist in recovering operators from their spectral characteristics. Such problems often appear in many branches of natural sciences and engineering. For the Sturm-Liouville differential operator, inverse spectral problems have been studied fairly completely (see the monographs [1]-[5] and the references therein). Inverse problems for integro-differential and integral operators are much more difficult for investigating, and nowadays there are only several isolated results related to these "non-local" inverse problems (see [6]-[9] and the references therein). The integro-differential operator ℓ , considered in the present paper, is the one-dimensional perturbation of the Volterra integro-differential operator. We study the inverse problem of recovering the perturbation provided that the Volterra part is known a priori. In order to formulate the inverse problem for (1)-(2) we first introduce the spectral data for *L*.

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Let $u(x, \lambda)$ be the solution of the Cauchy problem

$$-u''(x,\lambda) + q(x)u(x,\lambda) + \int_0^x M(x-t)u(t,\lambda)\,dt + R(x) = \lambda u(x,\lambda), \quad u(0,\lambda) = u'(0,\lambda) = 0.$$
(3)

Denote

$$\Delta(\lambda) := 1 - \int_0^{\pi} V(t) u(t, \lambda) \, dt. \tag{4}$$

The function $\Delta(\lambda)$ is entire in λ , and its zeros $\{\lambda_n\}$ coincide with the eigenvalues of *L*. The function $\Delta(\lambda)$ is called the characteristic function of *L*.

We note that if $V(x) \equiv 0$ or/and $R(x) \equiv 0$, then $\Delta(\lambda) \equiv 1$ (if $R(x) \equiv 0$, then $u(x, \lambda) \equiv 0$, since the Cauchy problem is equivalent to the homogeneous integral Volterra equation of second kind), and *L* has no eigenvalues. In order to avoid this trivial case we will assume in the sequel that

$$R(x) \sim d_0 x^{\alpha}, \quad V(\pi - x) \sim d_1 x^{\beta}, \ x \to 0, \ d_0 d_1 \neq 0,$$
 (5)

where $\alpha, \beta \ge 0$. In this case *L* has a countable set of eigenvalues $\{\lambda_n\}_{n\ge 1}$. Moreover, if $\kappa_n \ge 1$ is a multiplicity of the zero λ_n of $\Delta(\lambda)$, then the functions

$$u_{jn}(x) := \frac{\partial^{j} u(x,\lambda)}{\partial \lambda^{j}}_{|\lambda=\lambda_{n}}, \quad j = \overline{0, \kappa_{n} - 1}$$

are root functions of *L*. Denote $\alpha_{jn} := u_{jn}(\pi), n \ge 1, j = \overline{0, \kappa_n - 1}$. The data $S := \{\lambda_n, \alpha_{jn}\}_{n \ge 1, j = \overline{0, \kappa_n - 1}}$ are called the spectral data of *L*.

The inverse problem is formulated as follows: Let *q* and *M* be known a priori and fixed. Given the spectral data *S*, construct *R* and *V*.

The goal of the present paper is to prove the uniqueness theorem for the solution of this inverse problem. For this purpose together with *L* we consider a problem $\tilde{L} := L(q, M, \tilde{R}, \tilde{V})$. We agree that if a certain symbol *a* denotes an object related to *L*, then \tilde{a} will denote a similar object related to \tilde{L} . Now we formulate the main result of the paper.

Theorem 1. If $S = \tilde{S}$, then $R = \tilde{R}$ and $V = \tilde{V}$. Thus, the specification of the spectral data *S* uniquely determines the functions *R* and *V*.

In Section 2 we establish some auxiliary propositions, and in Section 3 we provide the proof of Theorem 1.

2. Auxiliary propositions

Denote

$$\ell_1 y(x) := -y''(x) + q(x)y(x) + \int_0^x M(x-t)y(t) \, dt.$$

Let $S(x, \lambda)$ be the solution of the Cauchy problem

$$\ell_1 S(x,\lambda) = \lambda S(x,\lambda), \quad S(0,\lambda) = 0, \ S'(0,\lambda) = 1.$$
(6)

By the same arguments as in [7] and [9] one gets that the following representation holds

$$S(x,\lambda) = \frac{\sin\rho x}{\rho} + \int_0^x K(x,t) \frac{\sin\rho t}{\rho} dt, \quad \lambda = \rho^2,$$
(7)

where K(x, t) is a twice continuously differentiable function which does not depend on λ , and K(x, 0) = 0.

Lemma 1. The following relations are valid

$$K_{tt}(x,t) - K_{xx}(x,t) + q(x)K(x,t) + M(x-t) + \int_{t}^{x} M(x-\xi)K(\xi,t)\,d\xi = 0,$$
(8)

$$q(x) = 2\frac{dK(x,x)}{dx}.$$
(9)

Proof. Differentiating (7) twice with respect to *x*, we get

$$S'(x,\lambda) = \cos\rho x + K(x,x)\frac{\sin\rho x}{\rho} + \int_0^x K_x(x,t)\frac{\sin\rho t}{\rho} dt,$$

$$S''(x,\lambda) = -\rho\sin\rho x + \frac{d}{dx} \left(K(x,x)\frac{\sin\rho x}{\rho} \right) + K_x(x,t)_{|t=x}\frac{\sin\rho x}{\rho} + \int_0^x K_{xx}(x,t)\frac{\sin\rho t}{\rho} dt.$$

Substituting into (6) we calculate

$$\rho \sin \rho x - \frac{d}{dx} \Big(K(x,x) \frac{\sin \rho x}{\rho} \Big) - K_x(x,t)|_{t=x} \frac{\sin \rho x}{\rho} - \int_0^x K_{xx}(x,t) \frac{\sin \rho t}{\rho} dt + q(x) \frac{\sin \rho x}{\rho} + q(x) \int_0^x K(x,t) \frac{\sin \rho t}{\rho} dt + \int_0^x M(x-t) \frac{\sin \rho t}{\rho} dt + \int_0^x M(x-t) \Big(\int_0^t K(t,\xi) \frac{\sin \rho \xi}{\rho} d\xi \Big) dt = \rho \sin \rho x + \rho \int_0^x K(x,t) \sin \rho t dt.$$

Integrating twice by parts the last integral we obtain

$$\begin{split} \int_0^x \Big(-K_{xx}(x,t) + q(x)K(x,t) + M(x-t) + \int_t^x M(x-\xi)K(\xi,t)\,d\xi \Big) \frac{\sin\rho t}{\rho}\,dt \\ -K_x(x,t)_{|t=x} \frac{\sin\rho x}{\rho} - \frac{dK(x,x)}{dx} \frac{\sin\rho x}{\rho} - K(x,x)\cos\rho x + q(x)\frac{\sin\rho x}{\rho} \\ &= -K(x,x)\cos\rho x + K(x,0) + K_t(x,t)_{|t=x} \frac{\sin\rho x}{\rho} - \int_0^x K_{tt}(x,t) \frac{\sin\rho t}{\rho}\,dt. \end{split}$$

Since

$$K_x(x,t)|_{t=x} + K_t(x,t)|_{t=x} = \frac{dK(x,x)}{dx}, \quad K(x,0) = 0,$$

it follows that

$$\int_0^x A(x,t) \sin \rho t \, dt + B(x) \sin \rho x = 0, \tag{10}$$

where

$$\begin{aligned} A(x,t) &= K_{tt}(x,t) - K_{xx}(x,t) + q(x)K(x,t) + M(x-t) + \int_{t}^{x} M(x-\xi)K(\xi,t) \, d\xi, \\ B(x) &= q(x) - 2\frac{dK(x,x)}{dx}. \end{aligned}$$

Fix *x* and take $\rho = \rho_n := (2\pi n + \pi/2)x^{-1}$ in (10). Then

$$\lim_{n \to \infty} \int_0^x A(x,t) \sin(\rho_n t x^{-1}) dt = 0,$$

and consequently, (10) yields $B(x) \equiv 0$. Therefore, $\int_0^x A(x, t) \sin \rho t \, dt = 0$ for all ρ , and hence A(x, t) = 0 for $0 \le t \le x$. Lemma 1 is proved.

Lemma 2. Let $f \in C^2[0,\pi]$, and let

$$h(x) := f(x) + \int_0^x K(x, t) f(t) dt.$$
(11)

Then

$$\ell_1 h(x) = -f''(x) - \int_0^x K(x,t) f''(t) \, dt + f(0) K_t(x,t)|_{t=0}, \ x \in [0,\pi].$$
(12)

Proof. Differentiating (11) twice we get

$$h'(x) = f'(x) + K(x, x)f(x) + \int_0^x K_x(x, t)f(t) dt,$$

$$h''(x) = f''(x) + \frac{d}{dx} \Big(K(x, x)f(x) \Big) + K_x(x, t)_{|t=x}f(x) + \int_0^x K_{xx}(x, t)f(t) dt,$$

and consequently,

$$\ell_1 h(x) = -f''(x) - \frac{d}{dx} \Big(K(x, x) f(x) \Big) - K_x(x, t)_{|t=x} f(x) - \int_0^x K_{xx}(x, t) f(t) dt + q(x) f(x) + \int_0^x q(x) K(x, t) f(t) dt + \int_0^x M(x-t) f(t) dt + \int_0^x M(x-t) \Big(\int_0^t K(t,\xi) f(\xi) d\xi \Big) dt.$$

Taking (9) into account we infer

$$\ell_1 h(x) = -f''(x) + \int_0^x f(t) \Big(-K_{xx}(x,t) + q(x)K(x,t) + M(x-t) + \int_t^x M(x-\xi)K(\xi,t) \, d\xi \Big) dt$$
$$-K_x(x,t)_{|t=x} f(x) - \frac{dK(x,x)}{dx} f(x) - K(x,x)f'(x) + 2\frac{dK(x,x)}{dx} f(x).$$

Together with (8) this yields

$$\ell_1 h(x) = -f''(x) - \int_0^x f(t) K_{tt}(x,t) \, dt - K_x(x,t)|_{t=x} f(x) + \frac{dK(x,x)}{dx} f(x) - K(x,x) f'(x).$$

Integrating the integral by parts twice we calculate

$$\ell_1 h(x) = -f''(x) - \int_0^x K(x,t) f''(t) \, dt + f(0) K_t(x,t)|_{t=0} \, ,$$

i.e. (12) is valid. Lemma 2 is proved.

3. The proof of Theorem 1

For each fixed *t*, let $g(x, t, \lambda)$, $x \ge t$ be the solution of the Cauchy problem

$$-g''(x,t,\lambda) + q(x)g(x,t,\lambda) - \lambda g(x,t,\lambda) + \int_t^x M(x-\xi)g(\xi,t,\lambda)\,d\xi = 0,$$
(13)

$$g(t, t, \lambda) = 0, \quad g_x(x, t, \lambda)|_{x=t} = 1$$
(14)

with respect to *x*. It is easy to check that

$$u(x,\lambda) = \int_0^x g(x,t,\lambda)R(t) \, dt, \tag{15}$$

where $u(x, \lambda)$ was defined by (3). Fix *t* in (13)-(14) and make the substitution x = z + t, $g_1(z, \lambda) := g(z + t, t, \lambda)$. Then (13)-(14) take the form

$$-g_1''(z,\lambda) + q(z+t)g_1(z,\lambda) - \lambda g_1(z,\lambda) + \int_0^z M(z-\tau)g_1(\tau,\lambda)\,d\tau = 0,$$
(16)

$$g_1(0,\lambda) = 0, \quad g'_1(0,\lambda) = 1.$$
 (17)

Similar to (7) one gets the representation

$$g_1(z,\lambda) = \frac{\sin\rho z}{\rho} + \int_0^z P_1(z,\tau,t) \frac{\sin\rho\tau}{\rho} d\tau,$$

where $P_1(z, \tau, t)$ is a smooth function. Therefore,

$$g(x,t,\lambda) = \frac{\sin\rho(x-t)}{\rho} + \int_0^{x-t} P(x,\tau,t) \frac{\sin\rho\tau}{\rho} d\tau,$$
(18)

where $P(x, \tau, t) = P_1(z, \tau, t)$. Substituting (18) into (15) we get

$$u(x,\lambda) = \int_0^x \Big(\frac{\sin\rho(x-t)}{\rho} + \int_0^{x-t} P(x,\tau,t)\frac{\sin\rho\tau}{\rho}\,d\tau\Big)R(t)\,dt,$$

and consequently,

$$u(x,\lambda) = \int_0^x \left(R(x-t) + \int_0^{x-t} P(x,t,\tau)R(\tau) \, d\tau \right) \frac{\sin \rho t}{\rho} \, dt.$$
(19)

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Substituting (19) into (4) we calculate

$$\Delta(\lambda) = 1 - \int_0^{\pi} V(t) dt \int_0^t \left(R(t-s) + \int_0^{t-s} P(t,s,\tau) R(\tau) d\tau \right) \frac{\sin \rho s}{\rho} ds.$$

This yields

$$\Delta(\lambda) = 1 - \int_0^\pi \frac{\sin\rho s}{\rho} \Big(\int_s^\pi V(t) \Big(R(t-s) + \int_0^{t-s} P(t,s,\tau) R(\tau) \, d\tau \Big) \, dt \Big) \, ds$$

or

$$\Delta(\lambda) = 1 + \int_0^{\pi} B(t) \frac{\sin \rho t}{\rho} dt, \qquad (20)$$

where

$$B(t) = -\int_{t}^{\pi} V(s) \Big(R(s-t) + \int_{0}^{s-t} P(s,t,\tau) R(\tau) \, d\tau \Big) \, ds \tag{21}$$

Changing the variable $s = \pi - \xi$ in (21) we infer

$$B(t) = -\int_0^{\pi-t} V(\pi-\xi) \Big(R(\pi-\xi-t) + \int_0^{\pi-\xi-t} P(\pi-\xi,t,\tau) R(\tau) \, d\tau \Big) \, d\xi.$$

Taking $x = \pi - t$, we rewrite the last relation in the following form

$$B(\pi - x) = -\int_0^x V(\pi - \xi) \Big(R(x - \xi) + \int_0^{x - \xi} P(\pi - \xi, \pi - x, \tau) R(\tau) \, d\tau \Big) \, d\xi.$$
(22)

It follows from (5) and (22) that $B(t) \in C[0, \pi]$, and

$$B(\pi - x) = dx^{\alpha + \beta + 1} (1 + o(1)), \ x \to 0,$$
(23)

where $d = -d_0 d_1 \neq 0$. Using (20) and (23) by the well-known method (see, for example, [10]) one gets that the function $\Delta(\lambda)$ is entire in λ of order 1/2, and

$$\Delta(\lambda) = 1 + O(\rho^{-1}), \quad \lambda = \rho^2 > 0, \ \lambda \to +\infty, \tag{24}$$

$$|\Delta(\lambda)| \ge C_{\delta} |\rho|^{-\gamma} \exp(|Im\rho|\pi), \, \rho \in G_{\delta}, \tag{25}$$

where $\gamma = \alpha + \beta + 3$, $G_{\delta} = \{\rho : |\rho - \rho_n| \ge \delta \ \forall n \ge 1\}$, $\lambda = \rho^2$, $\lambda_n = \rho_n^2$, $\delta > 0$. According to (24) and Hadamard's factorization theorem, the function $\Delta(\lambda)$ is uniquely determined by its zeros. Under the assumptions of the theorem this yields

$$\Delta(\lambda) \equiv \tilde{\Delta}(\lambda). \tag{26}$$

We consider the function

$$F(\lambda) := \frac{u(\pi, \lambda) - \tilde{u}(\pi, \lambda)}{\Delta(\lambda)}$$

Using (19), (25) and the assumptions of the theorem we conclude that the function $F(\lambda)$ is entire in λ , and $F(\lambda) = O(\lambda^p)$ as $|\lambda| \to \infty$, with $p \ge 0$. By Liouville's theorem one gets that $F(\lambda)$

is a polynomial. On the other hand, taking (19) and (24) into account we infer that $F(\lambda)$ tends to zero as $\lambda > 0$, $\lambda \to +\infty$. Therefore $F(\lambda) \equiv 0$, i.e.

$$u(\pi,\lambda) \equiv \tilde{u}(\pi,\lambda). \tag{27}$$

Furthermore, it follows from (19) and (27) that

$$\int_0^{\pi} \left(R(\pi - t) - \tilde{R}(\pi - t) + \int_0^{\pi - t} P(\pi, t, \tau) (R(\tau) - \tilde{R}(\tau)) \, d\tau \right) \sin \rho \, t \, dt \equiv 0,$$

and consequently,

$$R(\pi - t) - \tilde{R}(\pi - t) + \int_0^{\pi - t} P(\pi, t, \tau) (R(\tau) - \tilde{R}(\tau)) \, d\tau \equiv 0,$$

or

$$R(x) - \tilde{R}(x) + \int_0^x P(\pi, \pi - x, \tau) (R(\tau) - \tilde{R}(\tau)) d\tau \equiv 0.$$

Since this homogeneous integral equation has only the trivial solution it follows that

$$R(x) = \tilde{R}(x), \quad x \in [0, \pi].$$
 (28)

Let the functions $u_0(x, \lambda)$ and $R_0(x)$ be the solutions of the integral equations

$$u(x,\lambda) = u_0(x,\lambda) + \int_0^x K(x,t) u_0(t,\lambda) dt, \ R(x) = R_0(x) + \int_0^x K(x,t) R_0(t) dt.$$
(29)

In view of (3) and (29),

$$u_0(0,\lambda) = u'_0(0,\lambda) = 0, \ell_1 u(x,\lambda) = \lambda u(x,\lambda) - R(x).$$

Moreover, applying Lemma 2 one gets

$$\ell_1 u(x,\lambda) = -u_0''(x,\lambda) - \int_0^x K(x,t) u_0''(t,\lambda) \, dt.$$
(30)

It follows from (29) and () that

$$\ell_1 u(x,\lambda) = \lambda u_0(x,\lambda) + \lambda \int_0^x K(x,t) u_0(t,\lambda) \, dt - R_0(x) - \int_0^x K(x,t) R_0(t) \, dt.$$

Comparing this relation with (30) we obtain

$$u_0''(x,\lambda) + \lambda u_0(x,\lambda) - R_0(x) + \int_0^x K(x,t)(u_0''(t,\lambda) + \lambda u_0(t,\lambda) - R_0(t)) dt = 0,$$

and consequently,

$$u_0''(x,\lambda) + \lambda u_0(x,\lambda) = R_0(x).$$
(31)

The solution of the Cauchy problem (31), () has the form

$$u_0(x,\lambda) = \int_0^x \frac{\sin \rho (x-t)}{\rho} R_0(t) \, dt.$$
(32)

Denote

$$V_0(x) = V(x) + \int_x^{\pi} K(t, x) V(t) dt.$$
(33)

It follows from (4), (29) and (33) that

$$\Delta(\lambda) = 1 - \int_0^{\pi} V_0(t) \, u_0(t, \lambda) \, dt.$$
(34)

Taking (28), (29) and (32) into account we obtain $u_0(x, \lambda) \equiv \tilde{u}_0(x, \lambda)$. Together with (26) and (34) this yields

$$\int_0^{\pi} (V_0(t) - \tilde{V}_0(t)) u_0(t, \lambda) \, dt \equiv 0.$$

Using (32) again we calculate

$$\int_0^{\pi} \left(\int_s^{\pi} (V_0(t) - \tilde{V}_0(t)) R_0(t-s) \, dt \right) \sin \rho s \, ds \equiv 0,$$

and consequently,

$$\int_{s}^{\pi} (V_{0}(t) - \tilde{V}_{0}(t)) R_{0}(t-s) dt \equiv 0, \ s \in [0,\pi],$$

or

$$\int_0^x (V_0(\pi - \xi) - \tilde{V}_0(\pi - \xi)) R_0(x - \xi) \, d\xi \equiv 0, \ x \in [0, \pi].$$

Applying Titchmarsh's theorem we infer $V_0(\pi - \xi) \equiv \tilde{V}_0(\pi - \xi), \ \xi \in [0, \pi]$ or

$$V_0(x) \equiv \tilde{V}_0(x), \ x \in [0, \pi].$$

By virtue of (33) this yields

$$V(x) \equiv \tilde{V}(x), \ x \in [0,\pi],$$

and Theorem 1 is proved.

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