



STABILITY ESTIMATE FOR A STRONGLY COUPLED PARABOLIC SYSTEM

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Abstract. We consider an inverse source problem for a 2×2 strongly coupled parabolic system. The Lipschitz stability is proved and the proof is based on the Carleman estimates with two large parameters.

1. Introduction

We consider the following strongly coupled parabolic system

$$\begin{cases} \partial_t u_1 = a_{11}(x, t)\Delta u_1 + a_{12}(x, t)\Delta u_2 + \tilde{\ell}_1(u_1, \nabla u_1, u_2, \nabla u_2) + \tilde{f}_1(x, t), \\ \partial_t u_2 = a_{21}(x, t)\Delta u_1 + a_{22}(x, t)\Delta u_2 + \tilde{\ell}_2(u_1, \nabla u_1, u_2, \nabla u_2) + \tilde{f}_2(x, t) \end{cases}$$

in $Q := \Omega \times (0, T)$ with initial and boundary conditions

$$\begin{cases} (u_1, u_2) |_{\partial\Omega \times (0, T)} = 0, \\ (u_1, u_2) |_{t=0} = (u_{01}(x), u_{02}(x)) \text{ in } \Omega \subseteq \mathbb{R}^n. \end{cases}$$

Here $\Omega \subseteq \mathbb{R}^n$ is a bounded domain with smooth boundary $\partial\Omega$. $A(x, t) := (a_{ij})_{2 \times 2}$ is a smooth positive matrix with different eigenvalues. $\tilde{\ell}_i (i = 1, 2)$ are smooth linear functions and $\tilde{f}_i (i = 1, 2)$ are smooth unknown functions. It can be proved (see Appendix) that there exists an invertible matrix $P(x, t) = (p_{ij})_{2 \times 2}$ such that

$$P^{-1}AP = \begin{pmatrix} \mu_1 & 0 \\ \mu_0 & \mu_2 \end{pmatrix}$$

with $\mu_1 > 0, \mu_2 > 0$. Let

$$\begin{pmatrix} u \\ v \end{pmatrix} = P^{-1} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \quad \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} = P^{-1} \begin{pmatrix} \tilde{f}_1 \\ \tilde{f}_2 \end{pmatrix},$$

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2010 *Mathematics Subject Classification.* 35Q30, 35R30.

Key words and phrases. Inverse source problem, Lipschitz stability, Carleman estimates.

*Partially supported by the National Science Council and NCTS of Taiwan.

and similarly, we denote $\ell_i(u, \nabla u, v, \nabla v)$ ($i = 1, 2$) the linear function of $u, \nabla u, v, \nabla v$ with the coefficients depending on (x, t) . Therefore, it is natural to consider the following system

$$\begin{cases} \partial_t u = \mu_1 \Delta u + \ell_1(u, \nabla u, v, \nabla v) + f_1(x, t), \\ \partial_t v = \mu_0 \Delta u + \mu_2 \Delta v + \ell_2(u, \nabla u, v, \nabla v) + f_2(x, t), \\ u = v = 0 \text{ on } \partial\Omega \times (0, T). \end{cases} \quad (1.1)$$

Our inverse problem is to find $\{f_1(x, t), f_2(x, t)\}$ from the input data

$$(u, v)|_{\omega \times (0, T)} \text{ and } (u, v)(x, t_0), \quad x \in \Omega, \quad t_0 \in (0, T). \quad (1.2)$$

Here $\omega \subset\subset \Omega$ is a given subdomain. Our aim is to prove the Lipschitz stability of the inverse source problem. The key ingredient is a Carleman estimate with two large parameters due to Yamamoto [1]. The pioneering paper for the inverse problem by Carleman estimate was obtained by Bukhgeim and Klibanov [2]. For the related work, Klibanov [3] got estimates of initial conditions of parabolic equations and inequalities via lateral cauchy data. The first Lipschitz stability result of an inverse source problem for a parabolic equation was obtained by Imanuvilov and Yamamoto [4]. Moreover the method of [4] was generalized to the inverse source problem of Navier–Stokes equation [5] and the Boussinesq system [6], respectively. Very recently, Benabdallah–Cristofol–Gaitan–Yamamoto [7] study our inverse problem (1.1) with $\mu_0 = 0$. We note that the method of [7] can not be adapted to our system.

We make the following assumptions.

$$\begin{cases} (H1) \quad |\partial_t f_i(x, t)| \leq c |f_i(x, t_0)| \quad (i = 1, 2) \quad (x, t) \in \overline{\Omega} \times [0, T]. \\ (H2) \quad \mu_0, \mu_1, \mu_2 \in C^2(\overline{\Omega} \times [0, T]) \quad \mu_1 > 0, \mu_2 > 0. \end{cases}$$

Each $\ell_i(u, \nabla u, v, \nabla v)$ denotes a first order different differential operator acting on u and on v with C^2 coefficients depending on (x, t) .

Remark 1.1. (H1) is also assumed in [4]. Therefore, there exists a positive constant c such that

$$|f_i(x, t)| + |\partial_t f_i(x, t)| \leq c |f_i(x, t_0)| \quad (i = 1, 2) \quad (1.3)$$

for $(x, t) \in \overline{\Omega} \times [0, T]$. In [4], $f_i(x, t) = p_i(x)R_i(x, t)$ where $R_i(x, t)$ is given, and $R_i(x, t_0) \neq 0$. Then we are in a position to state our main result in this paper.

Theorem 1.1. *Let (H1) and (H2) be satisfied. Then there exists a positive constant $c := c(\Omega, T, t_0)$ such that*

$$\|f_1\|_{L^2(Q)} + \|f_2\|_{L^2(Q)} \leq c \{ \|u(\cdot, T/2)\|_{H^2} + \|v(\cdot, T/2)\|_{H^2} + \|u\|_{H^1(0, T; L^2(\omega))} + \|v\|_{H^1(0, T; L^2(\omega))} \}.$$

Remark 1.2. If $t_0 = 0$, then the corresponding inverse problem for a parabolic equation is open (cf Isakov [8, 9]); our inverse problem with $t_0 = 0$ is also open.

Remark 1.3. We can not prove a similar result for an $m \times n$ strongly coupled parabolic system for $m, n \geq 3$. It is an open problem posed in [1] to prove a Carleman estimate for $n \times n$ strongly coupled parabolic system for $n \geq 2$. Thus we solve the open problem when $n = 2$.

2. Key Carleman estimate

For our Carleman estimate we need a weight function with special properties. The existence of such a function is proved in [10, 11].

Lemma 2.1. *Let ω_0 be an arbitrary fixed sub-domain of Ω such that $\overline{\omega_0} \subset \omega$. Then there exists a function $\eta \in C^2(\overline{\Omega})$ such that*

$$\eta(x) > 0 \text{ in } \Omega, \eta|_{\partial\Omega} = 0, |\nabla\eta(x)| > 0 \text{ in } \overline{\Omega \setminus \omega_0}. \tag{2.1}$$

Let $\Omega := \{x; |x| < 1\}$ and $\omega_0 := \{x; |x| < \frac{1}{2}\}$. Then $\eta(x) = 1 - |x|^2$ satisfies (2.1). Set

$$\varphi(x, t) = \frac{e^{\lambda\eta}}{t(T-t)}, \alpha(x, t) = \frac{e^{\lambda\eta(x)} - e^{2\lambda\|\eta\|_{C(\overline{\Omega})}}}{t(T-t)},$$

where $\lambda > 0$, then we have the following Carleman estimates with two large parameters which were proved in [12].

Lemma 2.2. *Let*

$$\begin{cases} \partial_t y - a(x, t)\Delta y + b(x, t) \cdot \nabla y + c(x, t) y = g \text{ in } Q := \Omega \times (0, T), \\ y = 0 \text{ on } \partial\Omega \times (0, T), \end{cases}$$

where $\|a\|_{C^1(\overline{Q})} + \|b\|_{L^\infty(Q)} + \|c\|_{L^\infty(Q)} \leq M, g \in L^2(Q)$. Then there exists a number $\lambda_0 > 0$ such that for an arbitrary $\lambda \geq \lambda_0$, we can choose a constant $s_0(\lambda) \geq 0$ satisfying: there exist a constant $c := c(s_0, \lambda_0) > 0$ such that

$$\begin{aligned} & \int_Q \{(s\varphi)^{p-1} (|\partial_t y|^2 + \sum_{i,j=1}^n |\partial_i \partial_j y|^2) \\ & \quad + (s\varphi)^{p+1} \lambda^2 |\nabla y|^2 + (s\varphi)^{p+3} \lambda^4 y^2\} e^{2s\alpha} dx dt \\ & \leq c \int_Q (s\varphi)^p |g|^2 e^{2s\alpha} dx dt + c \int_{\omega \times (0, T)} (s\varphi)^{p+3} \lambda^4 y^2 e^{2s\alpha} dx dt, \end{aligned} \tag{2.2}$$

for all $s > s_0, p = 0, 1, 2$.

3. Proof of Theorem 1.1

First we assume that $t_0 = T/2$ without loss of generality by changing the scale of t . Applying Lemma 2.2 ($p = 2$) to the solution u of (1.1), we have the estimate

$$\begin{aligned} & \int_Q \{s\varphi(|\partial_t u|^2 + \sum_{i,j=1}^n |\partial_i \partial_j u|^2) + (s\varphi)^3 \lambda^2 |\nabla u|^2 + (s\varphi)^5 \lambda^4 u^2\} e^{2s\alpha} dx dt \\ & \leq c \int_Q (s\varphi)^2 (f_1^2 + |\nabla v|^2 + |v|^2) e^{2s\alpha} dx dt + c \int_{\omega \times (0,T)} (s\varphi)^5 \lambda^4 u^2 e^{2s\alpha} dx dt. \end{aligned} \quad (3.1)$$

Similarly, applying Lemma 2.2 ($p = 1$) to the solution v of (1.1), we get

$$\begin{aligned} & \int_Q \{|\partial_t v|^2 + \sum_{i,j=1}^n |\partial_i \partial_j v|^2 + (s\varphi)^2 \lambda^2 |\nabla v|^2 + (s\varphi)^4 \lambda^4 v^2\} e^{2s\alpha} dx dt \\ & \leq c \int_Q s\varphi (f_2^2 + |\Delta u|^2 + |\nabla u|^2 + |u|^2) e^{2s\alpha} dx dt \\ & \quad + c \int_{\omega \times (0,T)} (s\varphi)^4 \lambda^4 v^2 e^{2s\alpha} dx dt. \end{aligned} \quad (3.2)$$

By $\varphi \geq \frac{1}{t(T-t)} \geq \frac{4}{T^2}$, $(2c) \times (3.1) + (3.2)$ and λ sufficiently large, we deduce that

$$\begin{aligned} & \int_Q \{s\varphi(|\partial_t u|^2 + \sum_{i,j=1}^n |\partial_i \partial_j u|^2) + (s\varphi)^3 \lambda^2 |\nabla u|^2 + (s\varphi)^5 \lambda^4 u^2 \\ & \quad + (|\partial_t v|^2 + \sum_{i,j=1}^n |\partial_i \partial_j v|^2) + (s\varphi)^2 \lambda^2 |\nabla v|^2 + (s\varphi)^4 \lambda^4 v^2\} e^{2s\alpha} dx dt \\ & \leq c \int_Q [(s\varphi)^2 f_1^2 + s\varphi f_2^2] e^{2s\alpha} dx dt + \tilde{c} \int_{\omega \times (0,T)} (u^2 + v^2) dx dt. \end{aligned} \quad (3.3)$$

Taking ∂_t to the first equation of (1.1), we see that

$$\partial_t u_t = \mu_1 \Delta u_t + \partial_t \mu_1 \Delta u + \partial_t \ell_1 + \partial_t f_1. \quad (3.4)$$

Applying Lemma 2.2 ($p = 1$) to (3.4), we have

$$\begin{aligned} & \int_Q \{|\partial_t^2 u|^2 + \sum_{i,j=1}^n |\partial_i \partial_j u_t|^2 + (s\varphi)^2 \lambda^2 |\nabla u_t|^2 + (s\varphi)^4 \lambda^4 u_t^2\} e^{2s\alpha} dx dt \\ & \leq c \int_Q s\varphi (|\partial_t f_1|^2 + |\Delta u|^2 + |\nabla u|^2 + |u|^2 + |v|^2 + |\nabla v|^2 \\ & \quad + |v_t|^2 + |\nabla v_t|^2) e^{2s\alpha} dx dt + \tilde{c} \int_{\omega \times (0,T)} |u_t|^2 dx dt. \end{aligned} \quad (3.5)$$

Taking ∂_t to the second equation of (1.1), we find that

$$\partial_t v_t = \mu_0 \Delta u_t + \mu_2 \Delta v_t + \partial_t \mu_0 \Delta u + \partial_t \mu_2 \Delta v + \partial_t \ell_2 + \partial_t f_2. \quad (3.6)$$

Applying Lemma 2.2 ($p = 0$) to (3.6), we have

$$\begin{aligned}
 & \int_Q \left\{ \frac{1}{s\varphi} (|\partial_t^2 v|^2 + \sum_{i,j=1}^n |\partial_i \partial_j v_t|^2) + s\varphi \lambda^2 |\nabla v_t|^2 + (s\varphi)^3 \lambda^4 v_t^2 \right\} e^{2s\alpha} dx dt \\
 & \leq c \int_Q (|\partial_t f_2|^2 + |\Delta u_t|^2 + |\nabla u_t|^2 + |u_t|^2 + |\Delta u|^2 + |\nabla u|^2 + |u|^2 \\
 & \quad + |\Delta v|^2 + |\nabla v|^2 + |v|^2) e^{2s\alpha} dx dt + \tilde{c} \int_{\omega \times (0, T)} |v_t|^2 dx dt.
 \end{aligned} \tag{3.7}$$

Using (2c) \times (3.5) + (3.7), $\phi \geq \frac{4}{T^2}$ and λ sufficiently large, we find that

$$\begin{aligned}
 & \int_Q \{ |\partial_t^2 u|^2 + \sum_{i,j=1}^n |\partial_i \partial_j u_t|^2 + (s\varphi)^2 \lambda^2 |\nabla u_t|^2 + (s\varphi)^4 \lambda^4 u_t^2 \\
 & \quad + \frac{1}{s\varphi} (|\partial_t^2 v|^2 + \sum_{i,j=1}^n |\partial_i \partial_j v_t|^2) + s\varphi \lambda^2 |\nabla v_t|^2 + (s\varphi)^3 \lambda^4 v_t^2 \} e^{2s\alpha} dx dt \\
 & \leq c \int_Q [s\varphi |\partial_t f_1|^2 + |\partial_t f_2|^2 + s\varphi (|\Delta u|^2 + |\nabla u|^2 + |u|^2 + |v|^2 \\
 & \quad + |\nabla v|^2 + |\Delta v|^2)] e^{2s\alpha} dx dt + \tilde{c} \int_{\omega \times (0, T)} (|u_t|^2 + |v_t|^2) dx dt.
 \end{aligned} \tag{3.8}$$

Combining (3.3), (3.8), $\phi \geq \frac{4}{T^2}$ and s sufficiently large, we obtain

$$\begin{aligned}
 I & := \int_Q \{ |\partial_t^2 u|^2 + \sum_{i,j=1}^n |\partial_i \partial_j u_t|^2 + (s\varphi)^2 \lambda^2 |\nabla u_t|^2 + (s\varphi)^4 \lambda^4 u_t^2 \\
 & \quad + s\varphi \sum_{i,j=1}^n |\partial_i \partial_j u|^2 + (s\varphi)^3 \lambda^2 |\nabla u|^2 + (s\varphi)^5 \lambda^4 u^2 \\
 & \quad + \frac{1}{s\varphi} (|\partial_t^2 v|^2 + \sum_{i,j=1}^n |\partial_i \partial_j v_t|^2) + s\varphi \lambda^2 |\nabla v_t|^2 + (s\varphi)^3 \lambda^4 v_t^2 \\
 & \quad + \sum_{i,j=1}^n |\partial_i \partial_j v|^2 + (s\varphi)^2 \lambda^2 |\nabla v|^2 + (s\varphi)^4 \lambda^4 v^2 \} e^{2s\alpha} dx dt \\
 & \leq c \int_Q [(s\varphi)^2 f_1^2 + s\varphi f_2^2 + s\varphi (\partial_t f_1)^2 + (\partial_t f_2)^2] e^{2s\alpha} dx dt \\
 & \quad + \tilde{c} \int_{\omega \times (0, T)} (u^2 + u_t^2 + v^2 + v_t^2) dx dt \\
 & \leq c \int_Q [(s\varphi)^2 f_1^2(x, T/2) + s\varphi f_2^2(x, T/2)] e^{2s\alpha} dx dt \\
 & \quad + \tilde{c} \int_{\omega \times (0, T)} (u^2 + u_t^2 + v^2 + v_t^2) dx dt.
 \end{aligned} \tag{3.9}$$

On the other hand, in terms of $u_t^2(x, 0)e^{2s\alpha(x, 0)} = 0$, $v_t^2(x, 0)e^{2s\alpha(x, 0)} = 0$, $|\alpha_t| \leq c\varphi^2$, and equations (1.1) (1.2) at time $t = T/2$, we obtain

$$\int_{\Omega} [s^2 f_1^2(x, T/2) + s f_2^2(x, T/2)] e^{2s\alpha(x, T/2)} dx$$

$$\begin{aligned}
&\leq c \int_{\Omega} (s^2 |\partial_t u(x, T/2)|^2 + s |\partial_t v(x, T/2)|^2) e^{2s\alpha(x, T/2)} dx \\
&\quad + c \|u(\cdot, T/2)\|_{H^2}^2 + c \|v(\cdot, T/2)\|_{H^2}^2 \\
&= c \int_0^{T/2} \frac{\partial}{\partial t} \int_{\Omega} [s^2 u_t^2(x, t) + s v_t^2(x, t)] e^{2s\alpha(x, t)} dx \\
&\quad + c \|u(\cdot, T/2)\|_{H^2}^2 + c \|v(\cdot, T/2)\|_{H^2}^2 \\
&\leq \int_0^{T/2} \int_{\Omega} (2s^3 \partial_t \alpha u_t^2 + 2s^2 u_t u_{tt} + 2s^2 \partial_t \alpha v_t^2 + 2s v_t v_{tt}) e^{2s\alpha} dx dt \\
&\quad + c \|u(\cdot, T/2)\|_{H^2}^2 + c \|v(\cdot, T/2)\|_{H^2}^2 \\
&\leq \int_Q (2s^3 \varphi^2 u_t^2 + 2s^2 u_t u_{tt} + 2s^2 \varphi^2 v_t^2 + 2s v_t v_{tt}) e^{2s\alpha} dx dt \\
&\quad + c \|u(\cdot, T/2)\|_{H^2}^2 + c \|v(\cdot, T/2)\|_{H^2}^2 \\
&\leq cI + c \|u(\cdot, T/2)\|_{H^2}^2 + c \|v(\cdot, T/2)\|_{H^2}^2 \\
&\leq c \int_Q [(s\varphi)^2 f_1^2(x, T/2) + s\varphi f_2^2(x, T/2)] e^{2s\alpha} dx dt \\
&\quad + c \|u(\cdot, T/2)\|_{H^2}^2 + c \|v(\cdot, T/2)\|_{H^2}^2 \\
&\quad + \tilde{c} \int_{\omega \times (0, T)} (u^2 + u_t^2 + v^2 + v_t^2) dx dt. \tag{3.10}
\end{aligned}$$

By the same calculation as that in [4], we deduce that

$$\begin{aligned}
&\int_Q [(s\varphi)^2 f_1^2(x, T/2) + s\varphi f_2^2(x, T/2)] e^{2s\alpha} dx dt \\
&\quad \leq \frac{c}{\sqrt{s}} \int_{\Omega} [s^2 f_1(x, T/2) + s f_2^2(x, T/2)] e^{2s\alpha(x, T/2)} dx. \tag{3.11}
\end{aligned}$$

Combining (3.10), (3.11) and s sufficiently large, we arrive at

$$\begin{aligned}
\int_Q (f_1^2 + f_2^2) dx dt &\leq c \int_{\Omega} (s^2 f_1^2(x, T/2) + s f_2^2(x, T/2)) e^{2s\alpha(x, T/2)} dx \\
&\leq c \|u(\cdot, T/2)\|_{H^2}^2 + c \|v(\cdot, T/2)\|_{H^2}^2 \\
&\quad + \tilde{c} \int_{\omega \times (0, T)} (u^2 + u_t^2 + v^2 + v_t^2) dx dt.
\end{aligned}$$

Hence we complete the proof. \square

4. Appendix

In this appendix, we prove that there exists a smooth and invertible matrix $P = P(x, t)$ such that

$$P^{-1}AP = P^{-1} \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} P = \begin{pmatrix} \mu_1 & 0 \\ \mu_0 & \mu_2 \end{pmatrix},$$

where μ_1 and μ_2 are eigenvalues of A . If $a_{11}(x, t) \geq a_{22}(x, t)$, we define

$$\mu_1 = \frac{a_{11} + a_{22} + \sqrt{(a_{11} + a_{22})^2 - 4(a_{11}a_{22} - a_{12}a_{21})}}{2},$$

$$\mu_2 = \frac{a_{11} + a_{22} - \sqrt{(a_{11} + a_{22})^2 - 4(a_{11}a_{22} - a_{12}a_{21})}}{2}.$$

If $a_{11}(x, t) < a_{22}(x, t)$, we define

$$\mu_1 = \frac{a_{11} + a_{22} - \sqrt{(a_{11} + a_{22})^2 - 4(a_{11}a_{22} - a_{12}a_{21})}}{2},$$

$$\mu_2 = \frac{a_{11} + a_{22} + \sqrt{(a_{11} + a_{22})^2 - 4(a_{11}a_{22} - a_{12}a_{21})}}{2}.$$

Let

$$\mu_0(x, t) = a_{21}(x, t) \quad \text{and} \quad P = \begin{pmatrix} 1 & \frac{a_{12}}{\mu_2 - a_{11}} \\ 0 & 1 \end{pmatrix},$$

we can easily check that

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} 1 & \frac{a_{12}}{\mu_2 - a_{11}} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & \frac{a_{12}}{\mu_2 - a_{11}} \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \mu_1 & 0 \\ a_{21} & \mu_2 \end{pmatrix}.$$

and

$$\mu_2(x, t) - a_{11}(x, t) \neq 0.$$

The proof is complete. □

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